

Enhancing Rubin Science with Robust Cross-Matches in the Crowded LSST Sky

Tom J Wilson (he/him) and Tim Naylor

With George Beckett, Mike Read, and Dominic Sloan-Murphy

t.j.wilson@exeter.ac.uk

University of Exeter

LSST@EU5 – Joint TVS-SMWLV SC Session 28/Sep/23

 @Onoddil  @pm.me  .github.io 



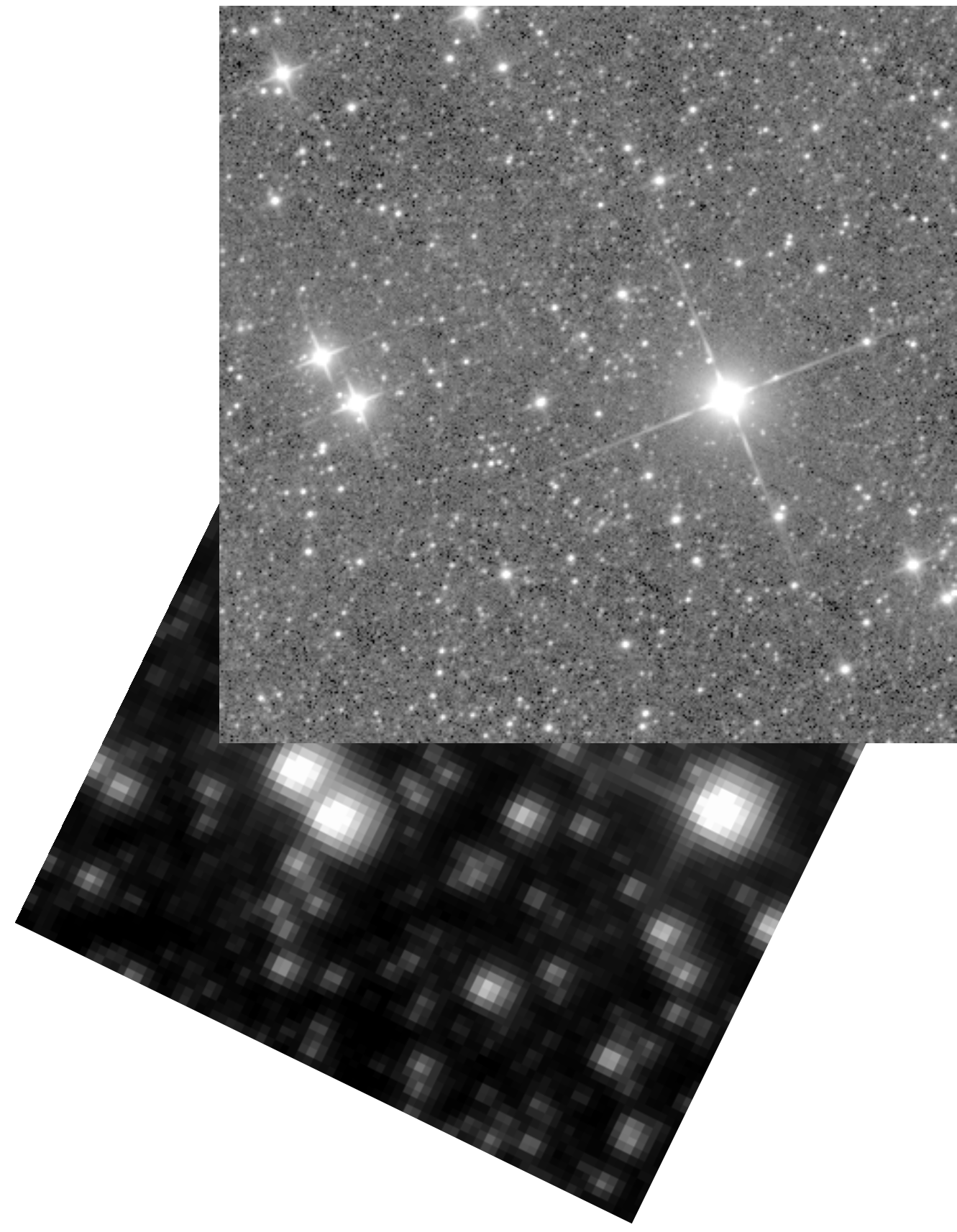
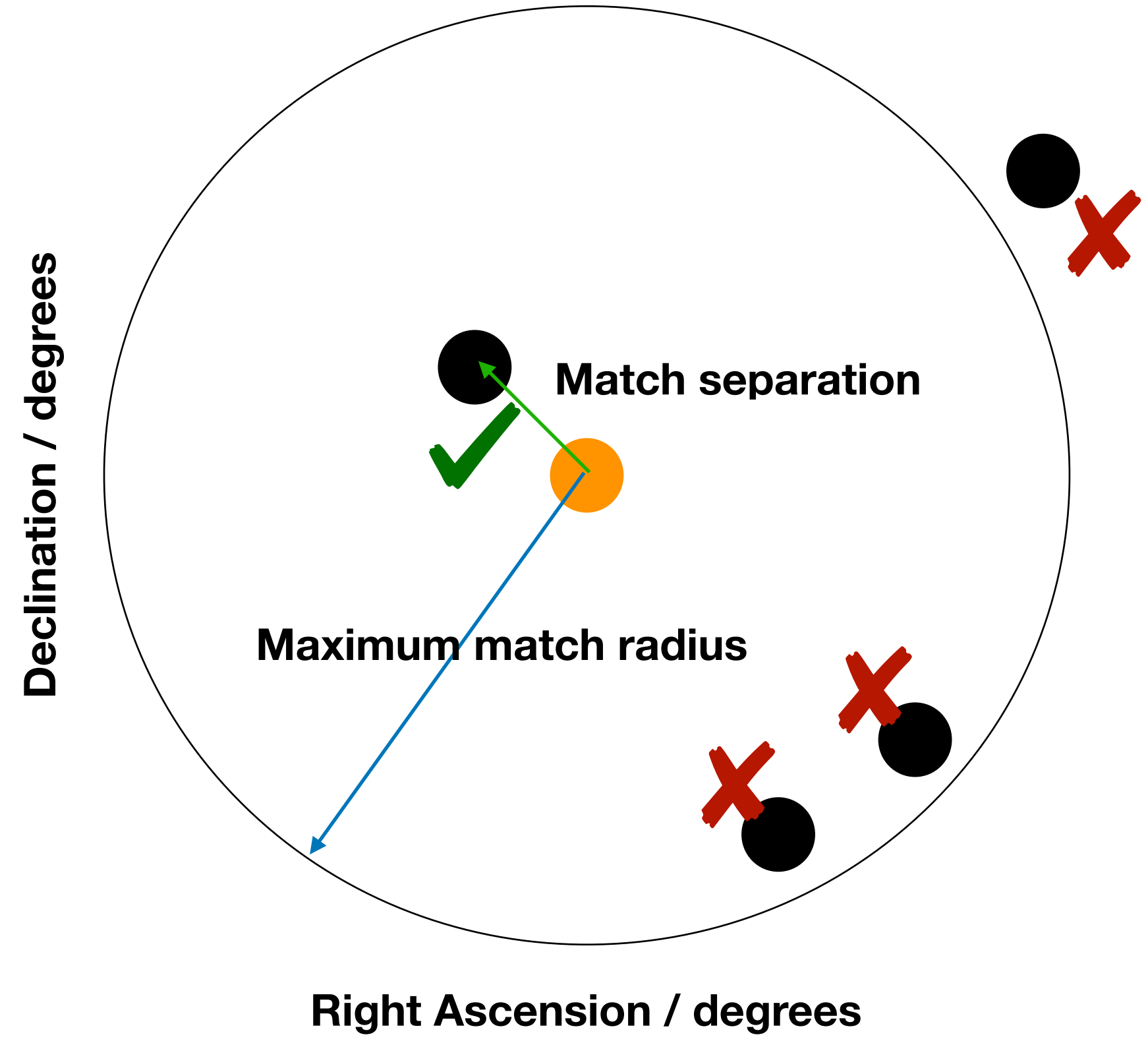
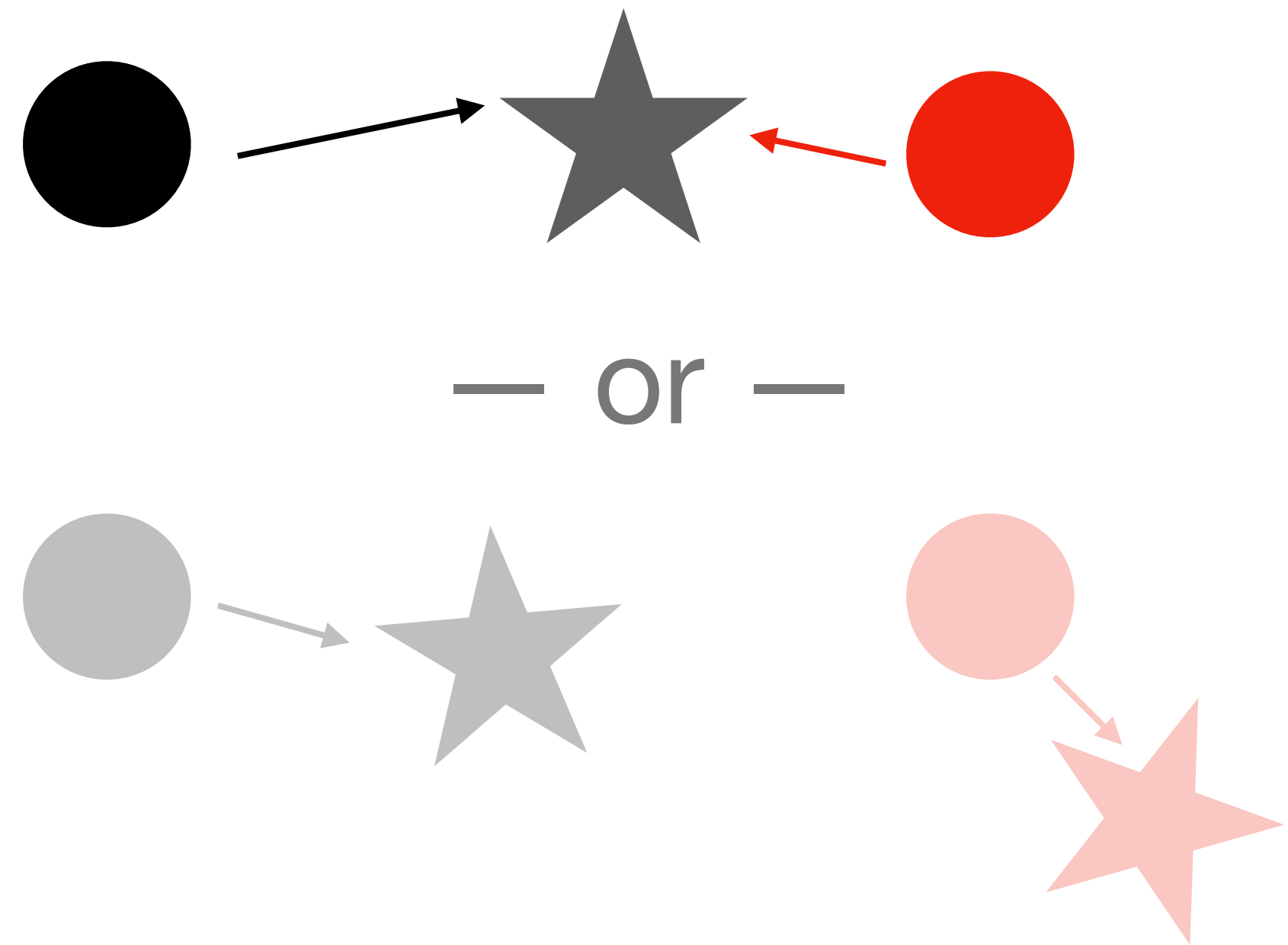
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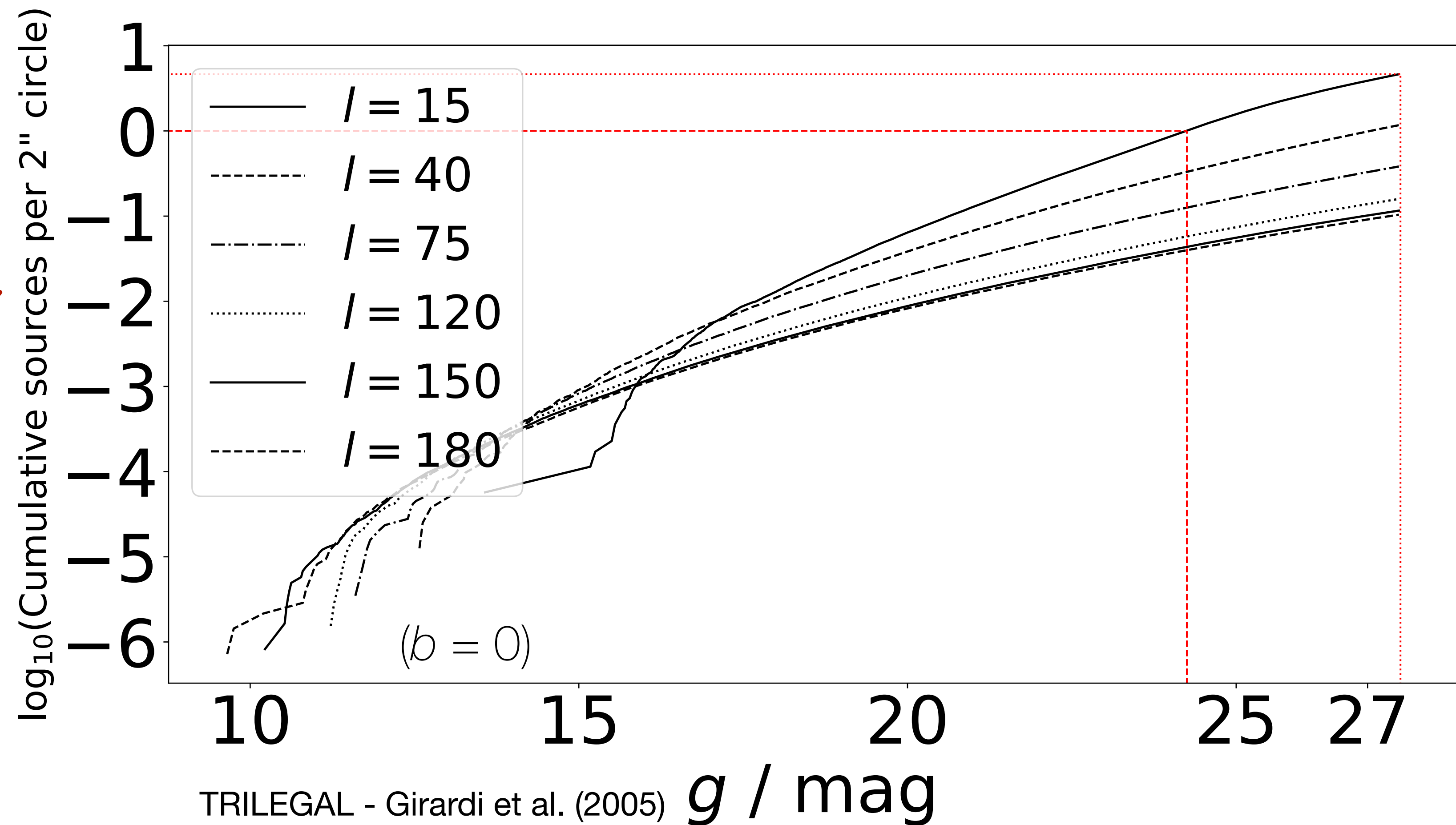
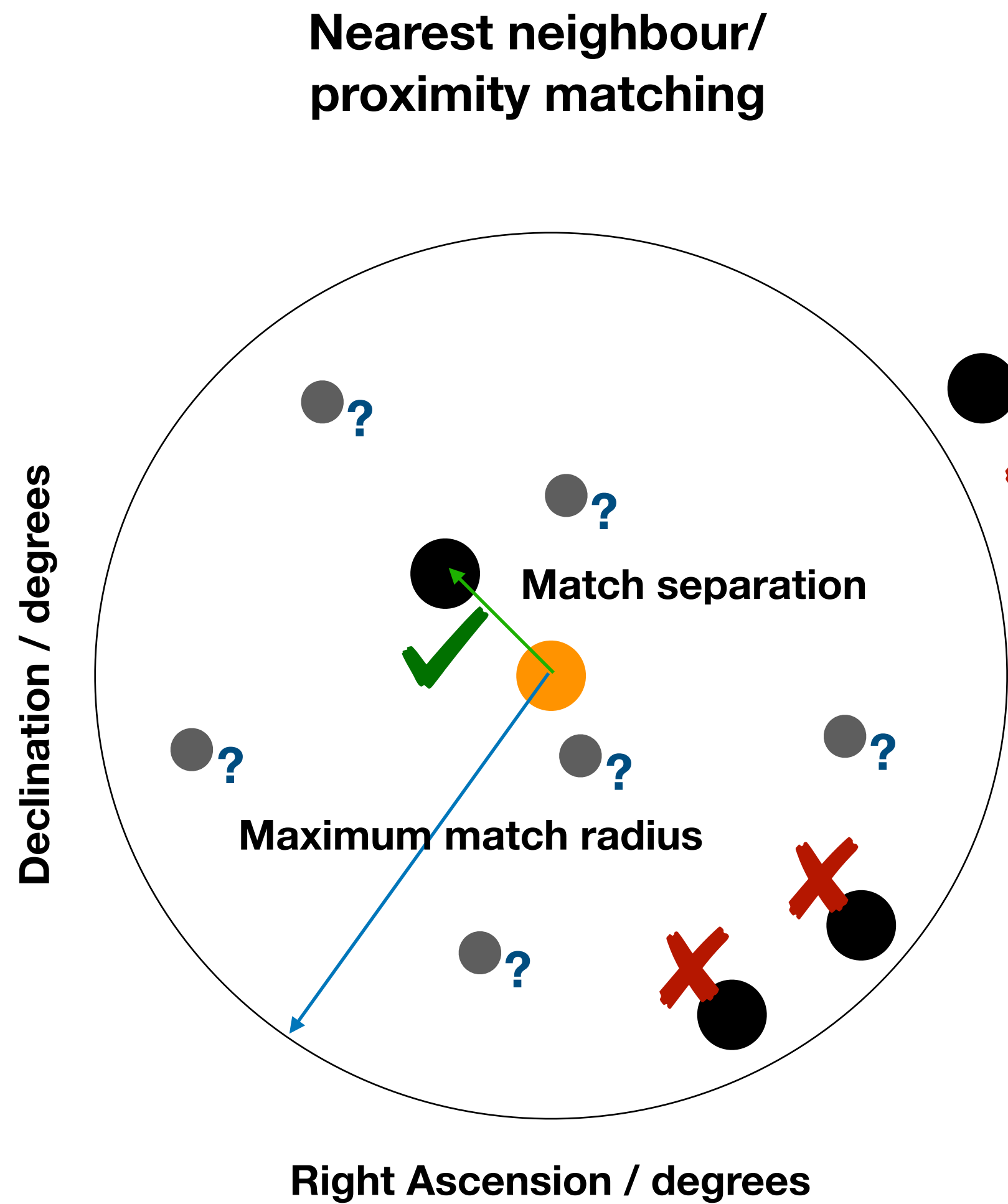
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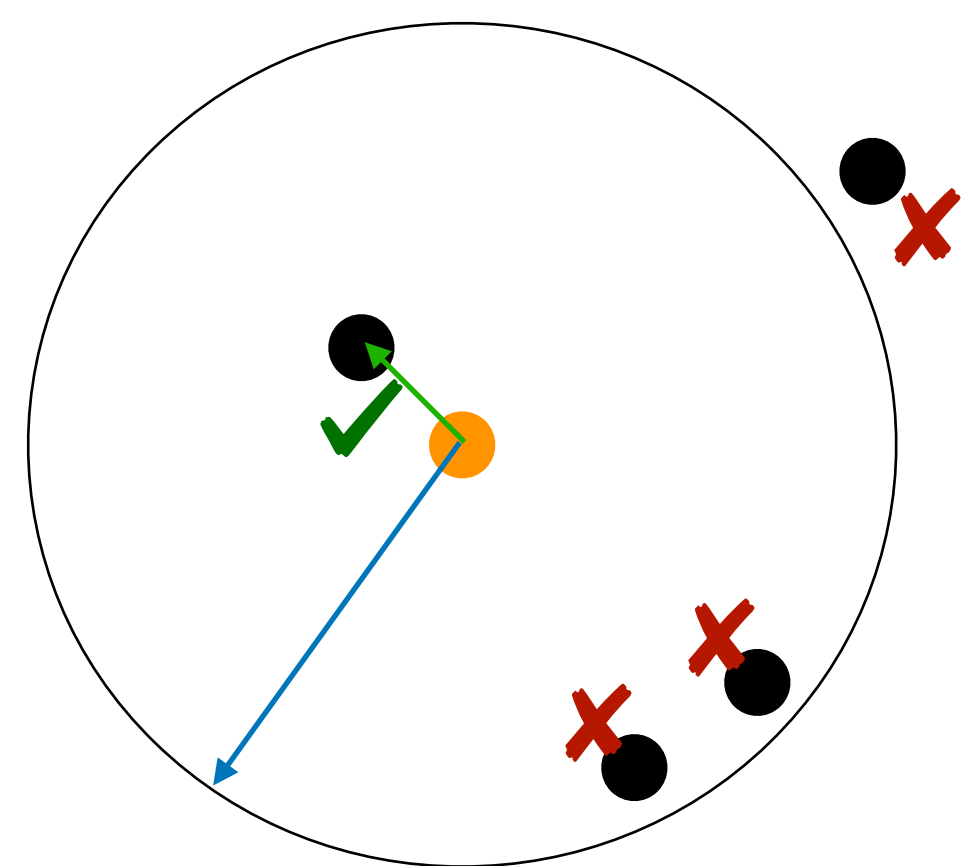
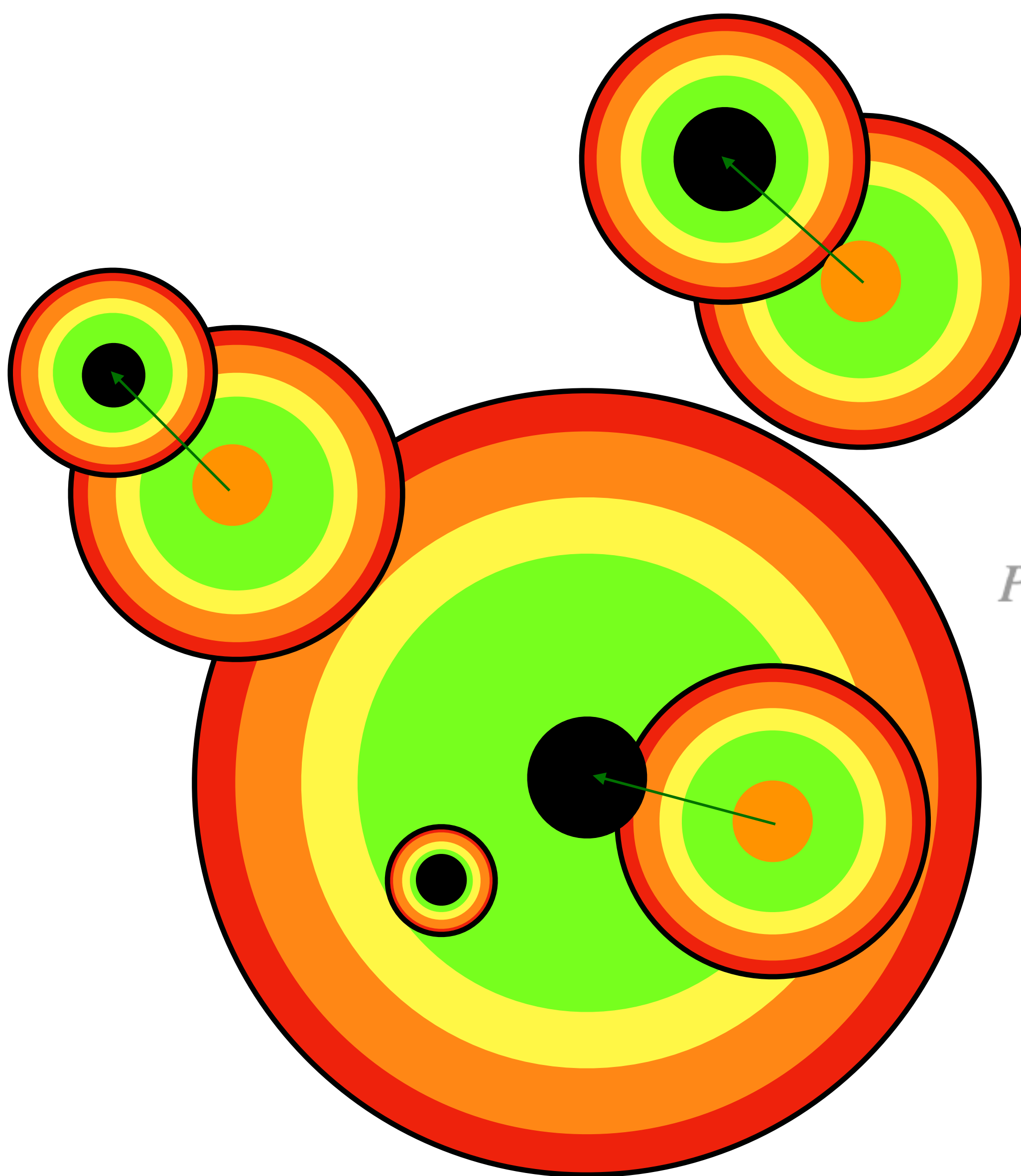
“Simple” Cross-Matching



The Problem With Rubin Obs.'s LSST



Probabilistic Cross-Matching



Probability of two sources having their on-sky separation given the hypothesis they are counterparts

$$P(\zeta, \lambda, k | \gamma, \phi) = \frac{1}{K} \times \prod_{\delta \notin \zeta \cap \delta \in \gamma} N_\gamma f_\gamma^\delta \prod_{\omega \notin \lambda \cap \omega \in \phi} N_\phi f_\phi^\omega \prod_{i=1}^k N_c G_{\gamma\phi}^{\zeta_i \lambda_i} c_{\gamma\phi}^{\zeta_i \lambda_i}$$

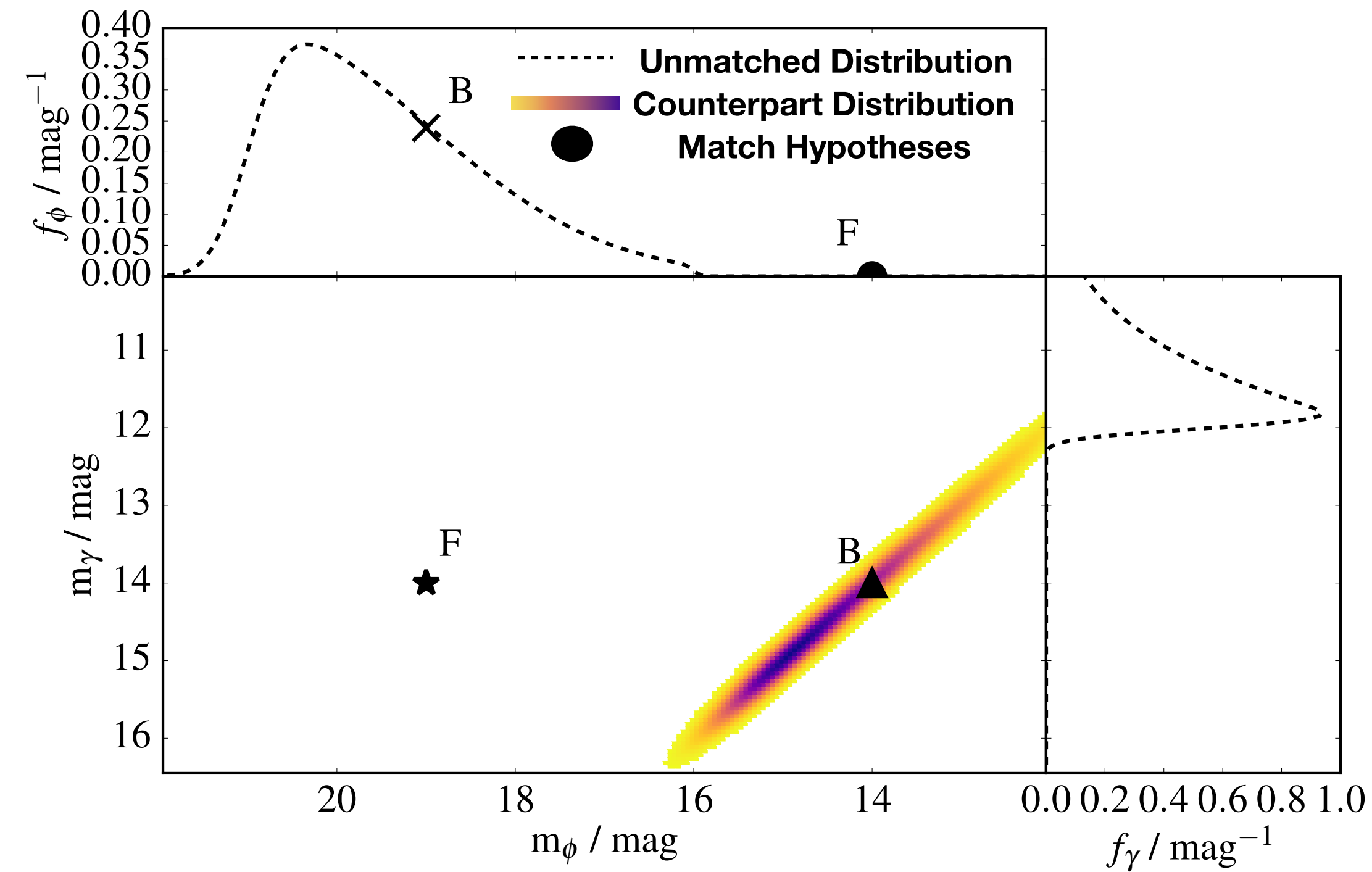
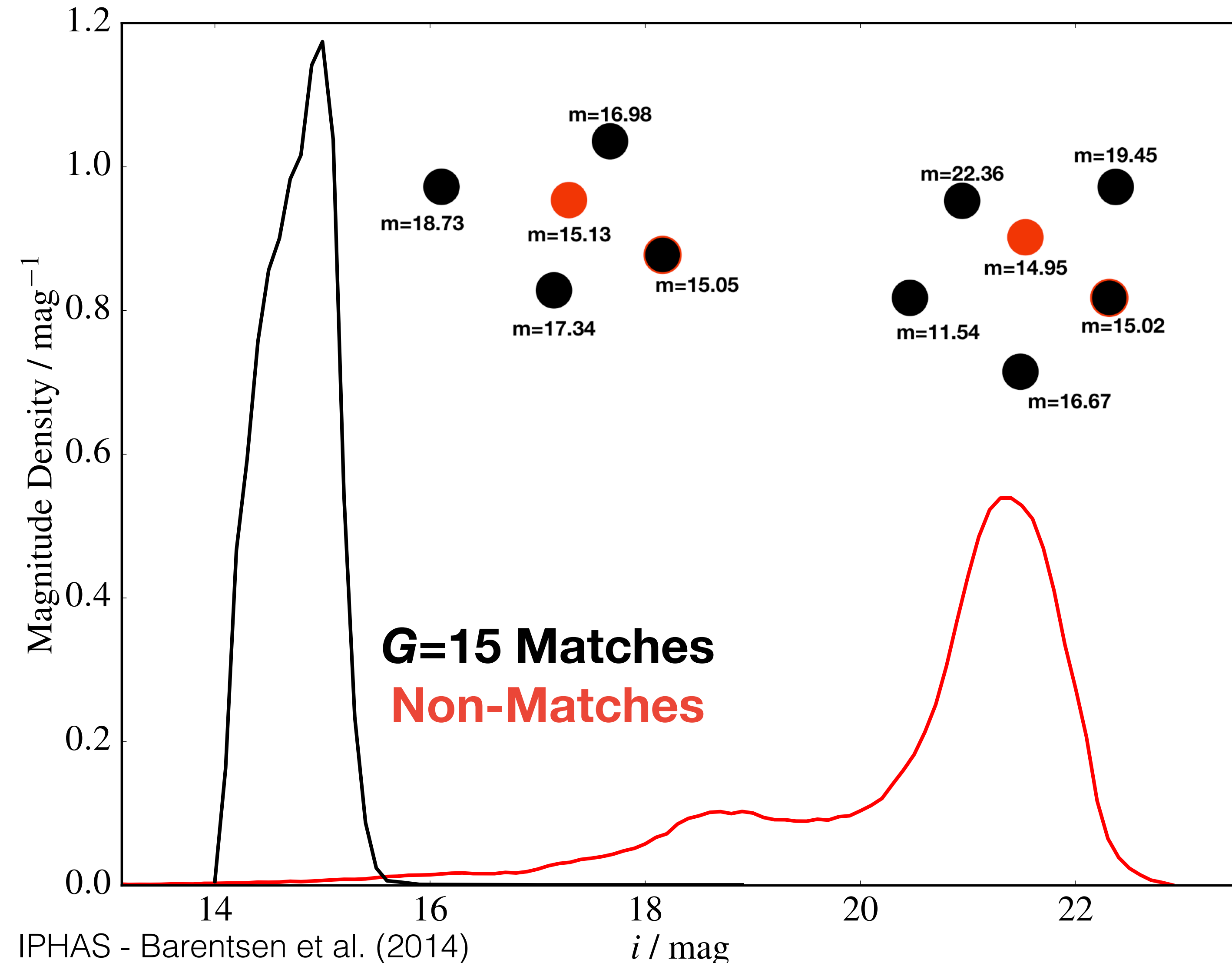
Wilson & Naylor (2018a)

Probability of sources having their brightnesses given they are unrelated to one another (“field stars”)

Probability of sources having their brightnesses given they are counterparts

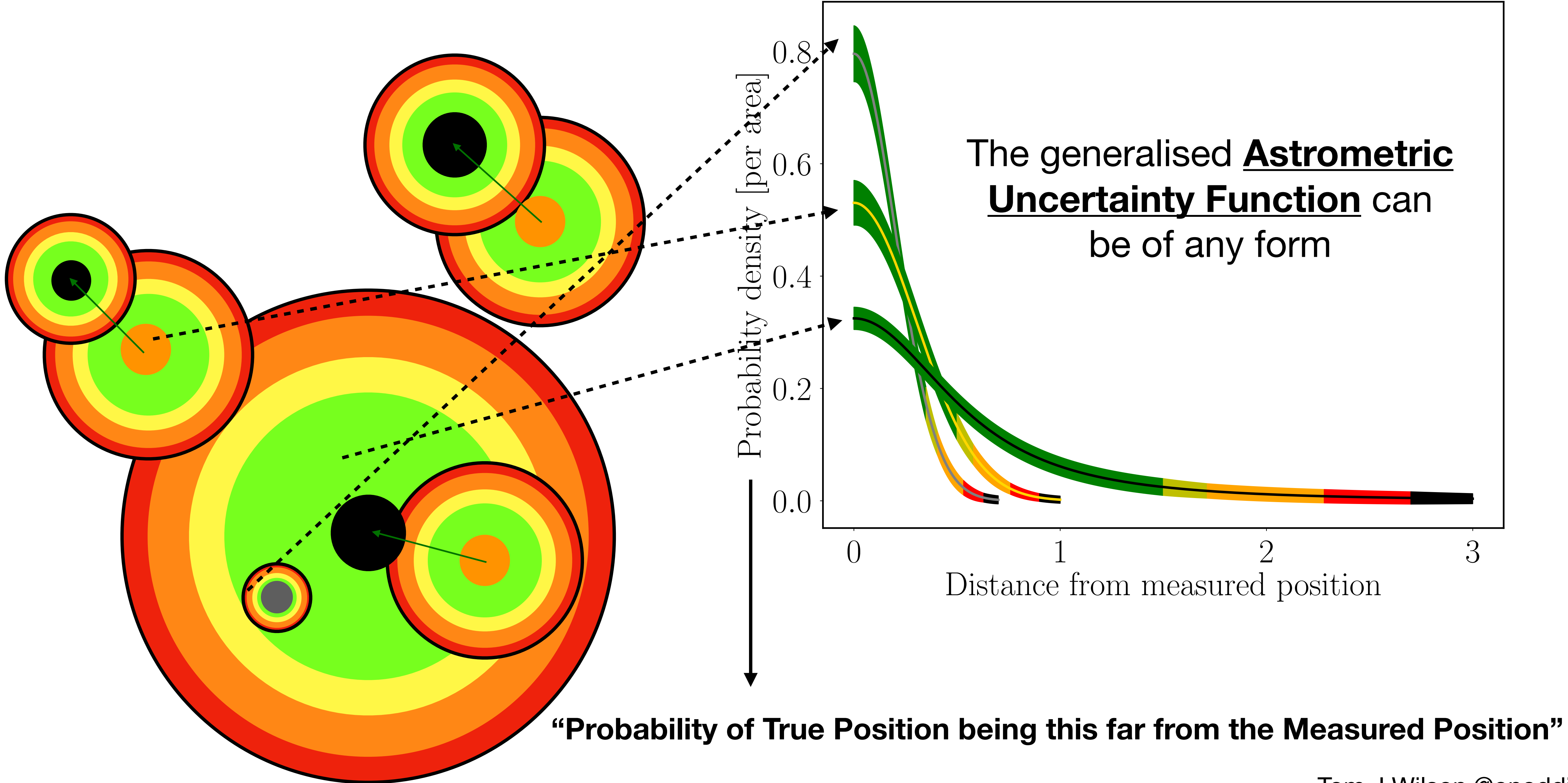
Including Magnitude Information: Rejecting False Positives

$$P(\zeta, \lambda, k | \gamma, \phi) = \frac{1}{K} \times \prod_{\delta \neq \zeta} N_{\gamma} f_{\gamma}^{\delta} \prod_{\omega \neq \lambda} N_{\phi} f_{\phi}^{\omega} \prod_{i=1}^k N_c G_{\gamma\phi}^{\zeta_i \lambda_i} c_{\gamma\phi}^{\zeta_i \lambda_i}$$

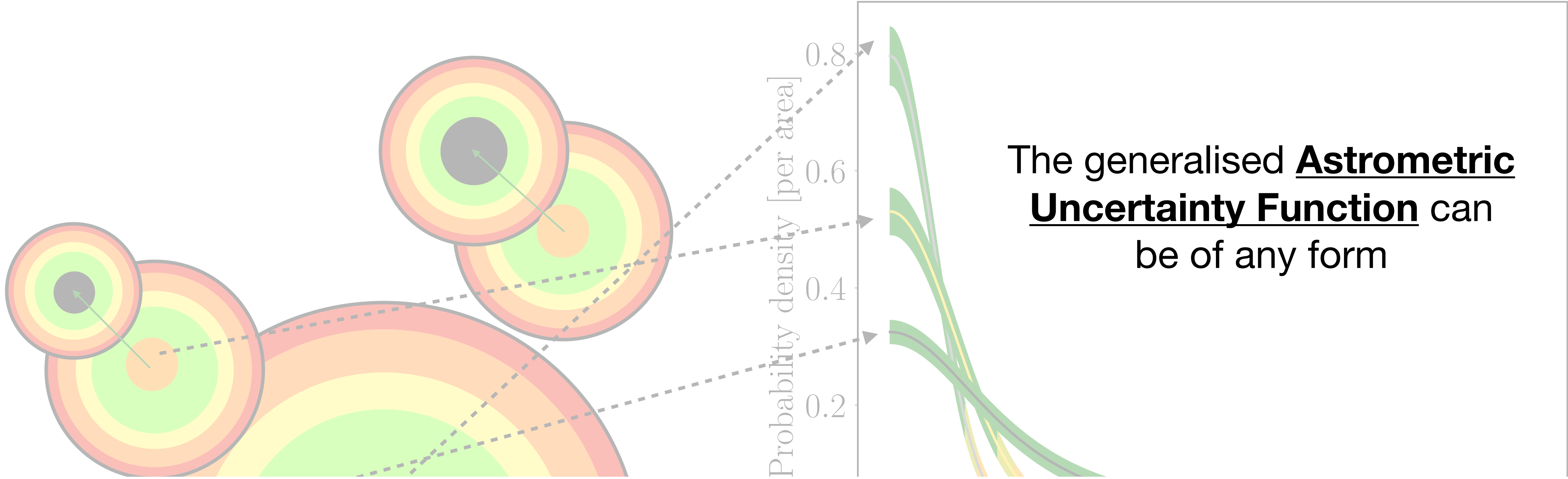


The photometry-based likelihoods (c and f) allow us to mitigate high false positive rate in crowded fields, but now we need the position-based likelihood G

Probabilistic Cross-Matching: the AUF



Probabilistic Cross-Matching: the AUF



One assumption made in basically all literature: positional errors of sources are Gaussian!

$$dp(r|id) = r \times e^{-r^2/2} dr.$$

de Ruiter, Willis, & Arp (1977)

$$P(i) = \frac{\frac{Xc(m_i) g(\Delta x_i, \Delta y_i)}{Nf(m_i)}}{1 - X + \sum_j \frac{Xc(m_j) g(\Delta x_j, \Delta y_j)}{Nf(m_j)}}$$

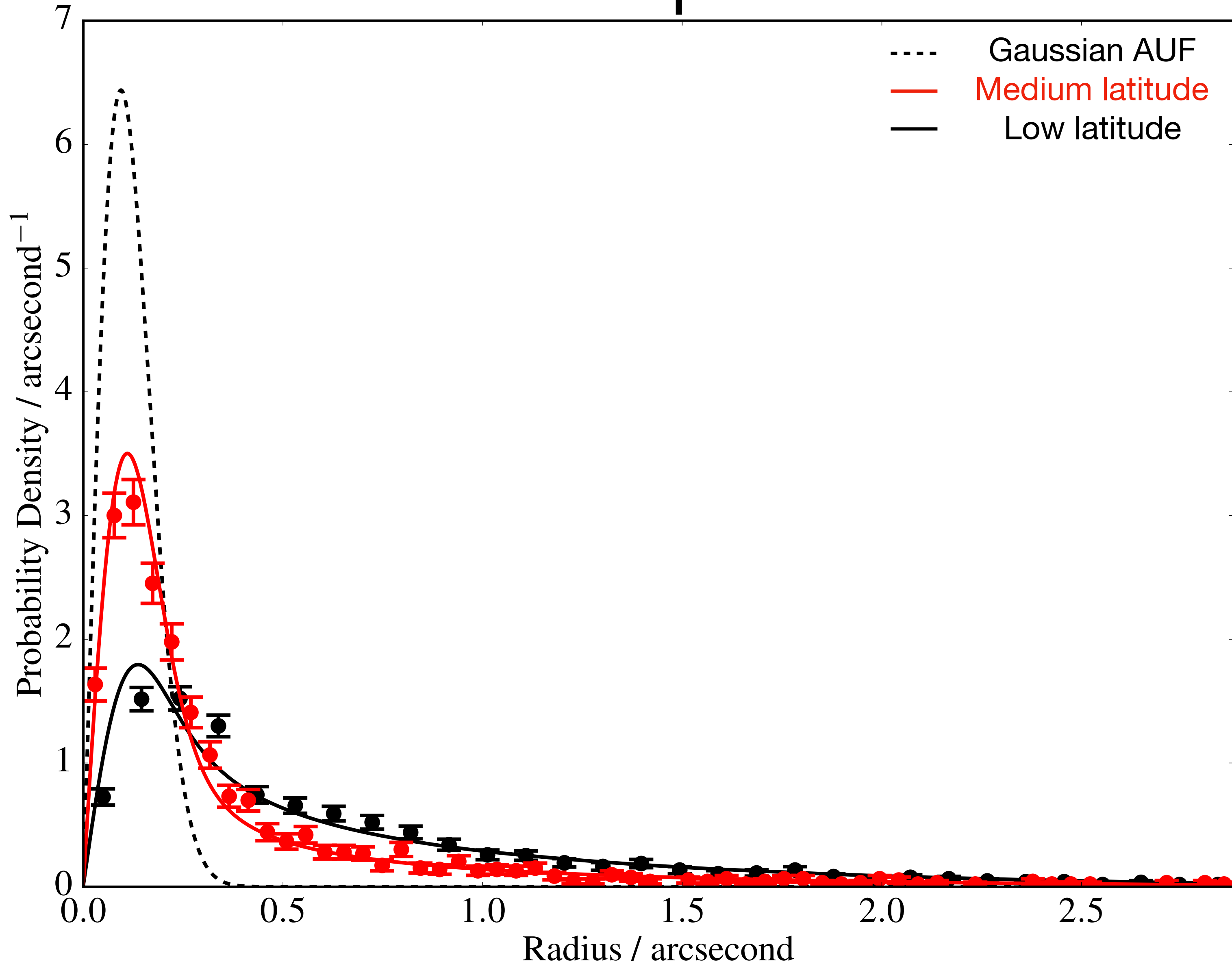
Naylor, Broos, & Feigelson (2013)

$$p(D|H) = \int p(m|H) \prod_{i=1}^n p_i(x_i|m, H) d^3m$$

Budavári & Szalay (2008)

“Probability of True Position being this far from the Measured Position”

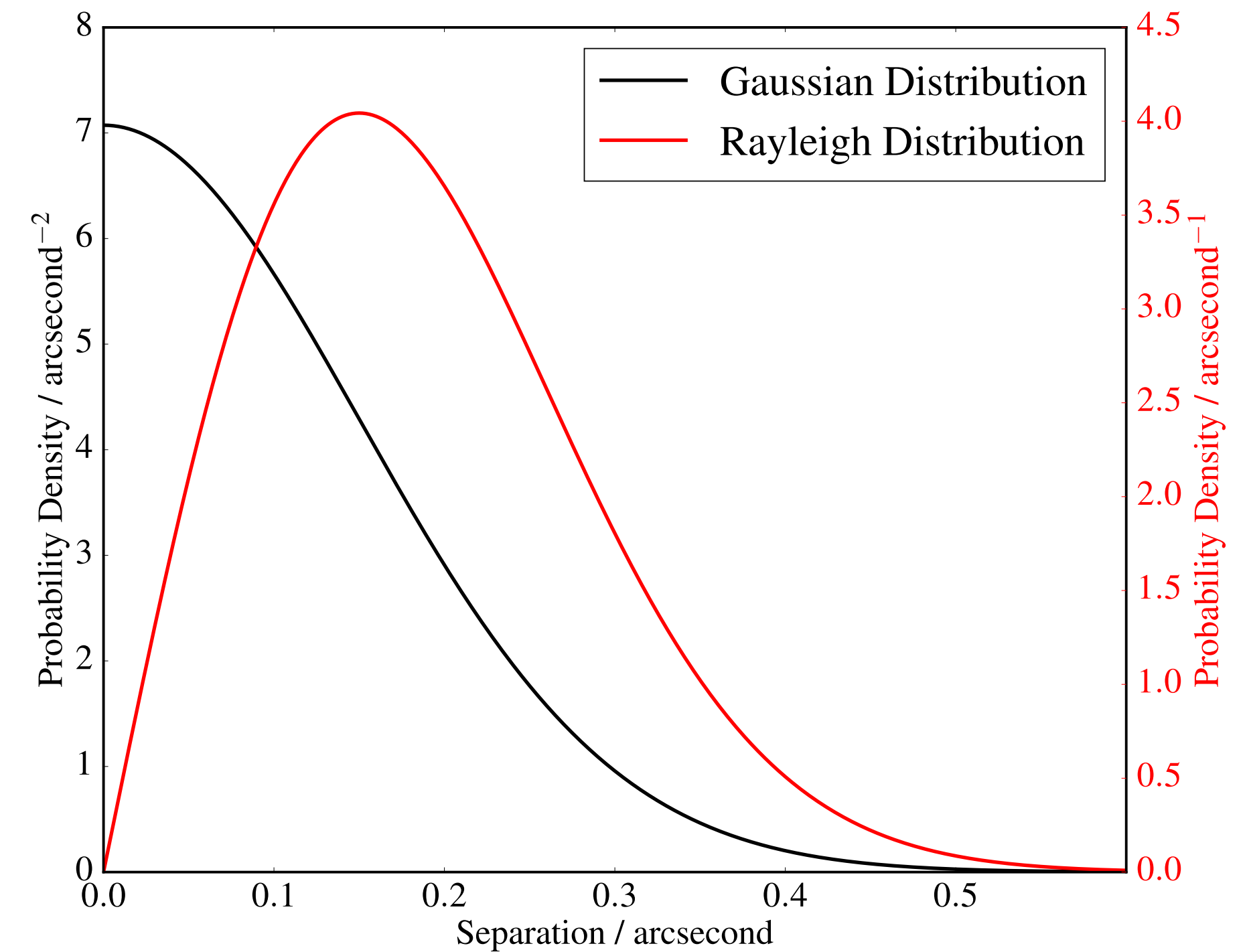
Additional Components of the AUF



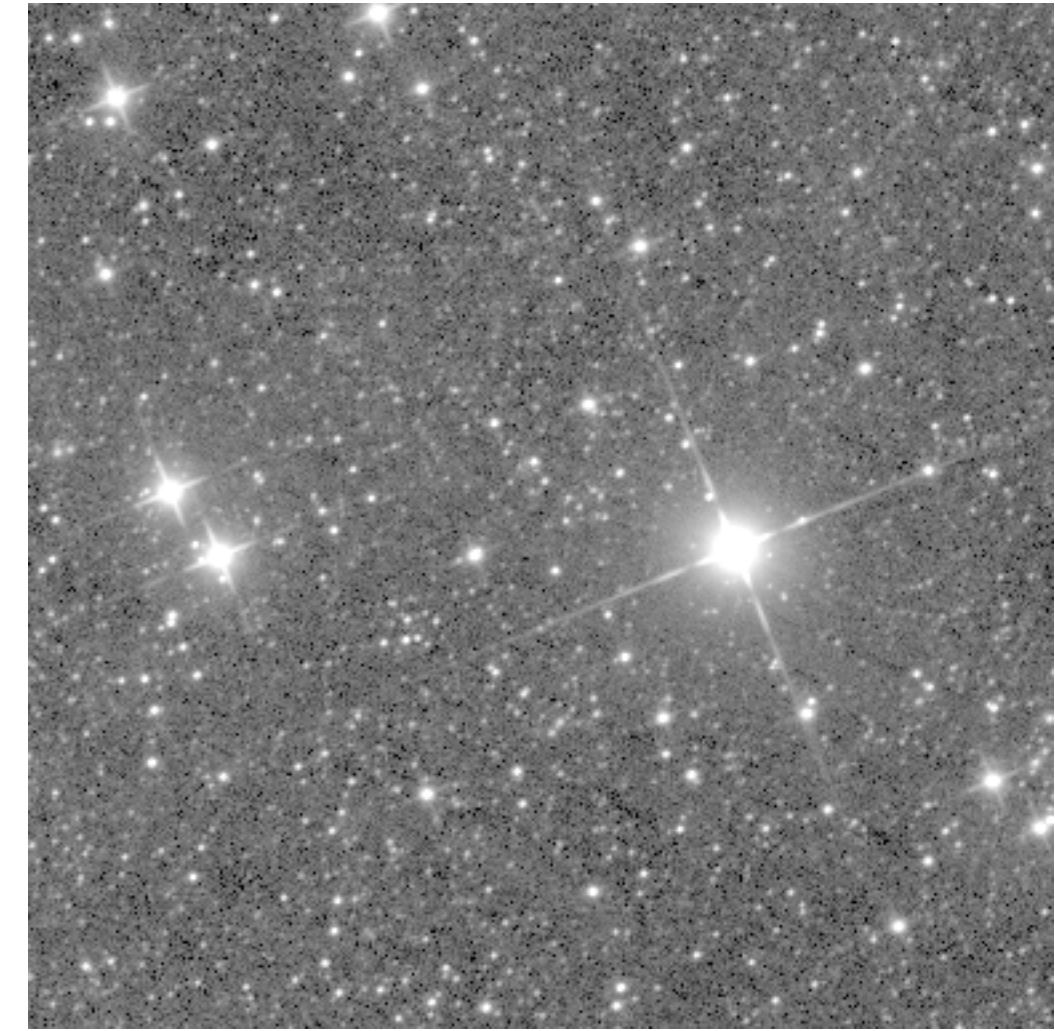
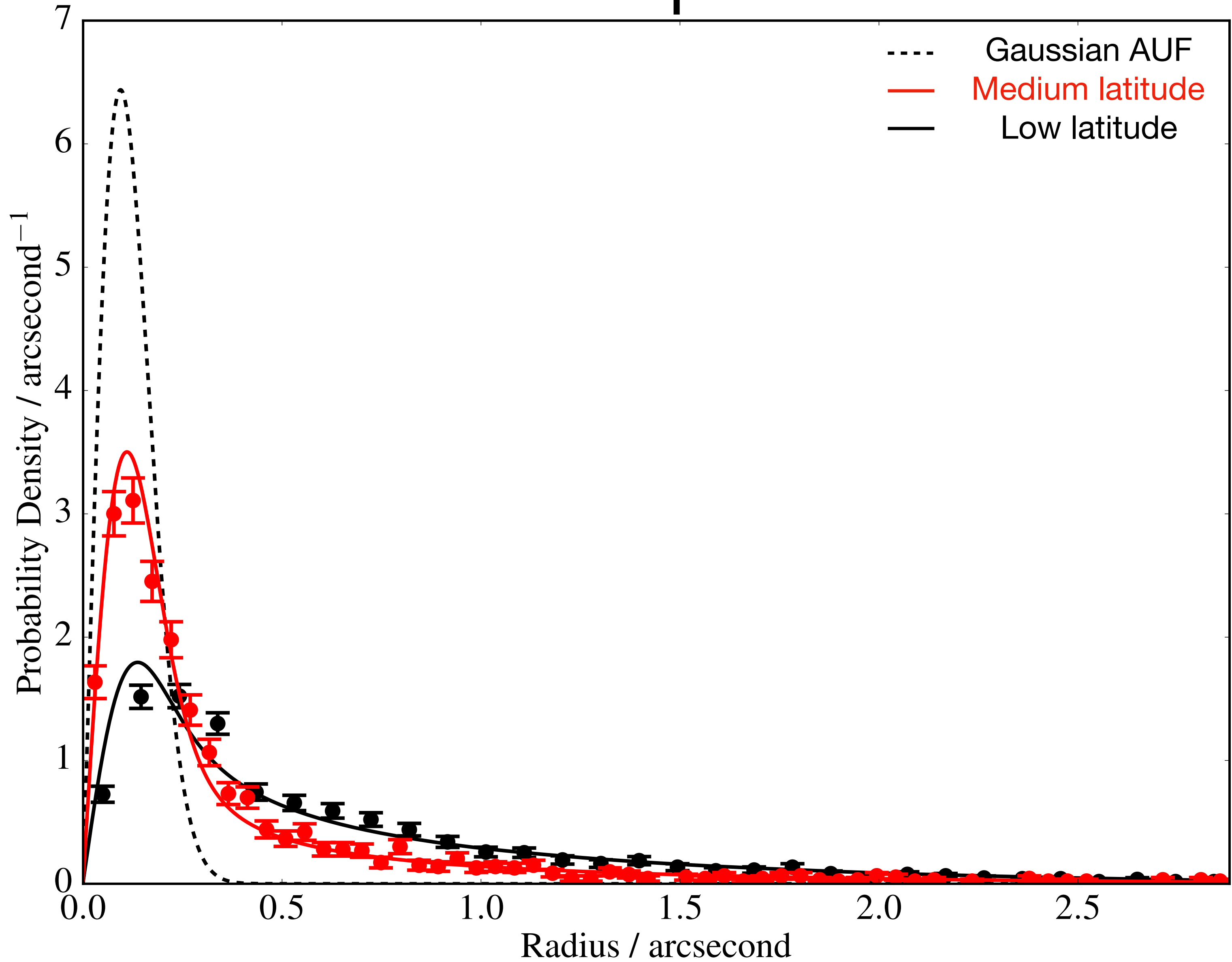
$$g(x, y, \sigma) = (2\pi\sigma^2)^{-1} \exp\left(-\frac{1}{2} \frac{x^2 + y^2}{\sigma^2}\right)$$

↓

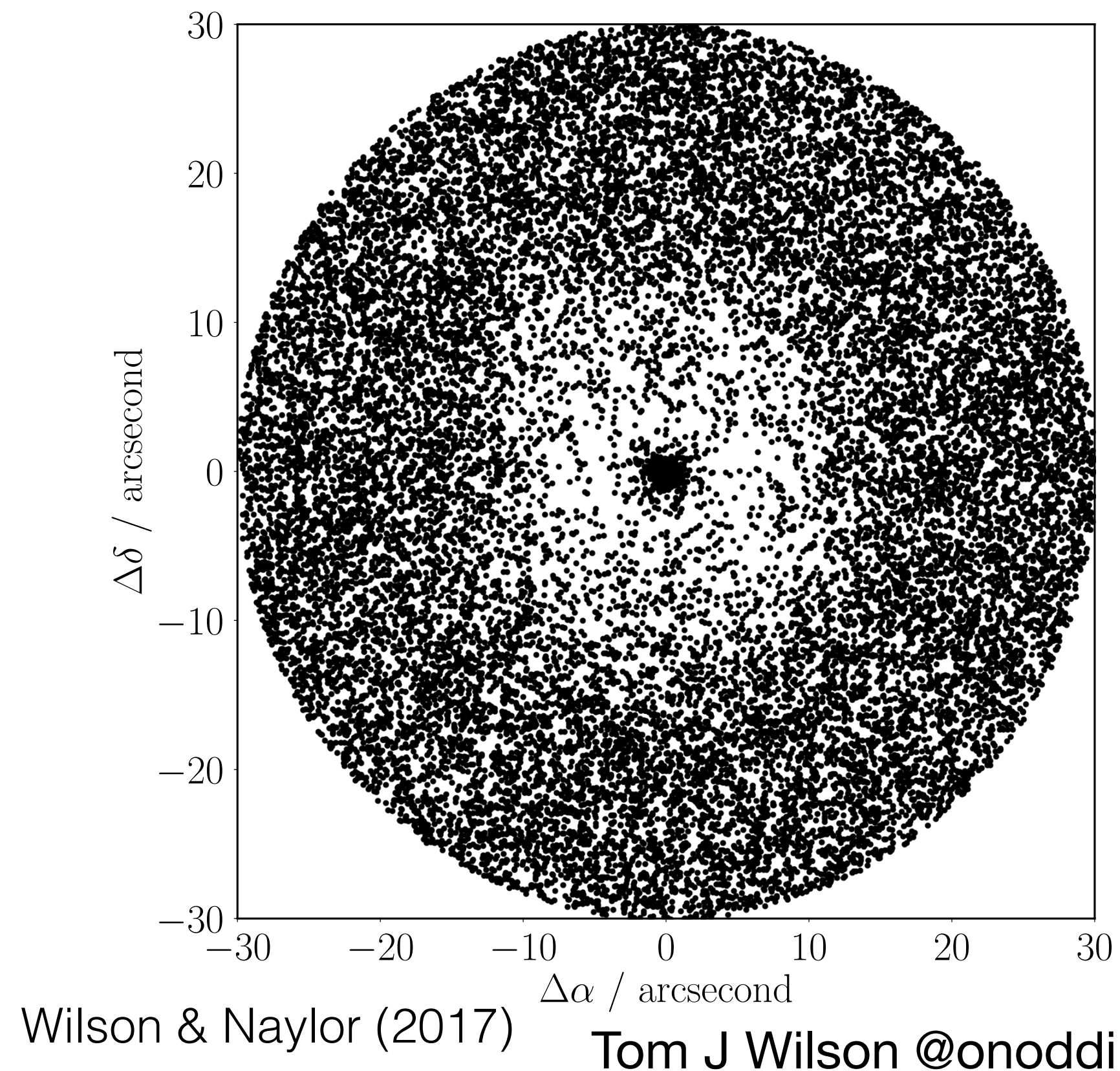
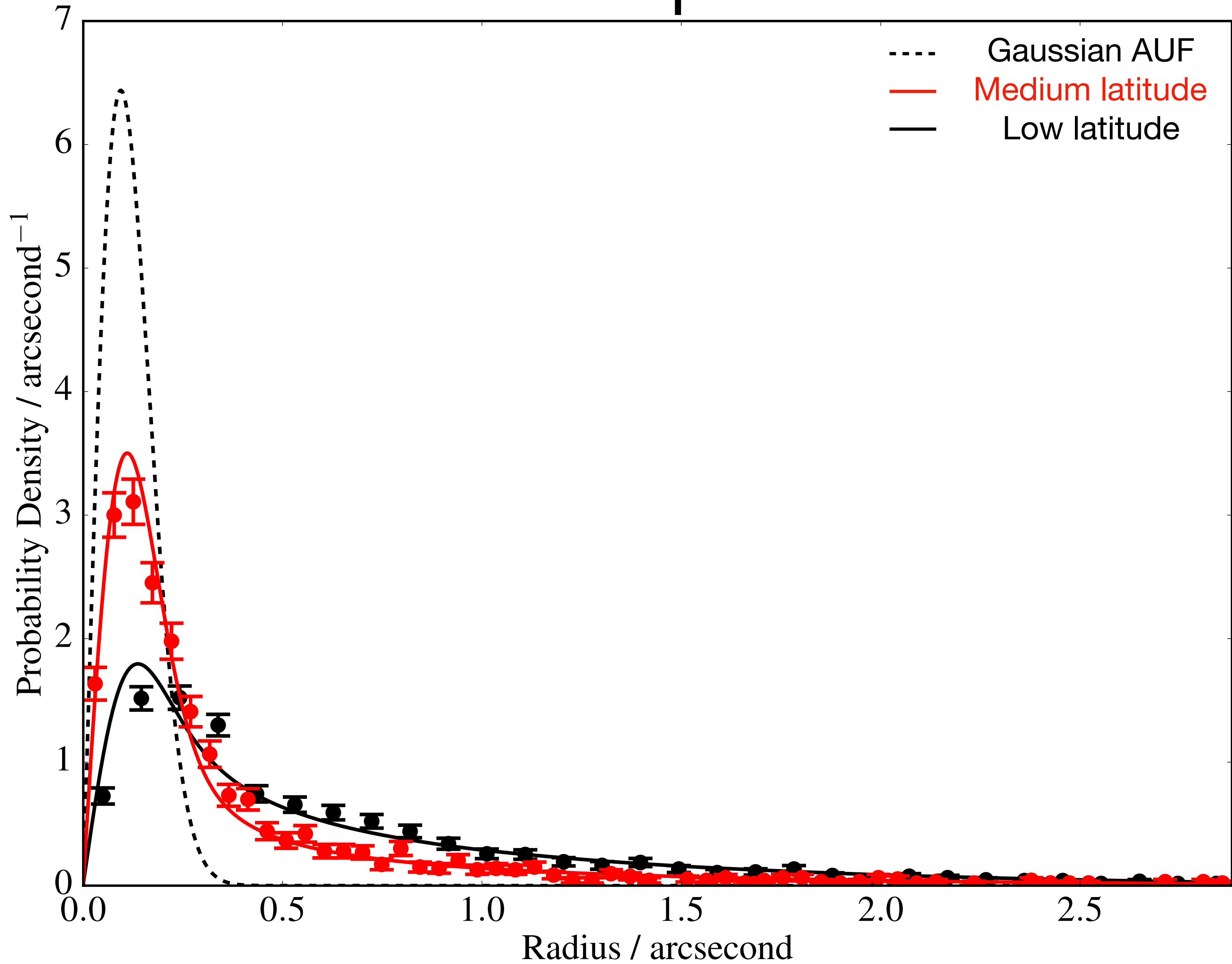
$$g(r, \sigma) = \frac{r}{\sigma^2} \exp\left(-\frac{1}{2} \frac{r^2}{\sigma^2}\right)$$



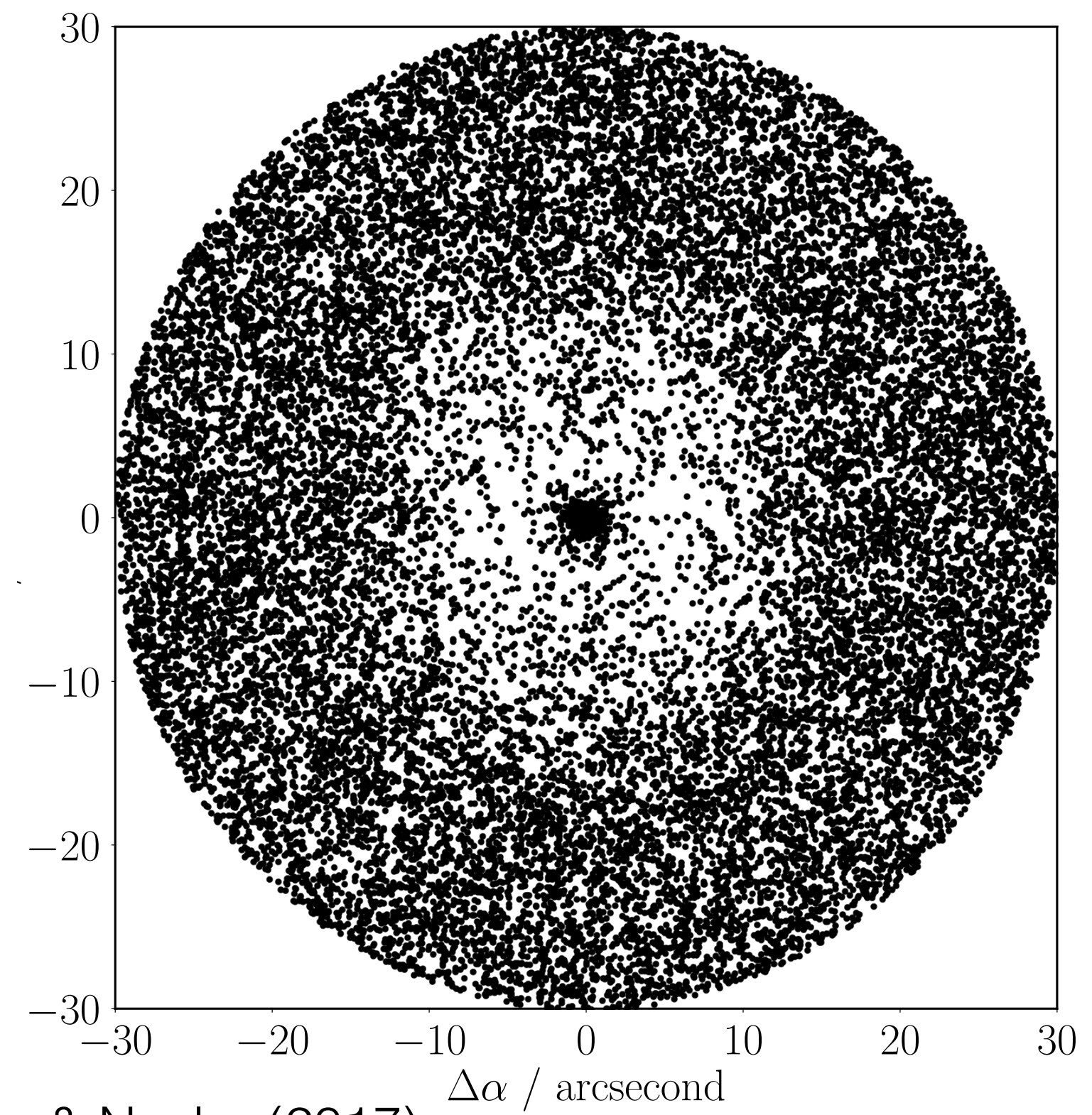
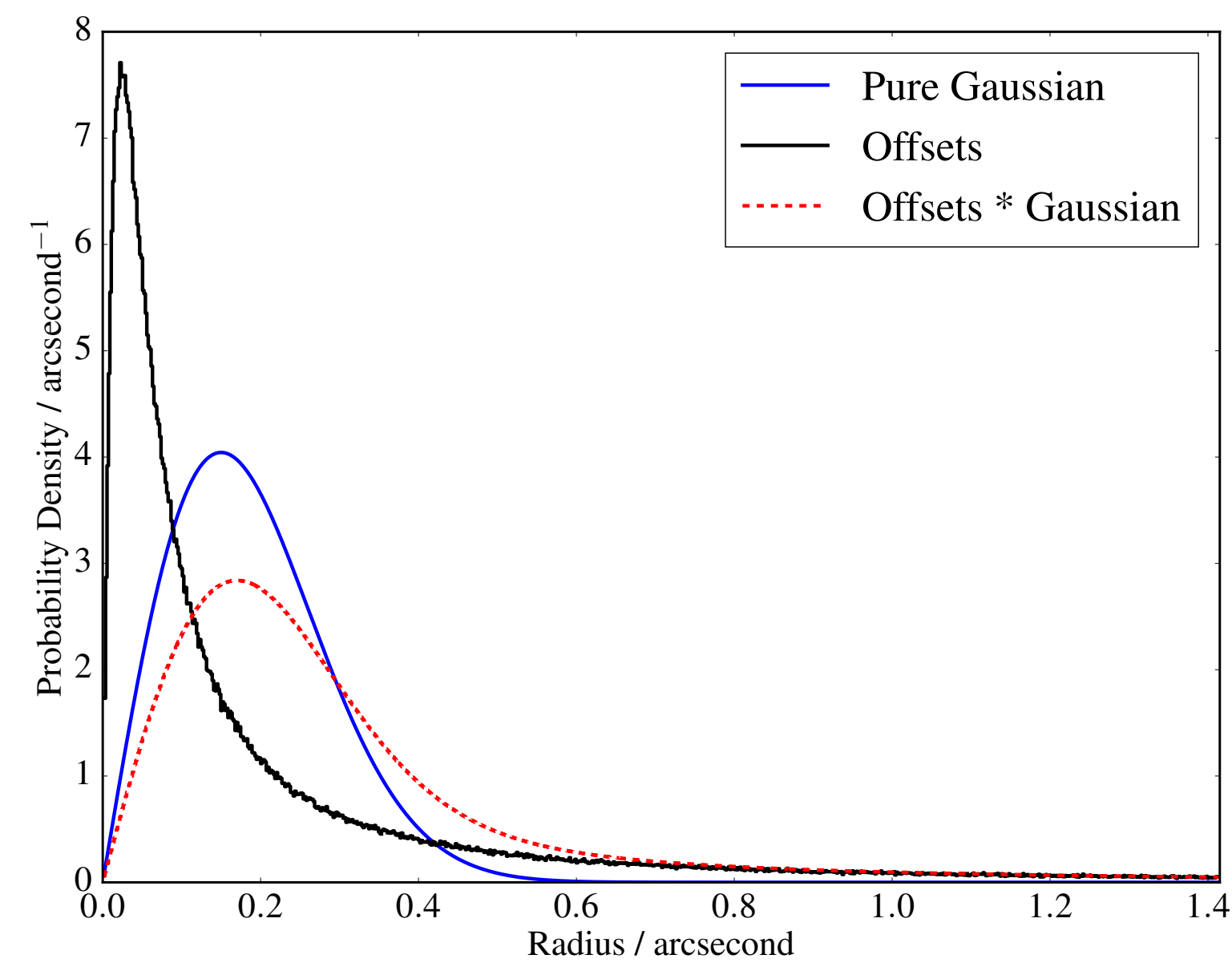
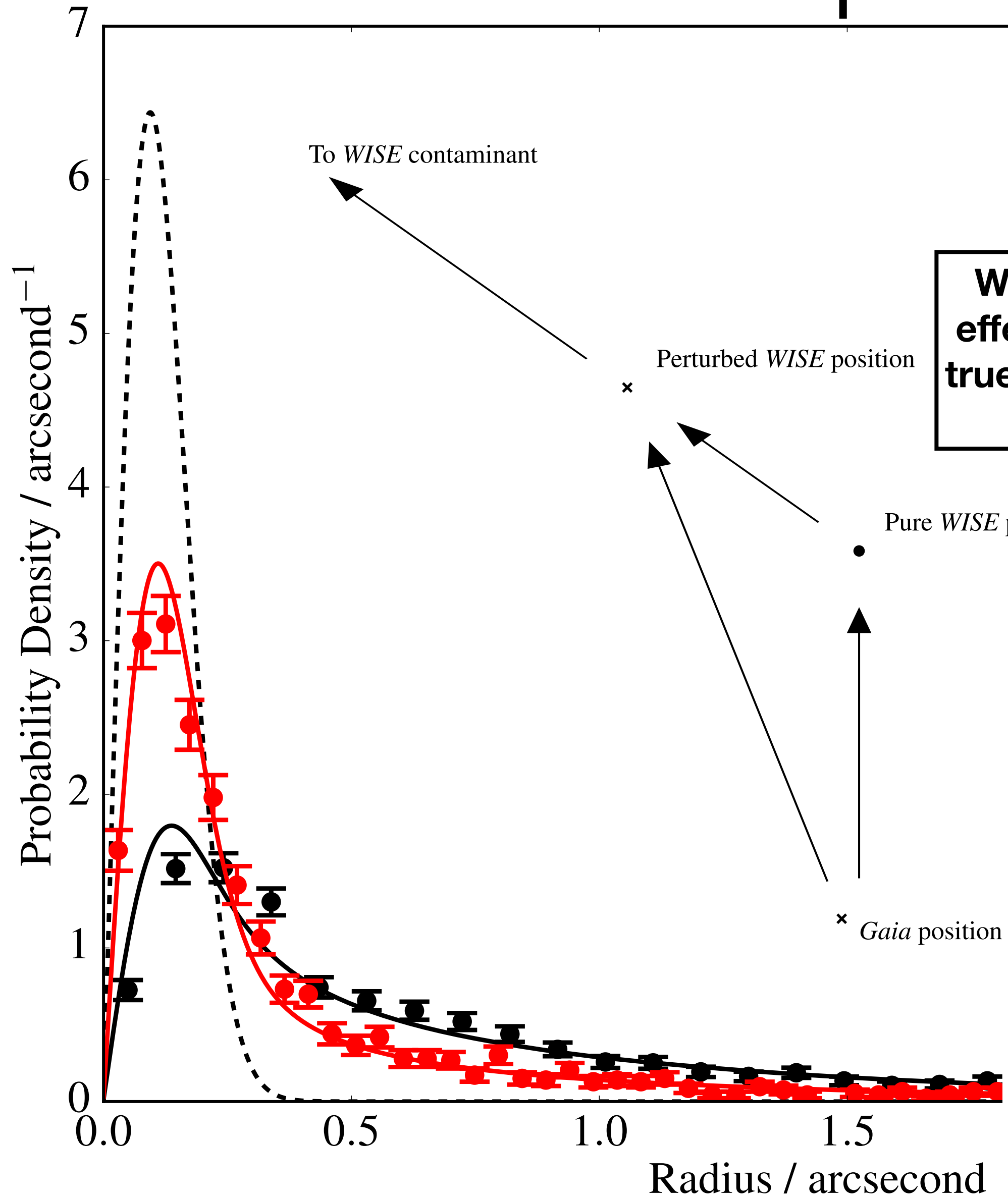
Additional Components of the AUF



Additional Components of the AUF (and any other systematic — e.g. proper motions, cf. Wilson 2023, RASTI)



Additional Components of the AUF (and any other systematic — e.g. proper motions, cf. Wilson 2023, RASTI)



WISE - Wright et al. (2010)

Gaia DR2 - Gaia Collaboration, Brown A. G. A., et al. (2018)

Wilson & Naylor (2018b)

Wilson & Naylor (2017)

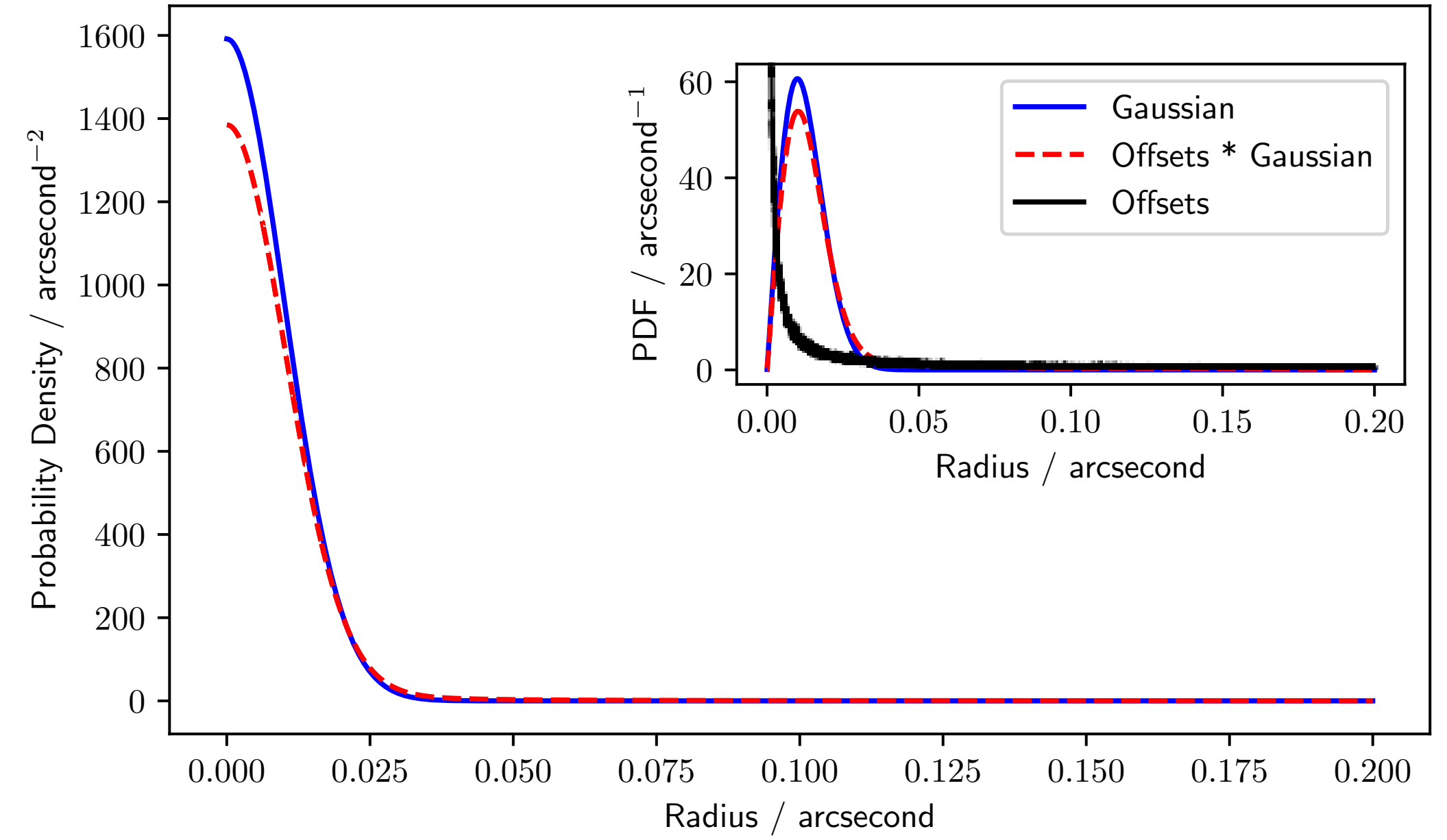
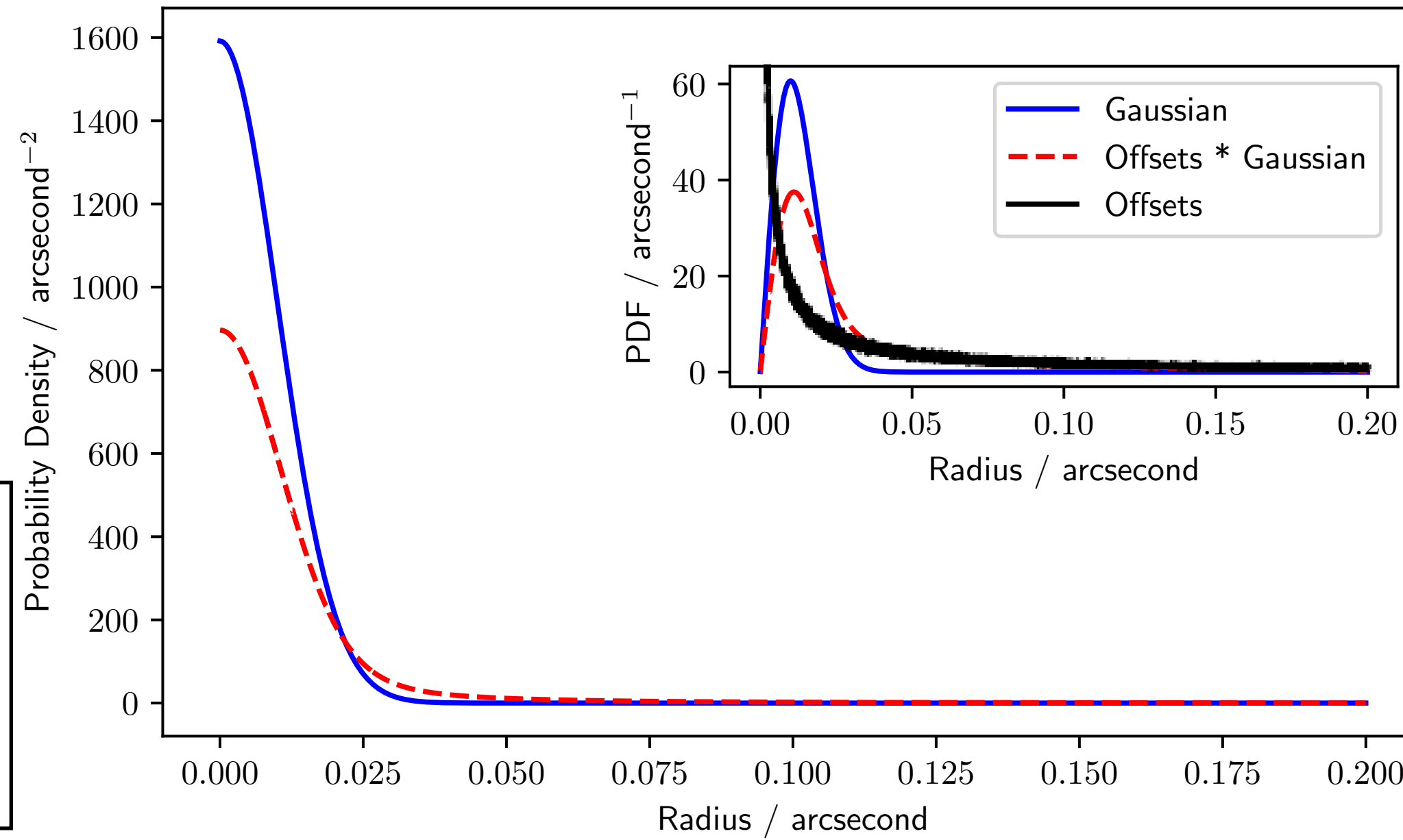
The Rubin AUF: Galactic Plane

Galactic Centre

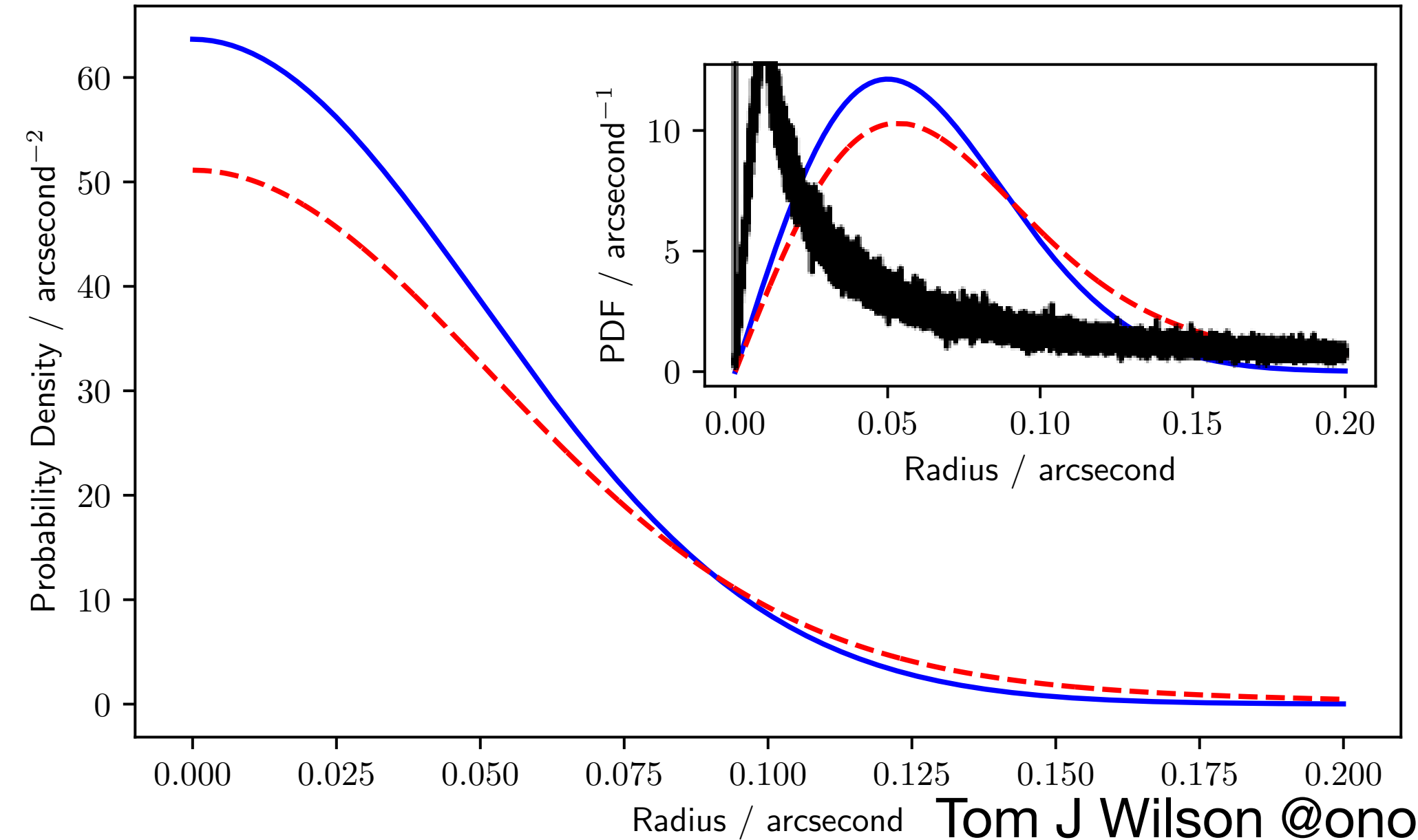
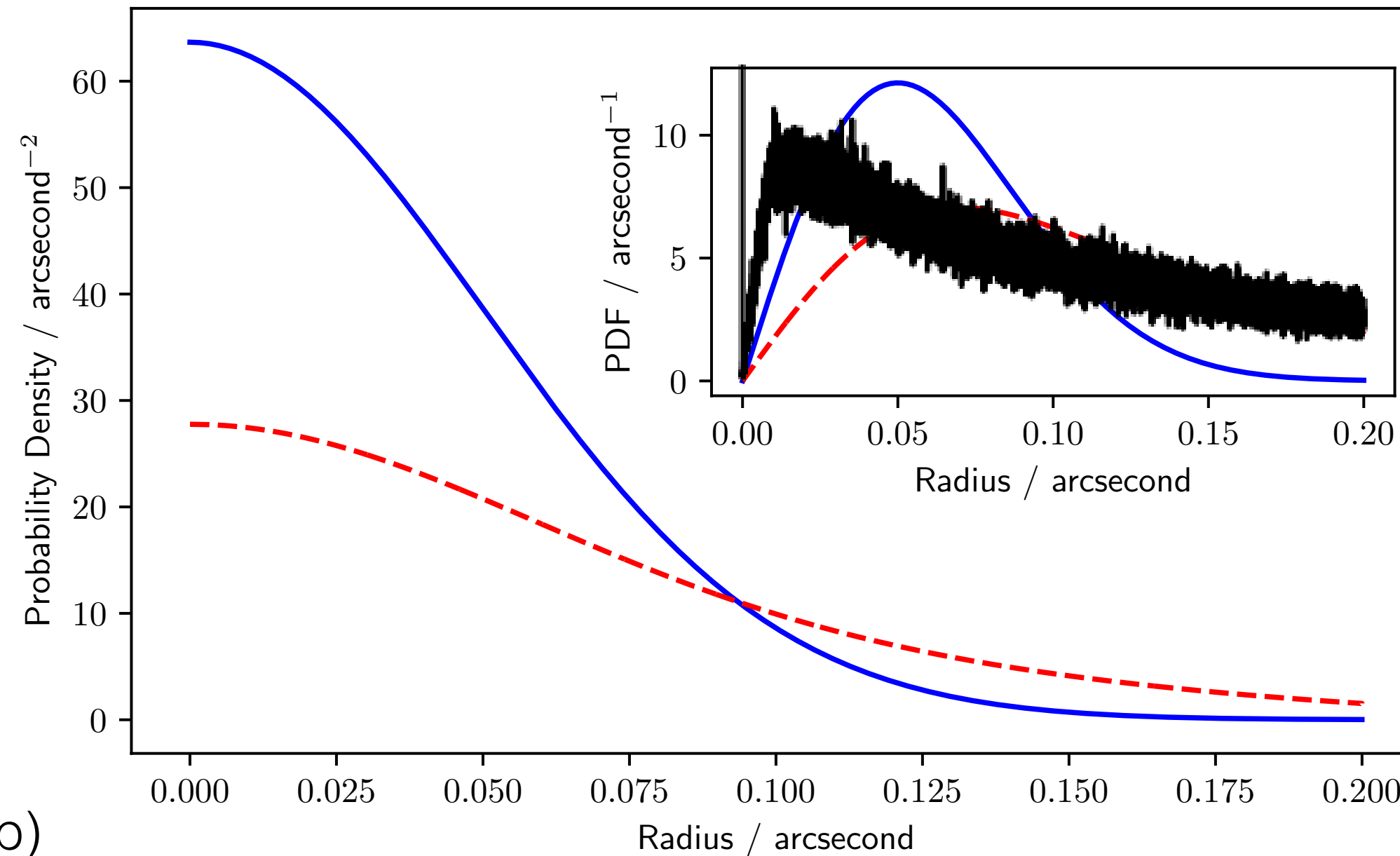
Not the Galactic Centre

Single-visit

Without modelling this extra effect, we fail to recover many true pairings, with an artificially high false negative rate!

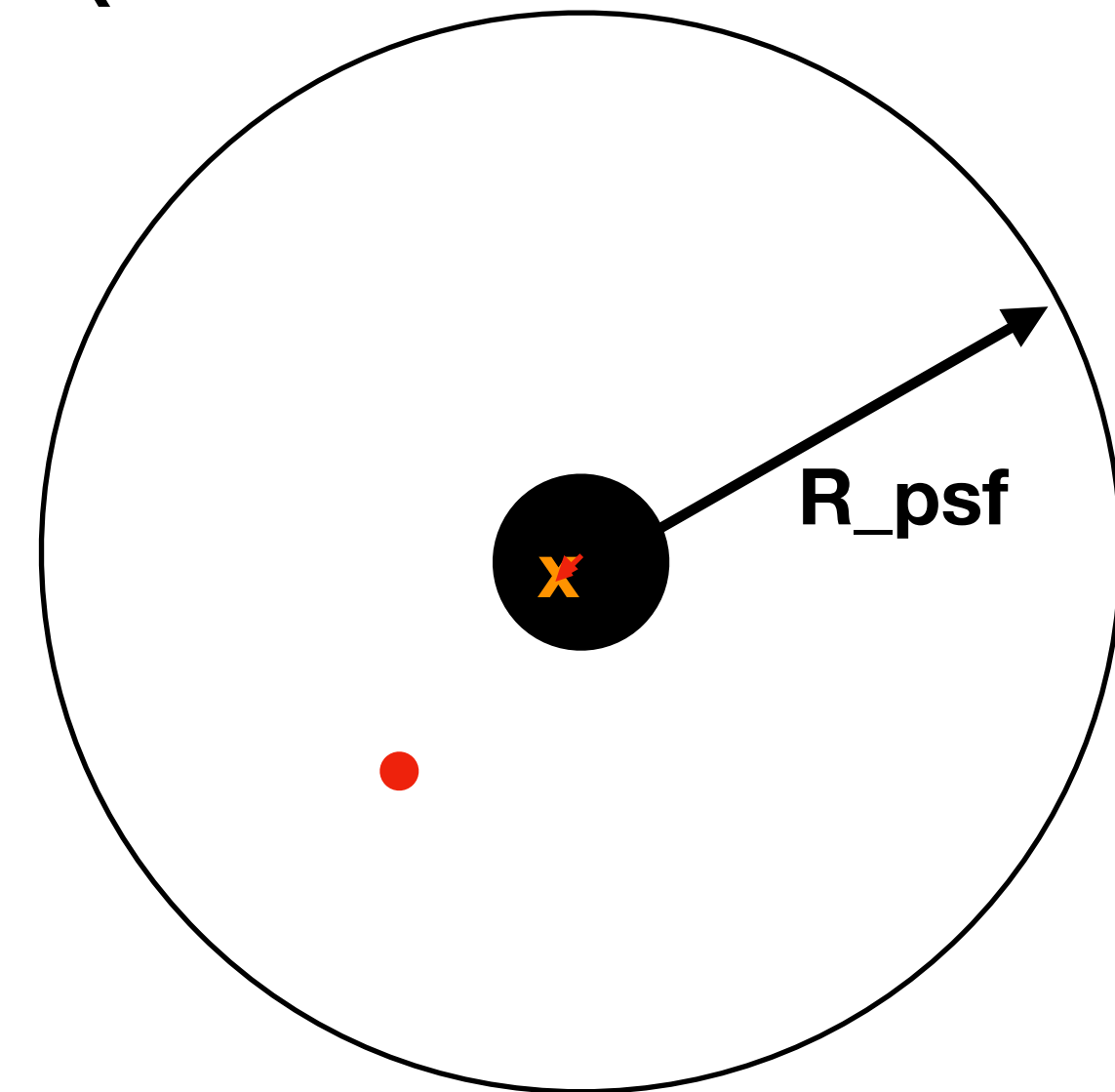
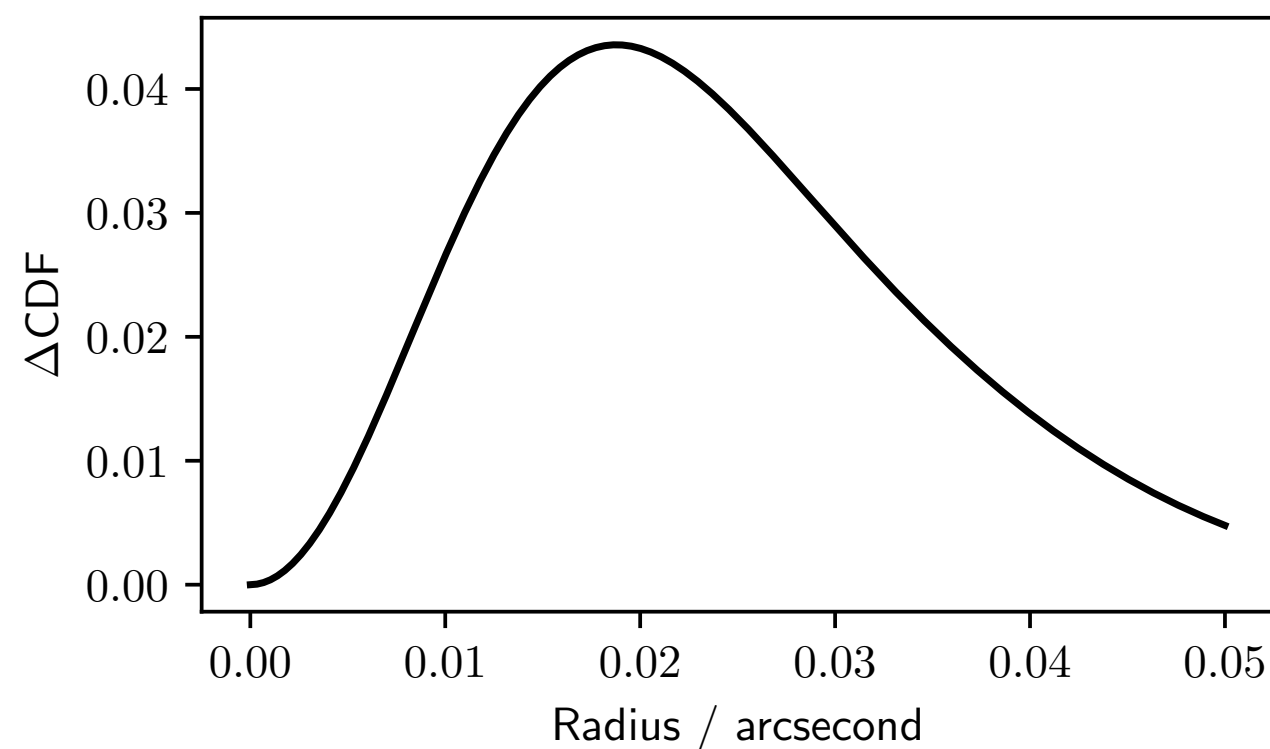
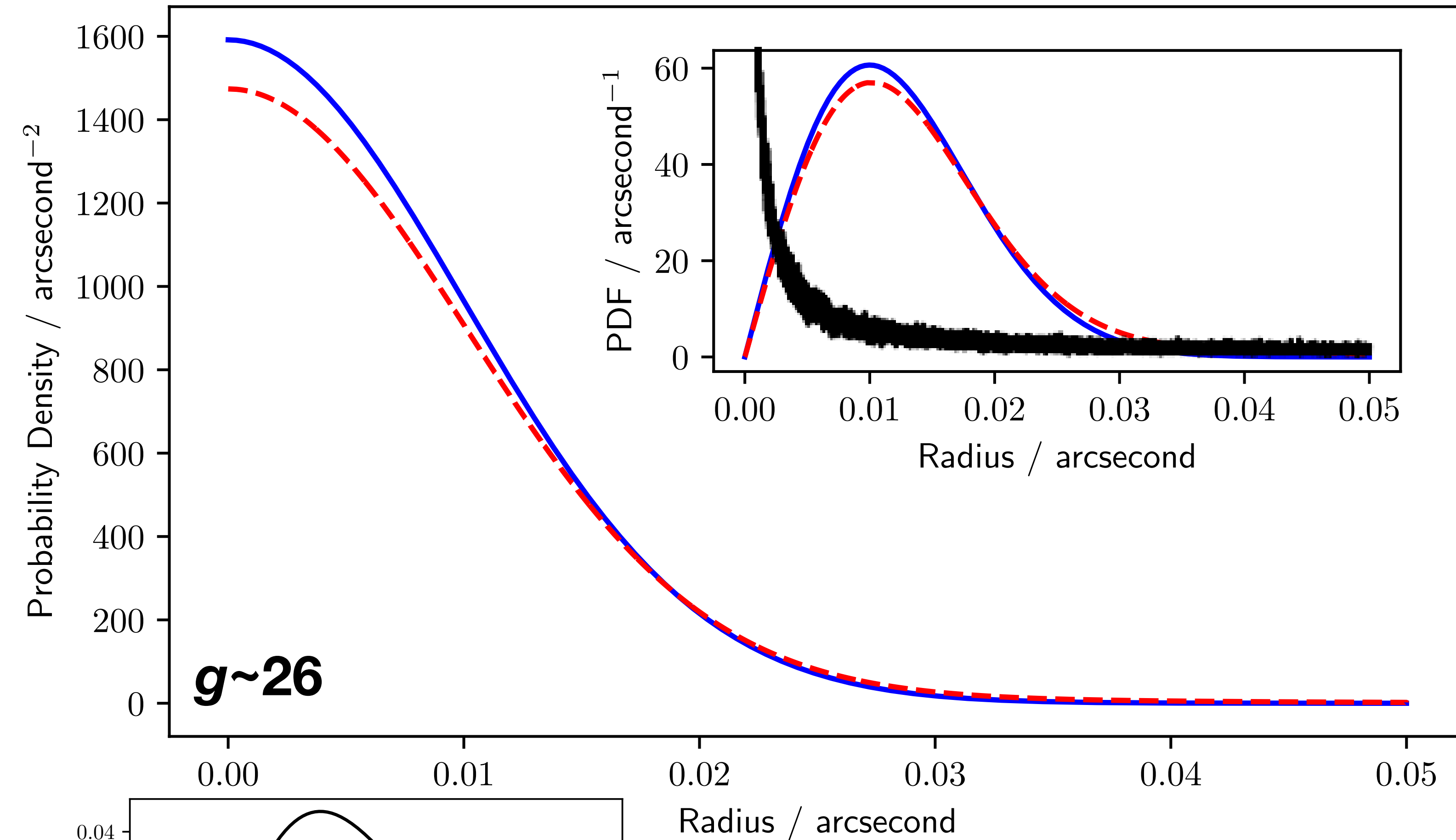


Co-add

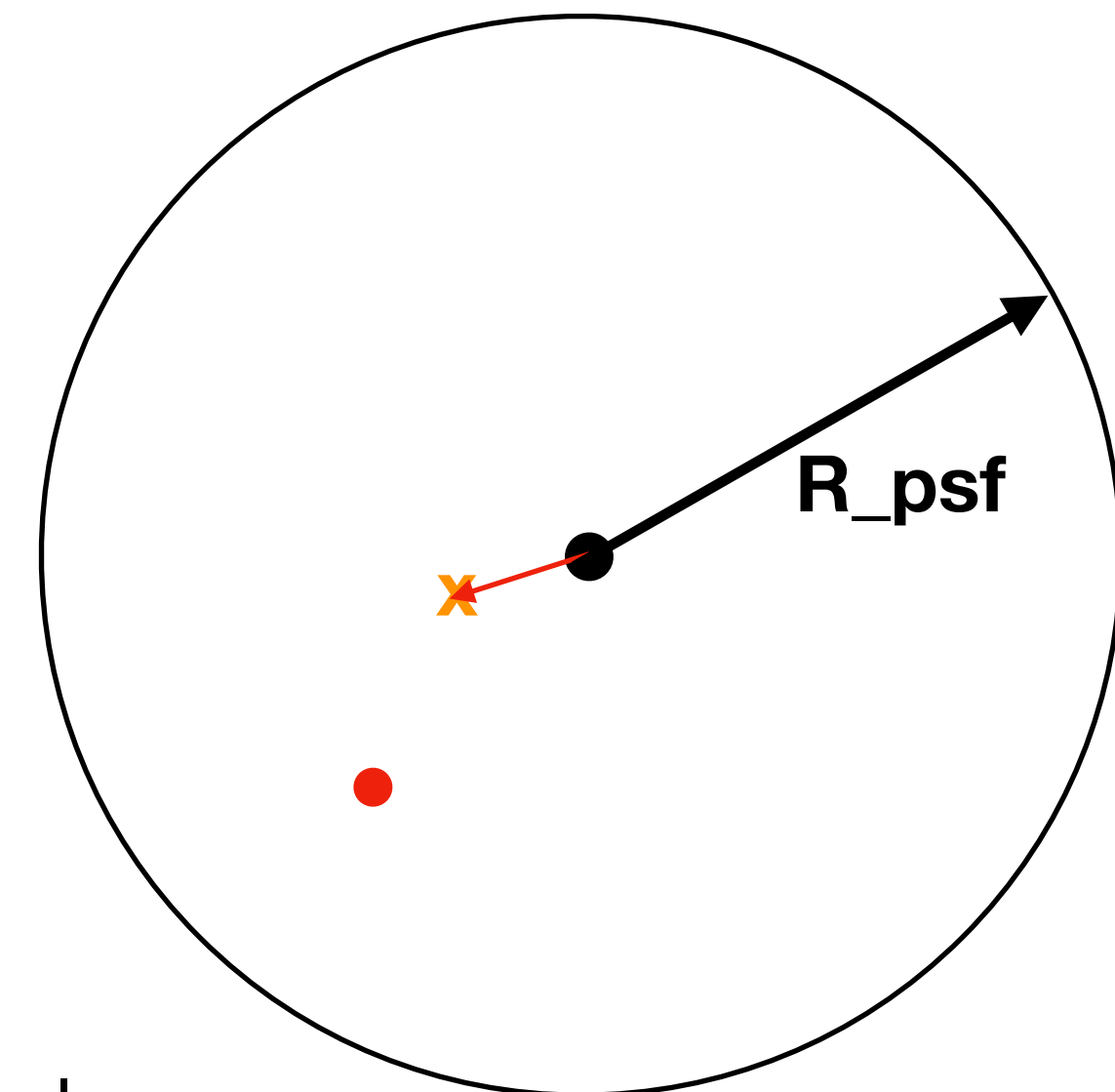


The Rubin AUF: \checkmark Extra-Galactic (Transients)

(very well-behaved!)



Explosion

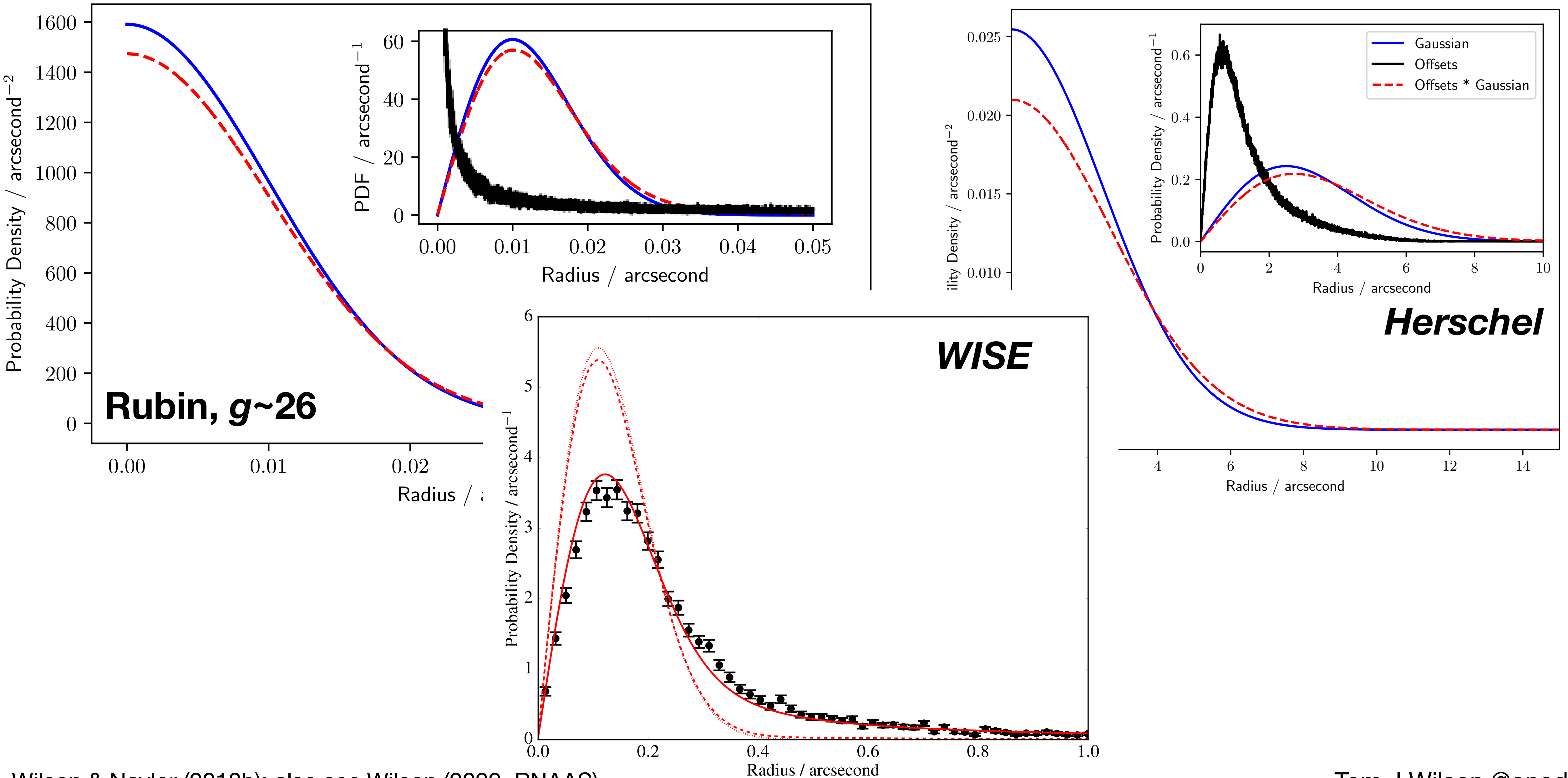


Progenitor

Wilson & Naylor (2018b); also
see Wilson (2022, RNAAS)

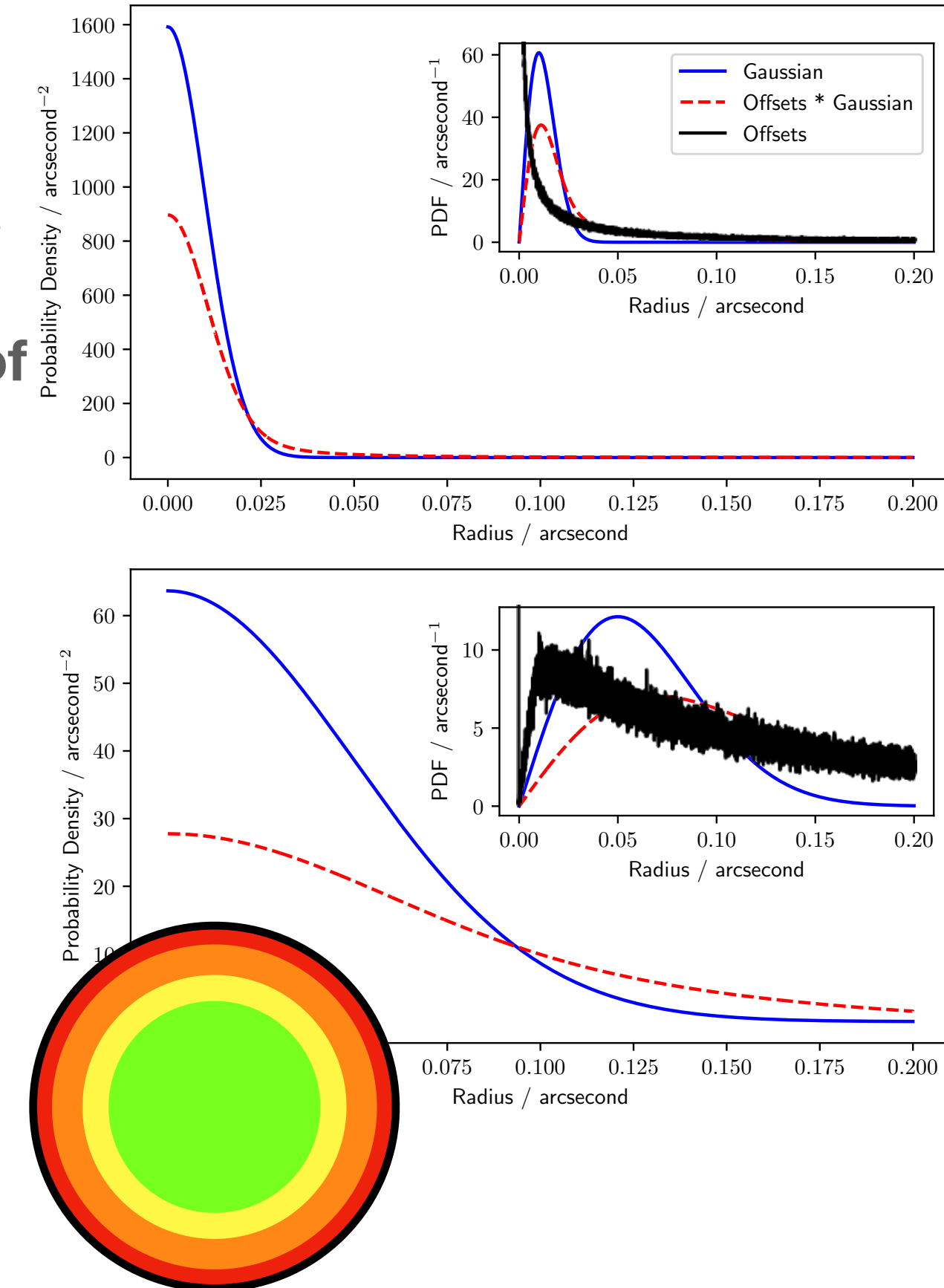
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The Rubin AUF: Extra-Galactic (Transients)



Conclusions

- Our cross-match algorithms include two key elements to avoid issues with crowded & confused data
 - A generalised approach to the Astrometric Uncertainty Function allows for the full inclusion of the effects of perturbation due to blended sources — reduce false -ves!
 - Where it can be applied (i.e., the static sky) use of (two-sided) photometry to sort out multiplicity of higher resolution data — reduce false +ves!
- Software package macauff developed to cross-match catalogues, including the effect of unresolved contaminant sources (and rejection of interloper objects using photometry in the static sky)
 - Developed through an IKC to Rubin/LSST:UK, matches planned to *Gaia*, *WISE*, *VISTA*, *SDSS*, ...
 - We have compute time to cross-match datasets — let me know your favourite combo, and what you need matched (to LSST or otherwise)!
- Incorporating this extension of position uncertainty into real-time matches allows for more robust counterpart identification in the alert stream and a more accurate and precise transient SED
 - Furthermore, we can provide *statistical* information on the level of photometric contamination unresolved contaminant sources cause, which can be subtracted in a probabilistic framework!



The AUF does not need to, and in fact quite often should not, be Gaussian!



University of Exeter

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.github.io



Wilson & Naylor, 2017, MNRAS, 468, 2517
Wilson & Naylor, 2018a, MNRAS, 473, 5570
Wilson & Naylor, 2018b, MNRAS, 481, 2148
Wilson, 2022, RNAAS, 6, 60
Wilson, 2023, RASTI, 2, 1

<https://github.com/Onoddil/macauff>



Tom J Wilson @onoddil



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