

Enhancing ^(transient) Rubin Science with Robust Cross-Matches in the Crowded LSST Sky

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transient identification using the alert stream?* 9/Aug/23

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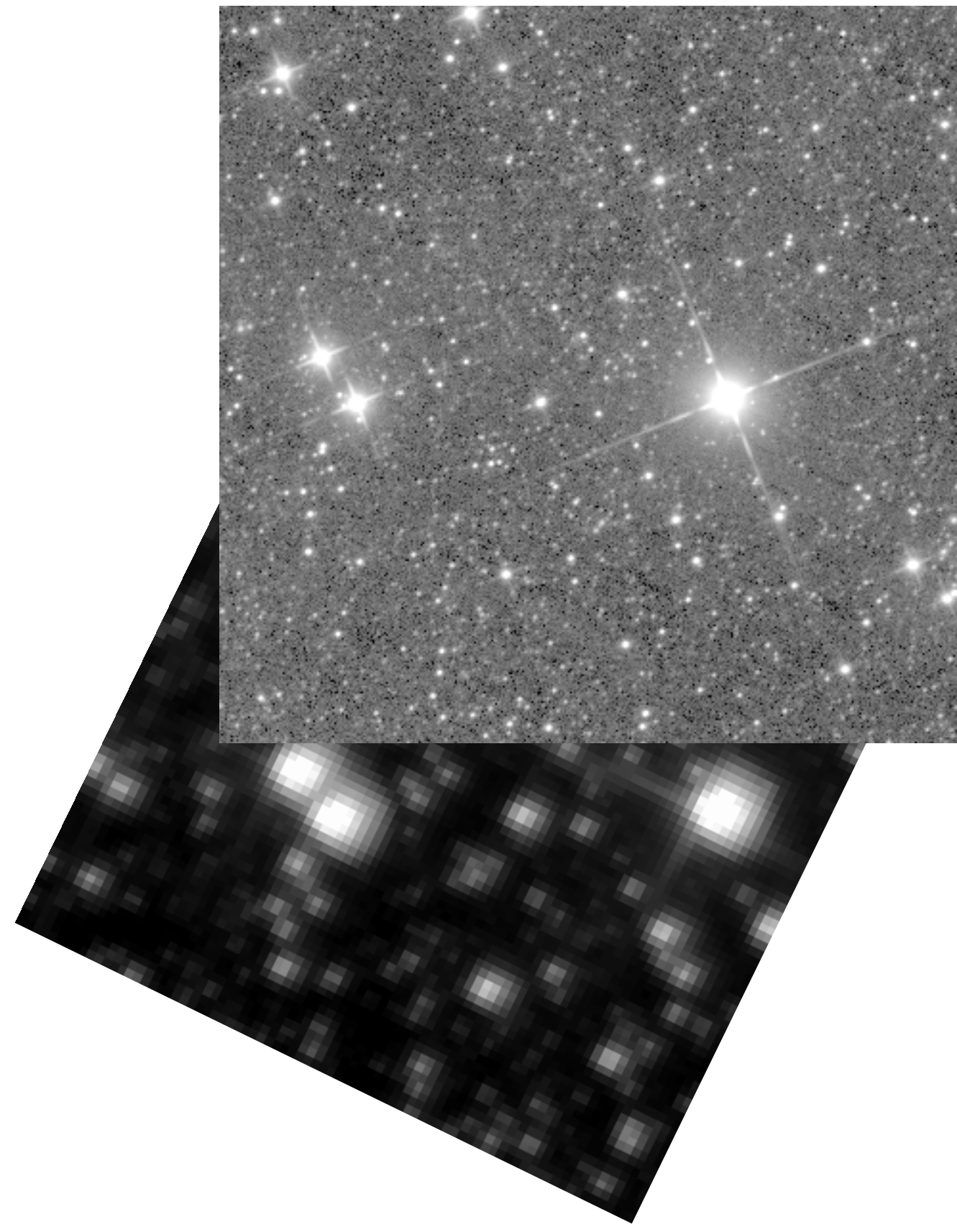
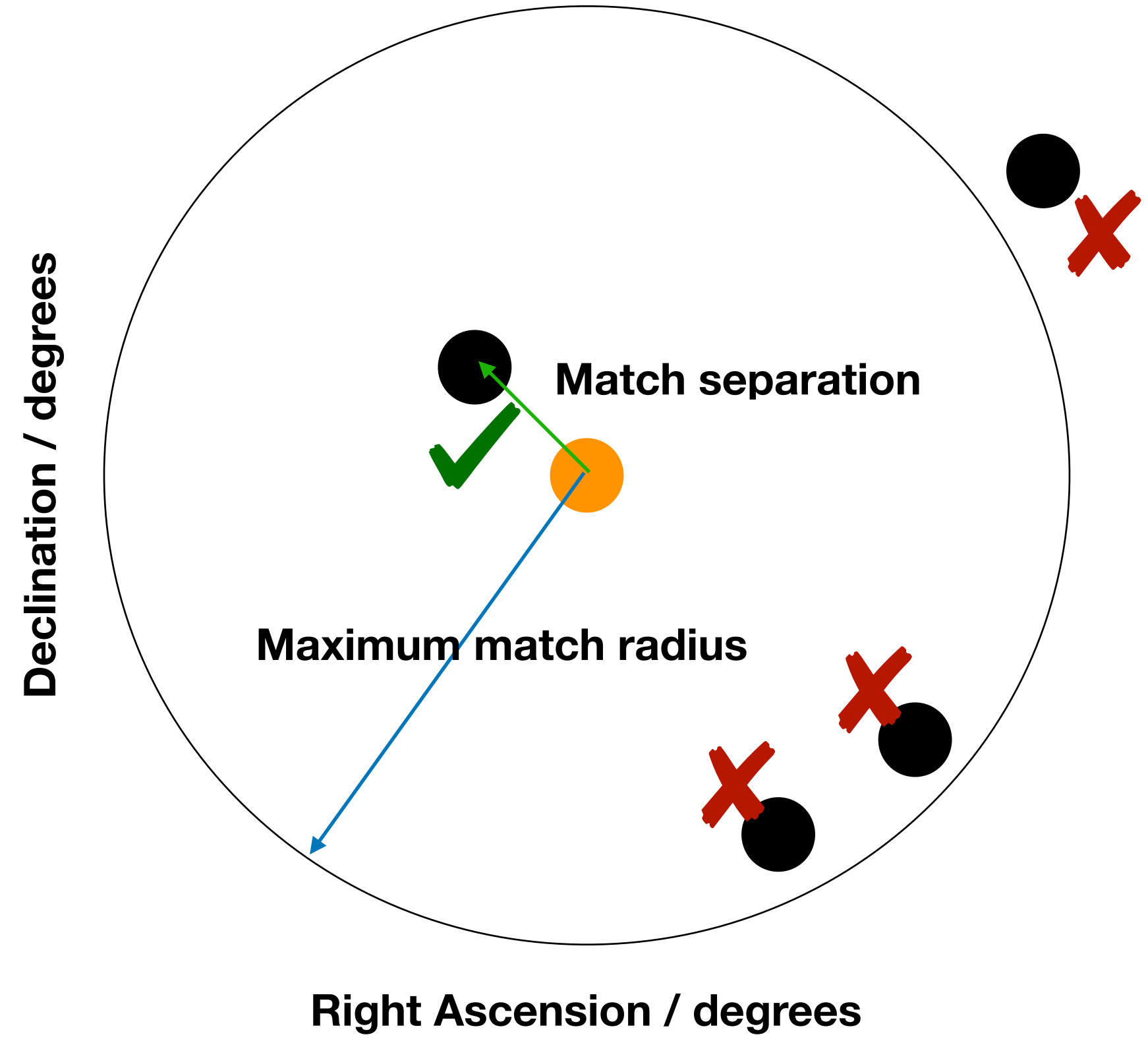
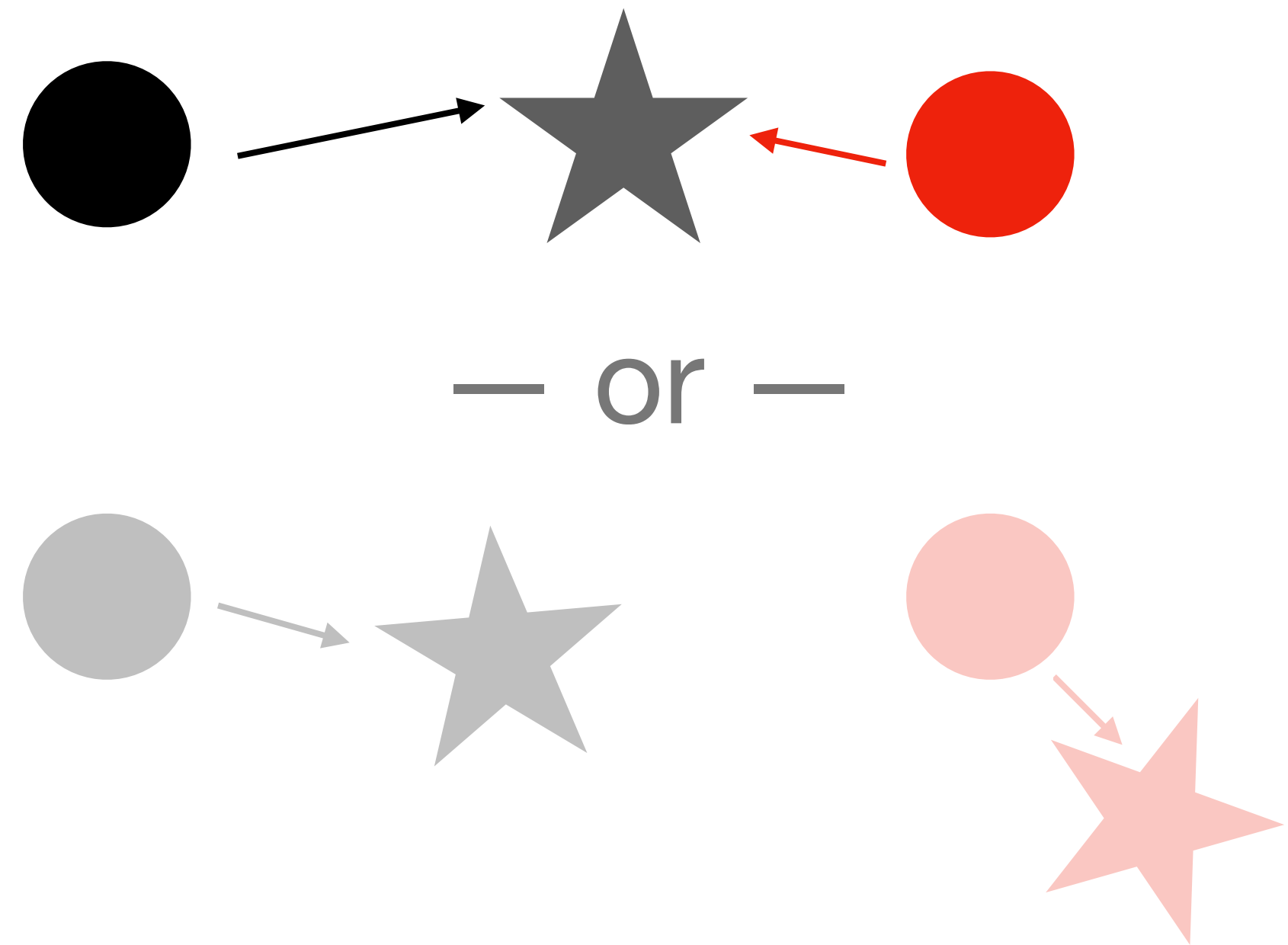
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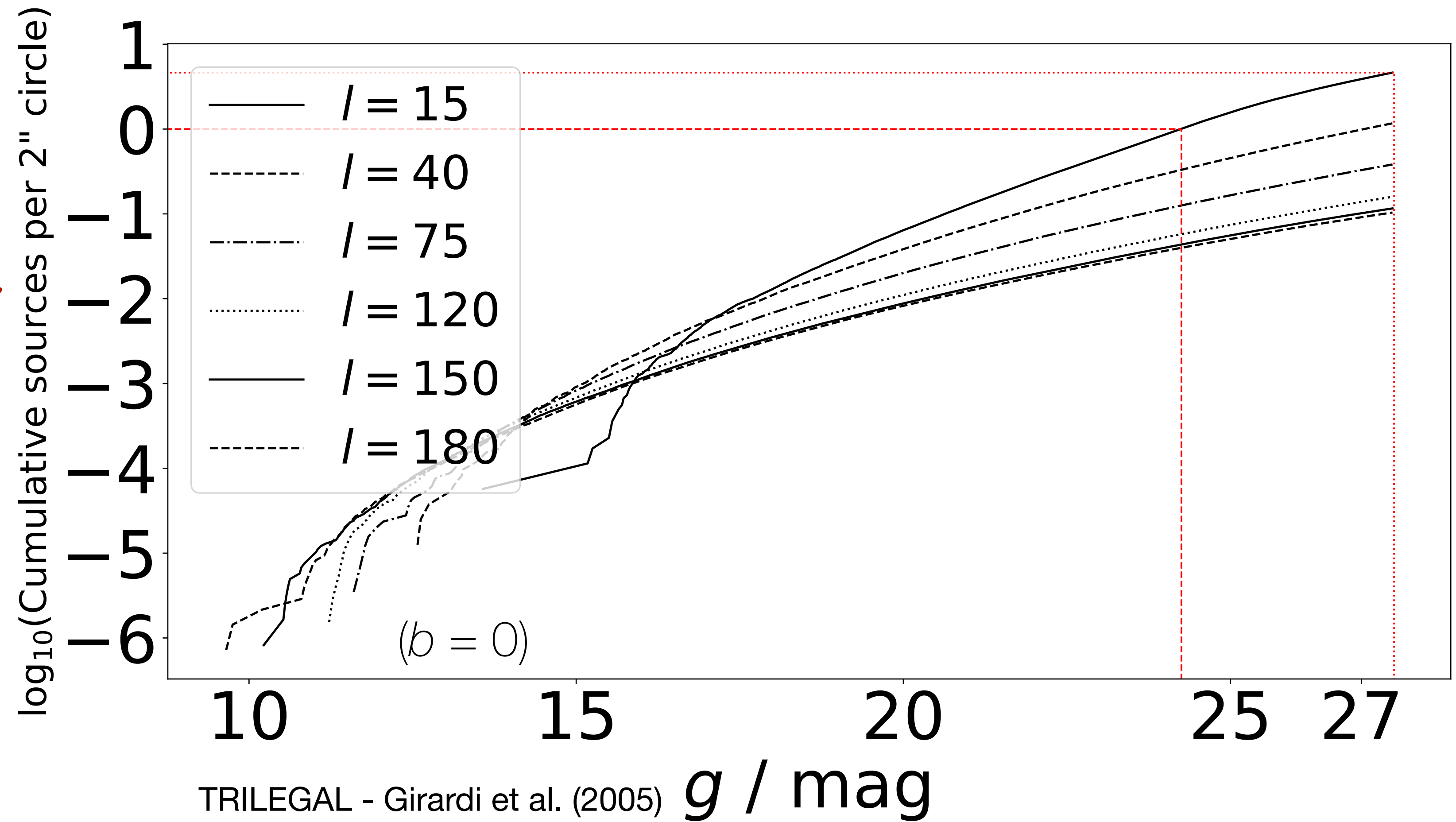
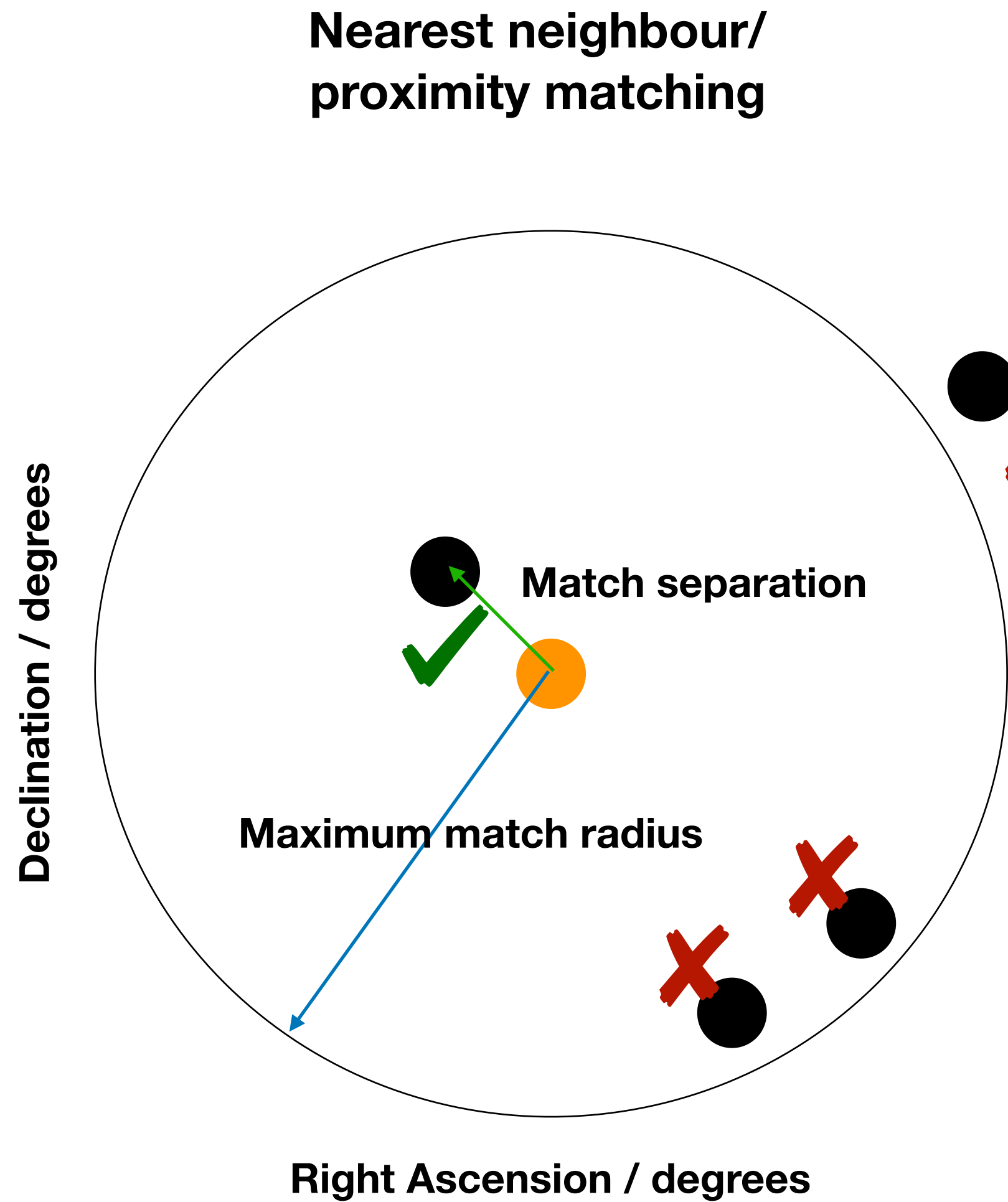
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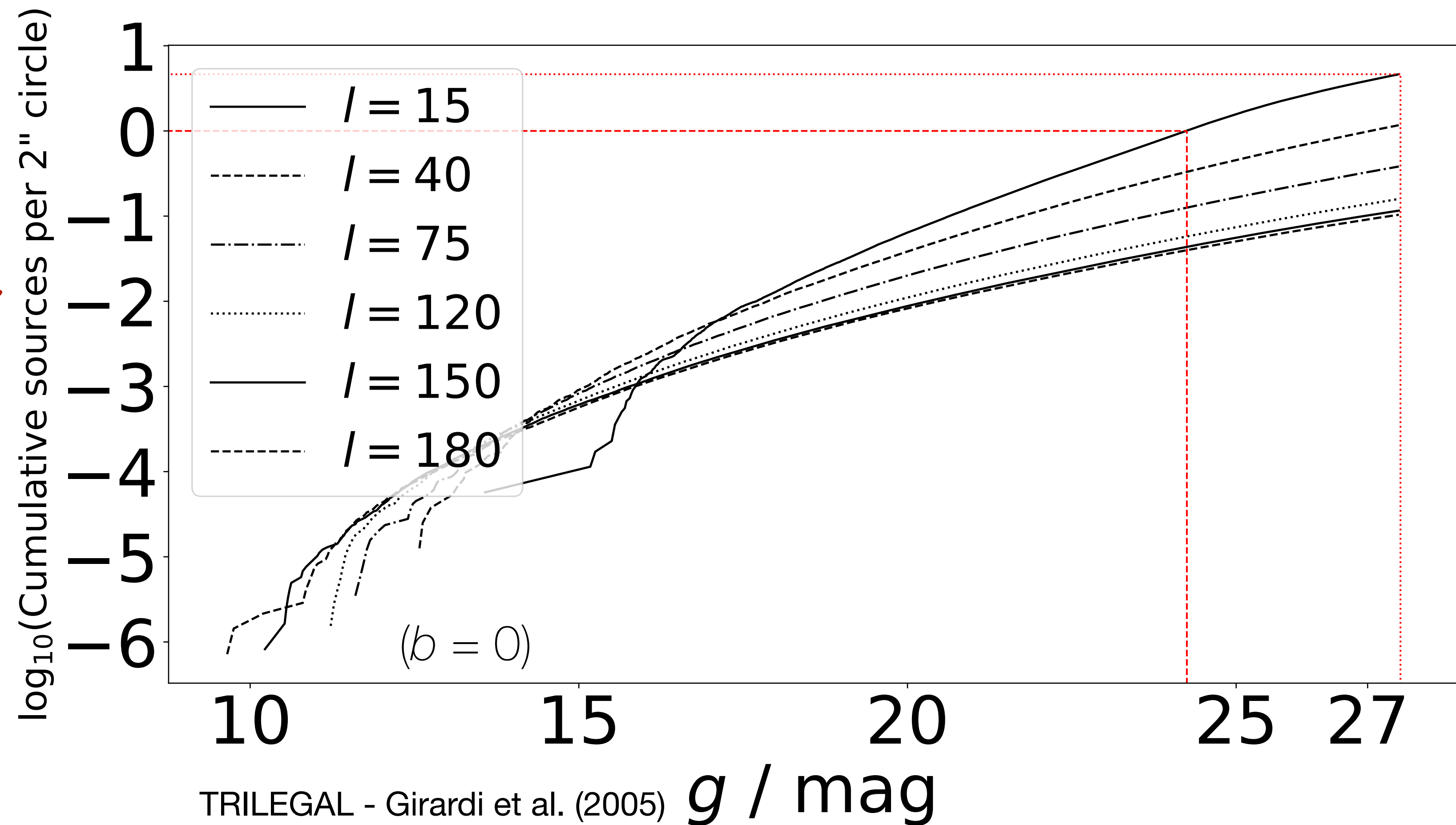
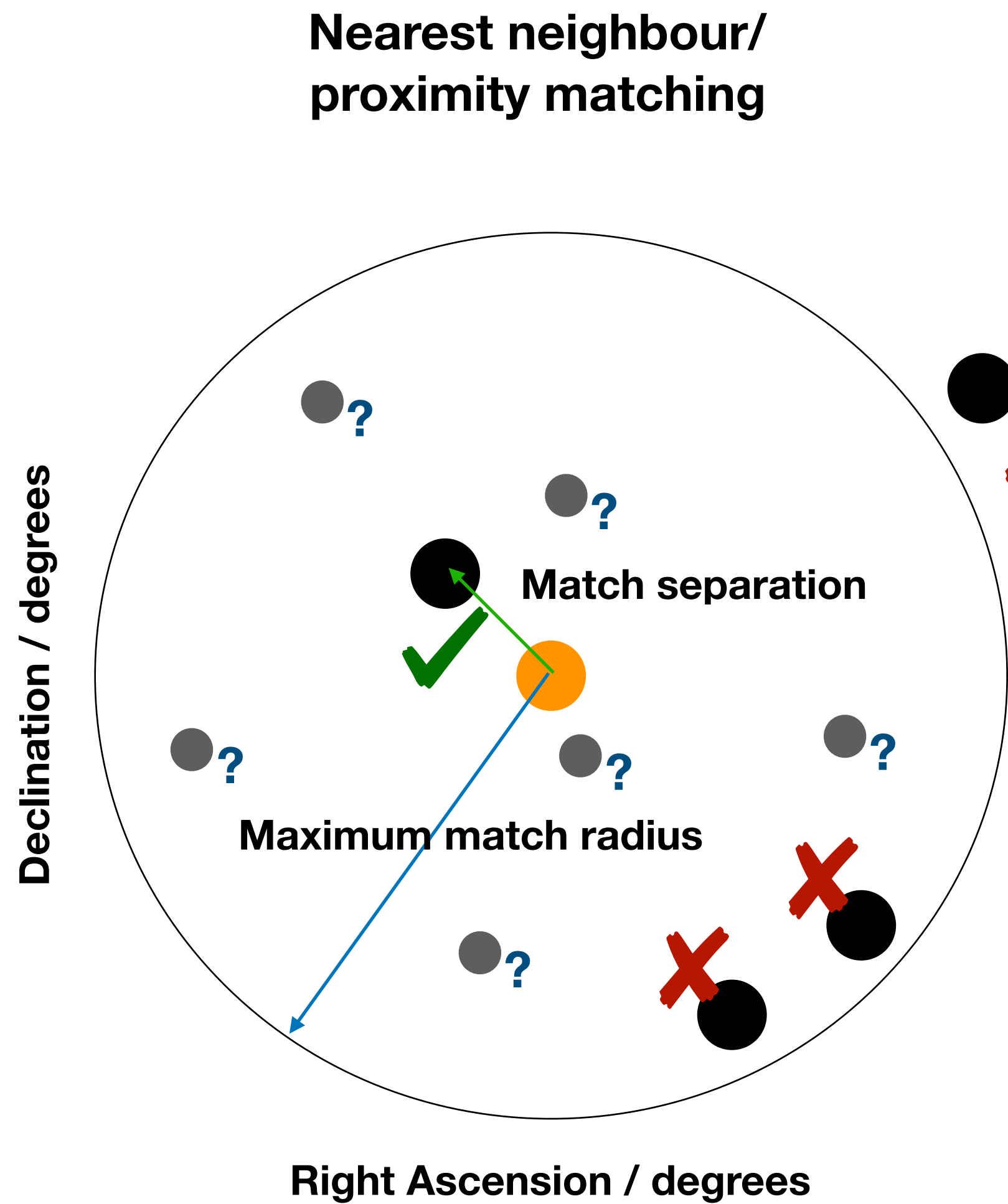
“Simple” Cross-Matching



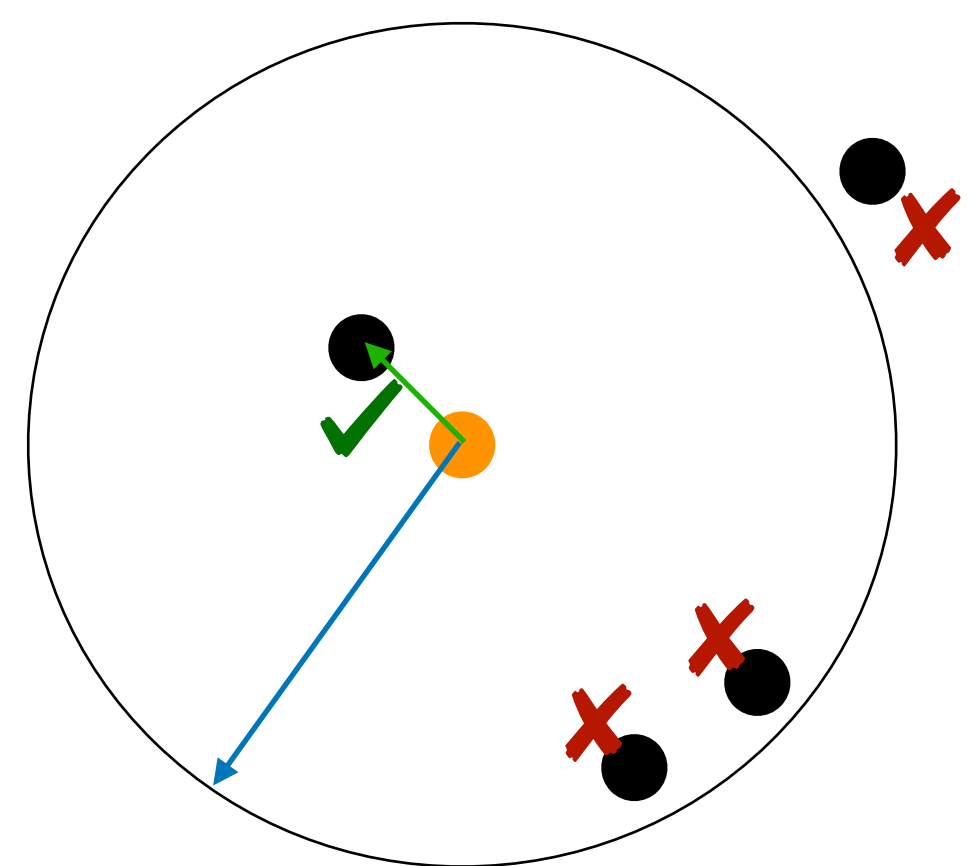
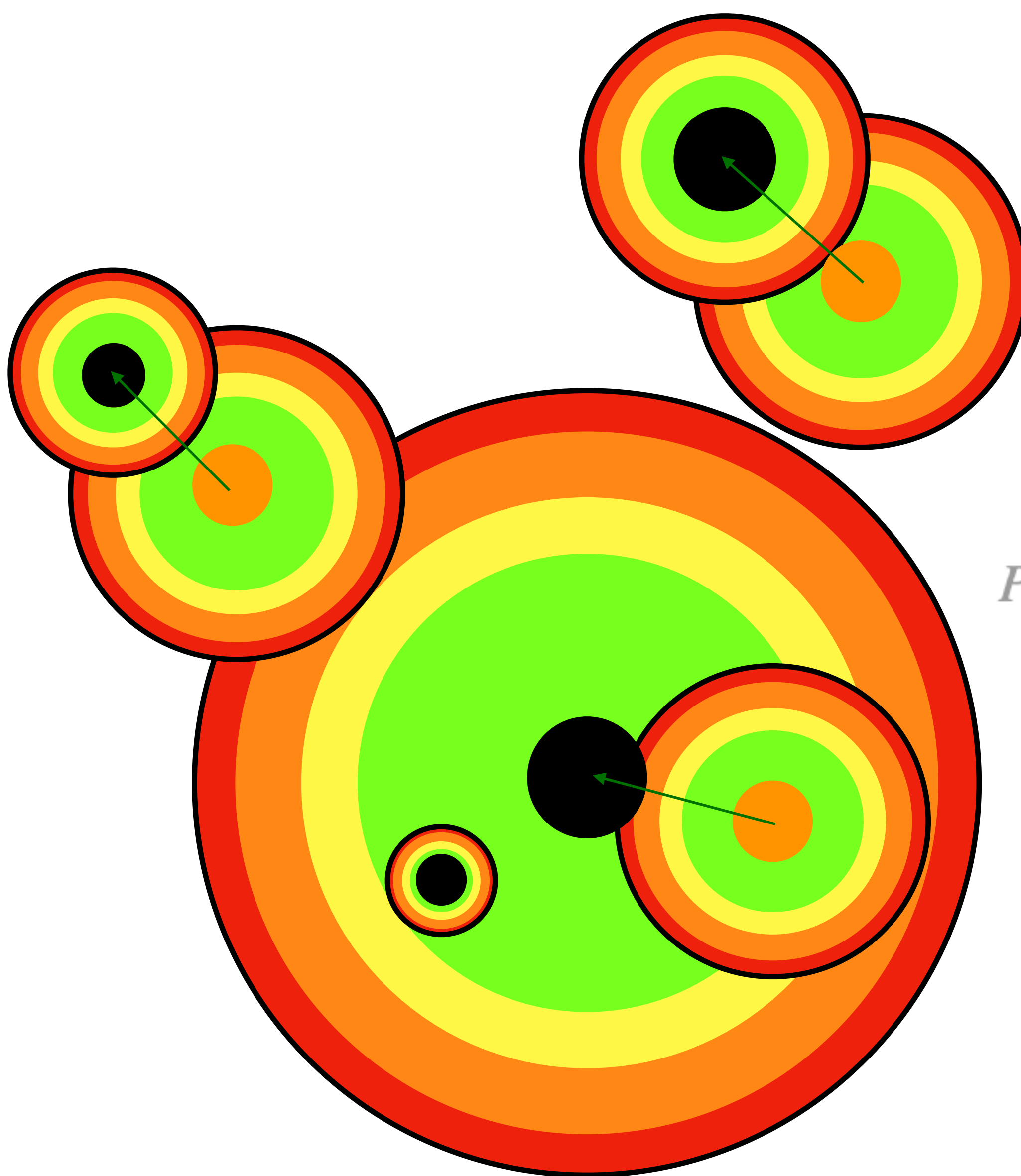
The Problem With Rubin Obs.'s LSST



The Problem With Rubin Obs.'s LSST



Probabilistic Cross-Matching



Probability of two sources having their on-sky separation given the hypothesis they are counterparts

$$P(\zeta, \lambda, k | \gamma, \phi) = \frac{1}{K} \times \prod_{\delta \notin \zeta \cap \delta \in \gamma} N_\gamma f_\gamma^\delta \prod_{\omega \notin \lambda \cap \omega \in \phi} N_\phi f_\phi^\omega \prod_{i=1}^k N_c G_{\gamma\phi}^{\zeta_i \lambda_i} c_{\gamma\phi}^{\zeta_i \lambda_i}$$

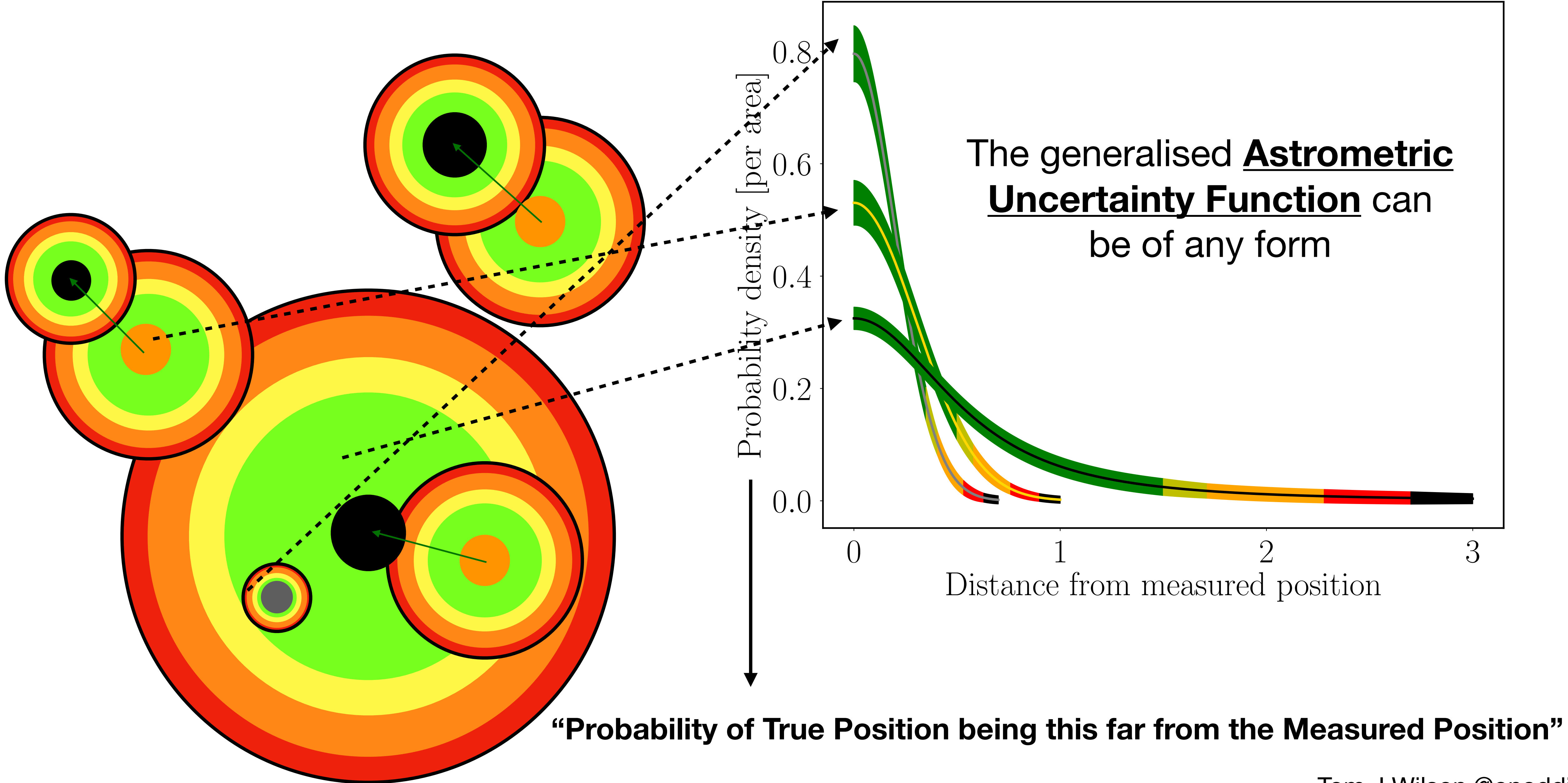
Wilson & Naylor (2018a)

Probability of sources having their brightnesses given they are unrelated to one another (“field stars”)

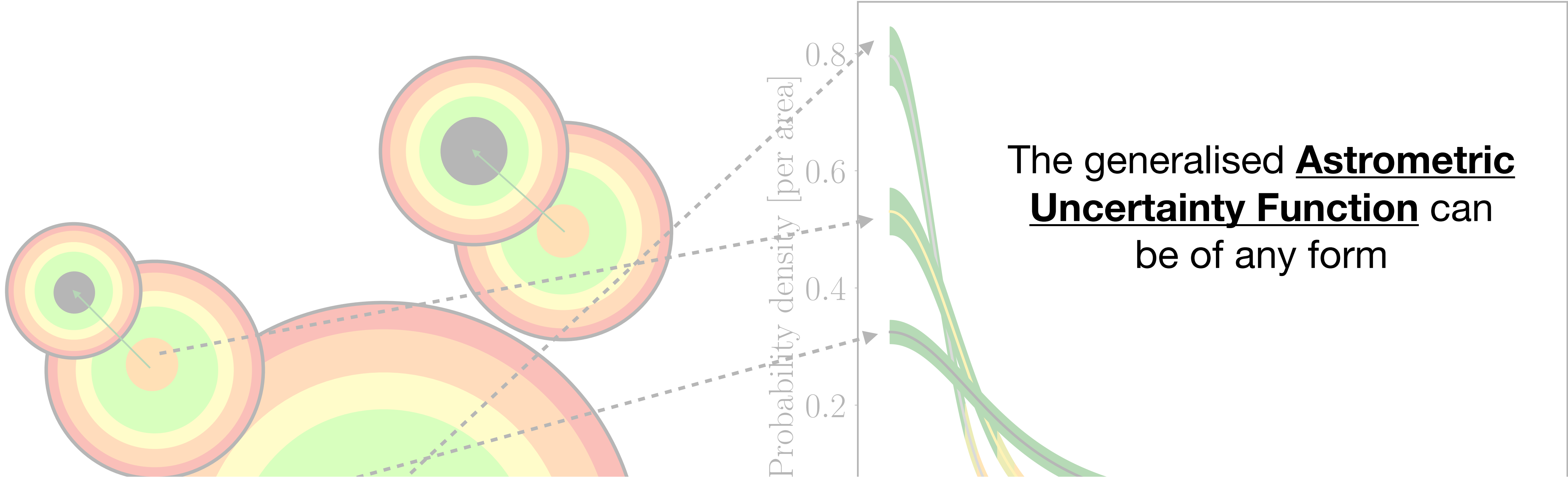
Probability of sources having their brightnesses given they are counterparts

(Although for transient matching, by definition, we probably want to skip this part of the equation, given that the colours won't make sense anymore!)

Probabilistic Cross-Matching: the AUF



Probabilistic Cross-Matching: the AUF



One assumption made in basically all literature: positional errors of sources are Gaussian!

$$dp(r|id) = r \times e^{-r^2/2} dr.$$

de Ruiter, Willis, & Arp (1977)

$$P(i) = \frac{Xc(m_i) g(\Delta x_i, \Delta y_i)}{Nf(m_i) + \sum_j \frac{Xc(m_j) g(\Delta x_j, \Delta y_j)}{Nf(m_j)}}$$

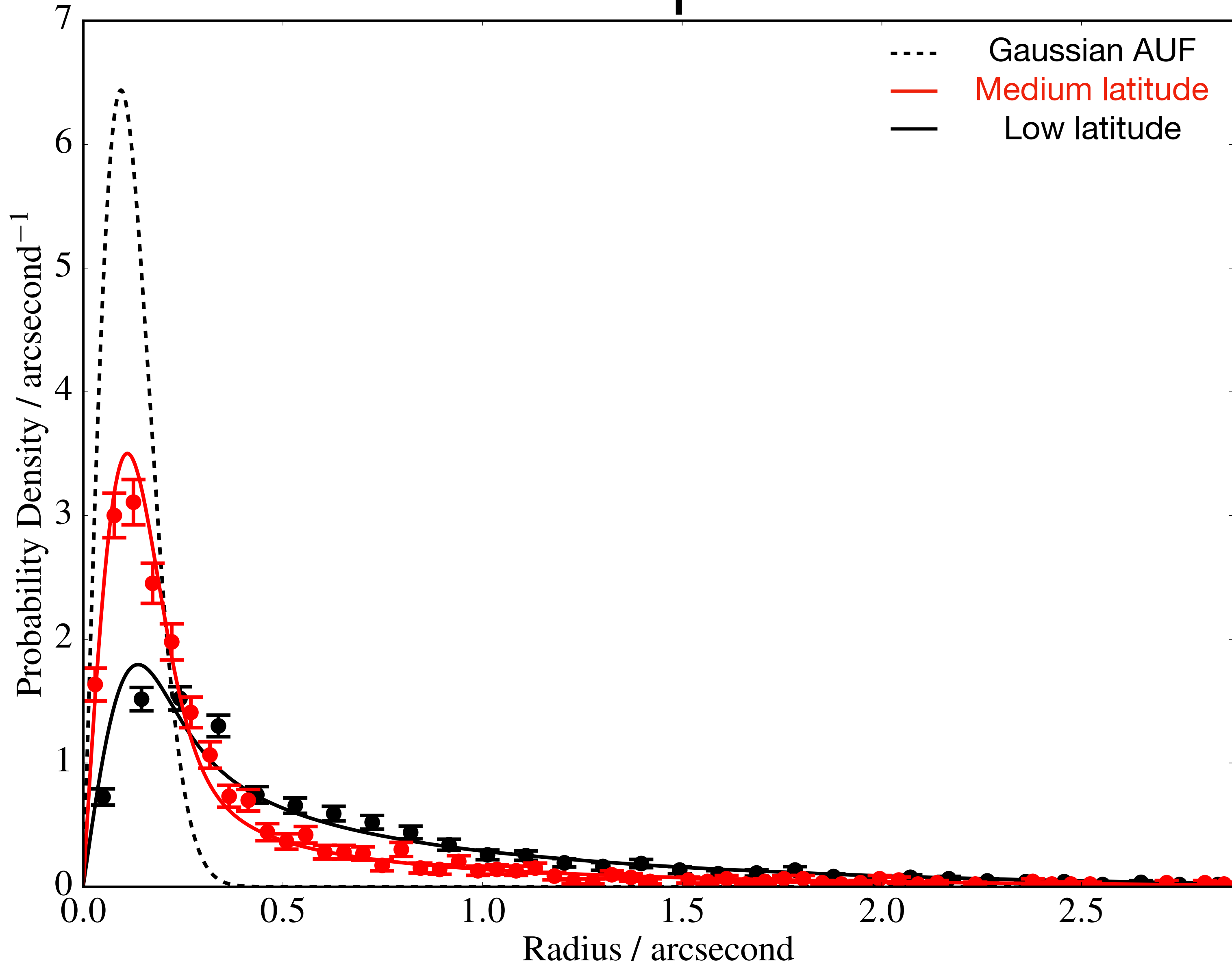
Naylor, Broos, & Feigelson (2013)

$$p(D|H) = \int p(m|H) \prod_{i=1}^n p_i(x_i|m, H) d^3m$$

Budavári & Szalay (2008)

“Probability of True Position being this far from the Measured Position”

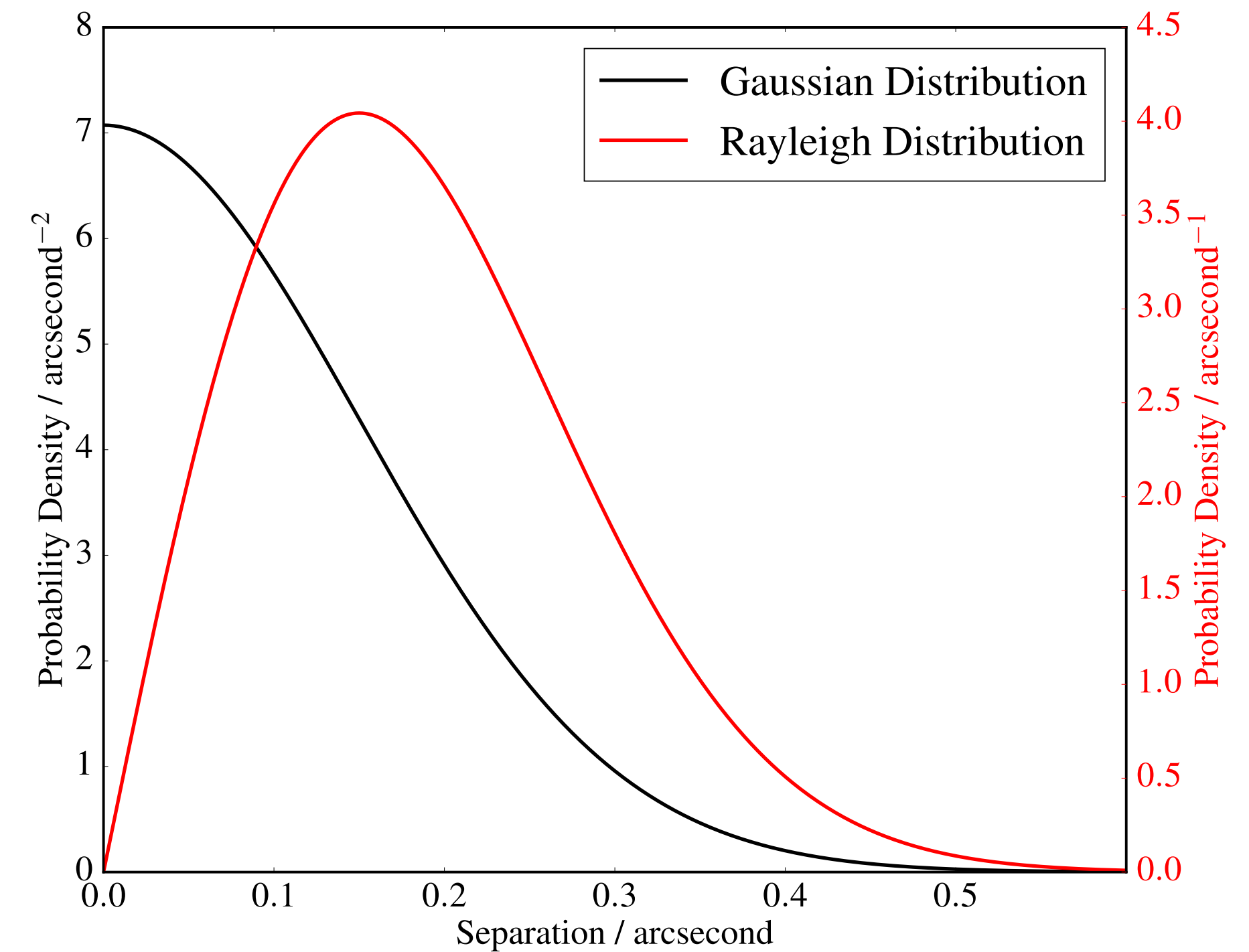
Additional Components of the AUF



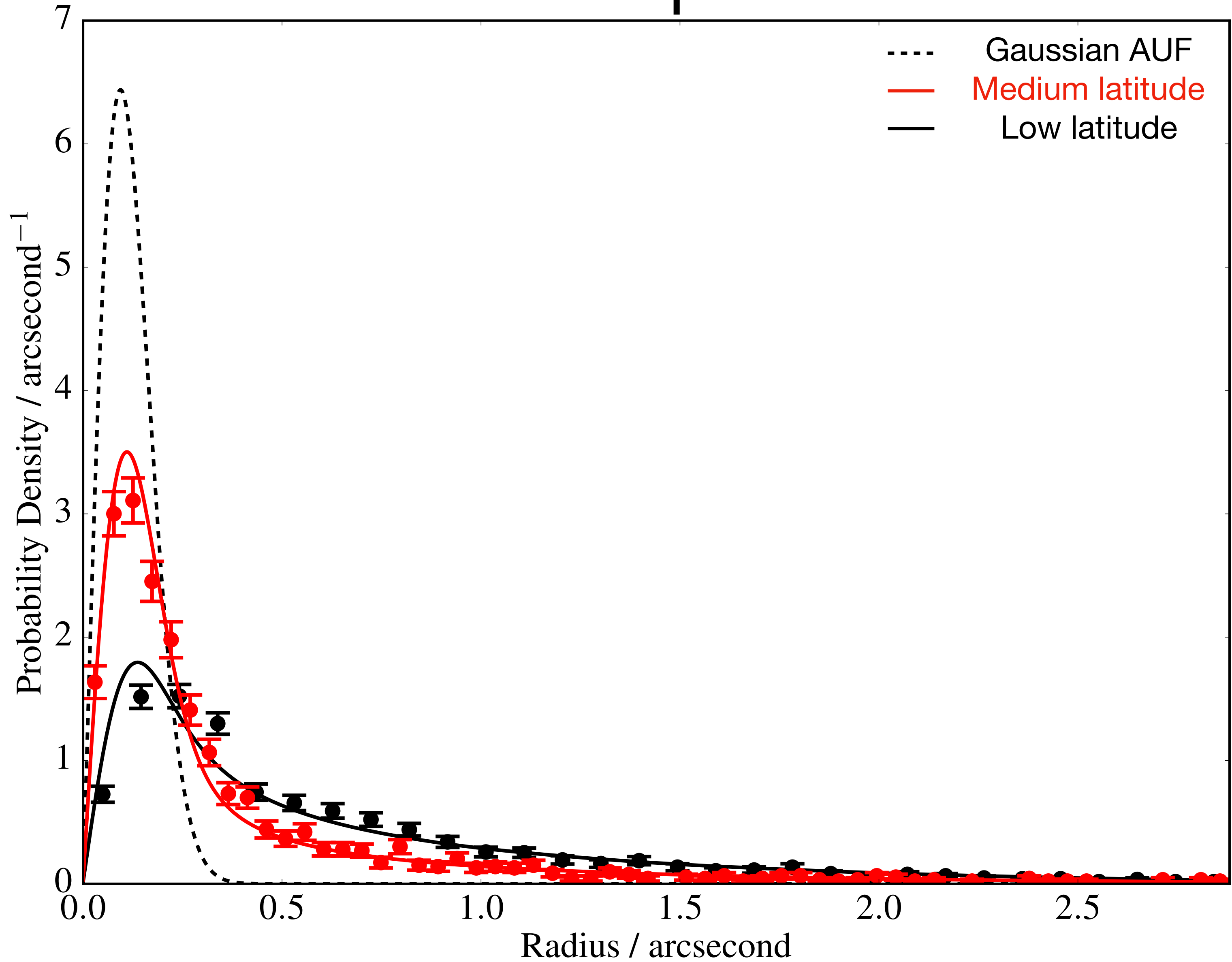
$$g(x, y, \sigma) = (2\pi\sigma^2)^{-1} \exp\left(-\frac{1}{2} \frac{x^2 + y^2}{\sigma^2}\right)$$

↓

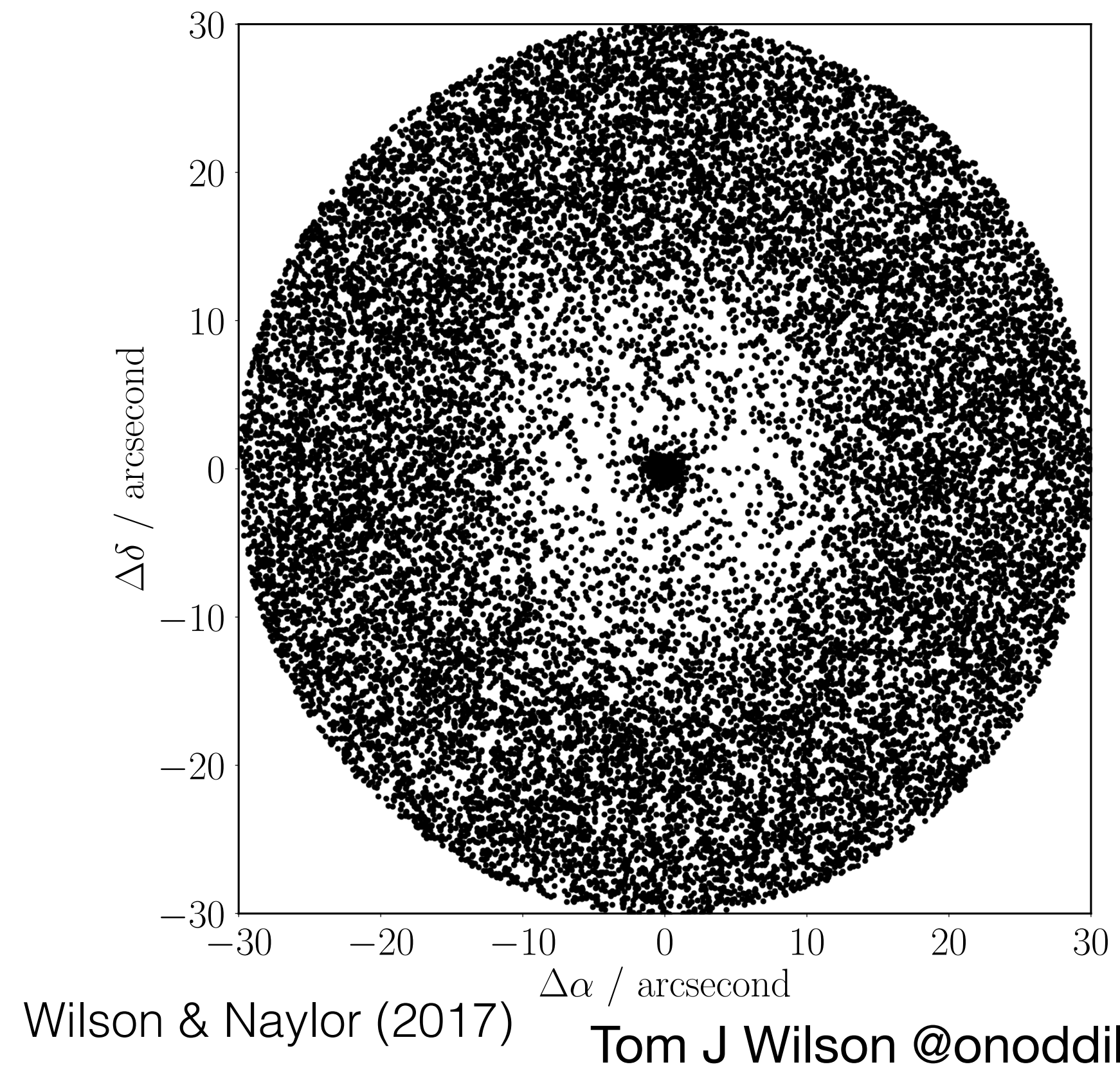
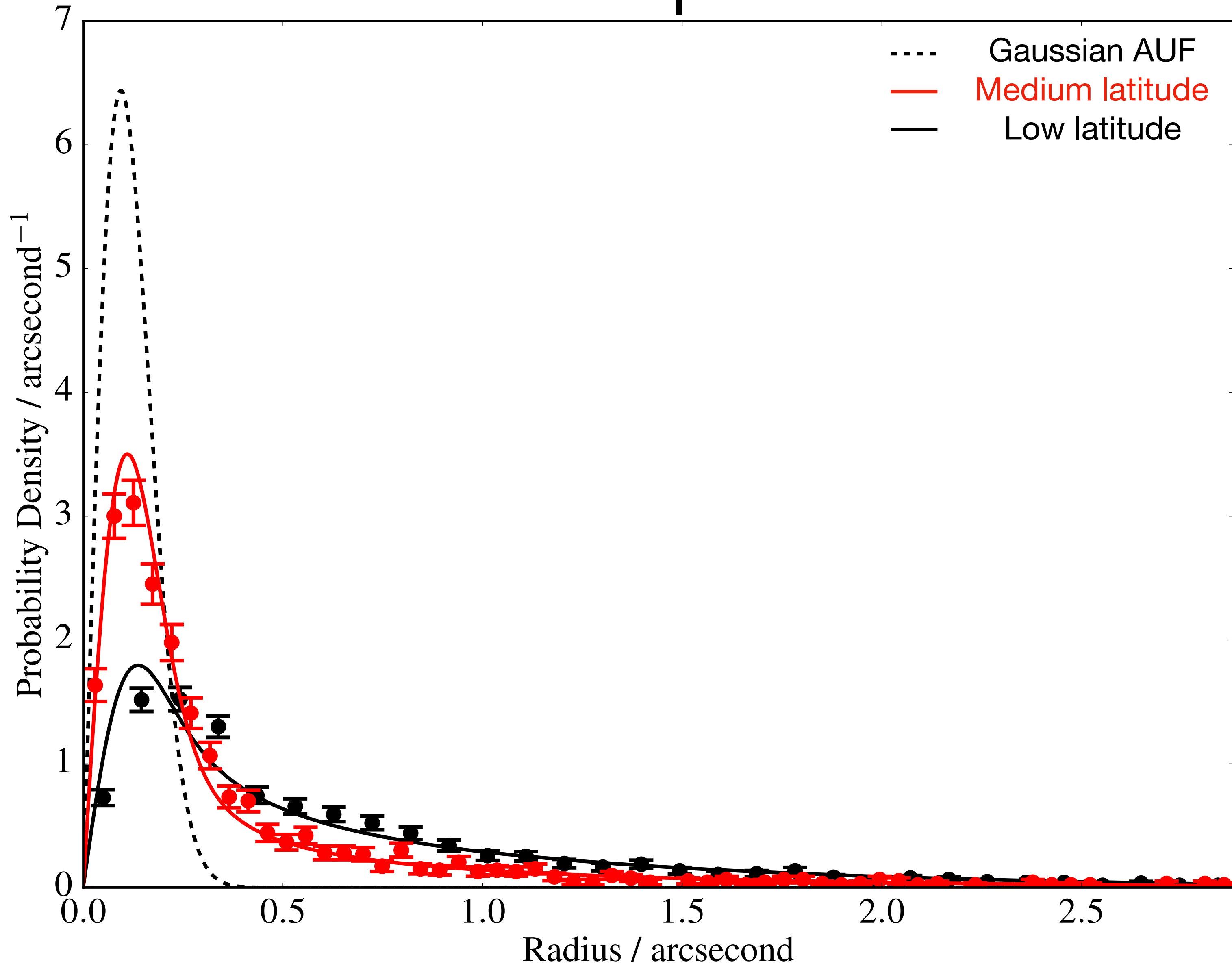
$$g(r, \sigma) = \frac{r}{\sigma^2} \exp\left(-\frac{1}{2} \frac{r^2}{\sigma^2}\right)$$



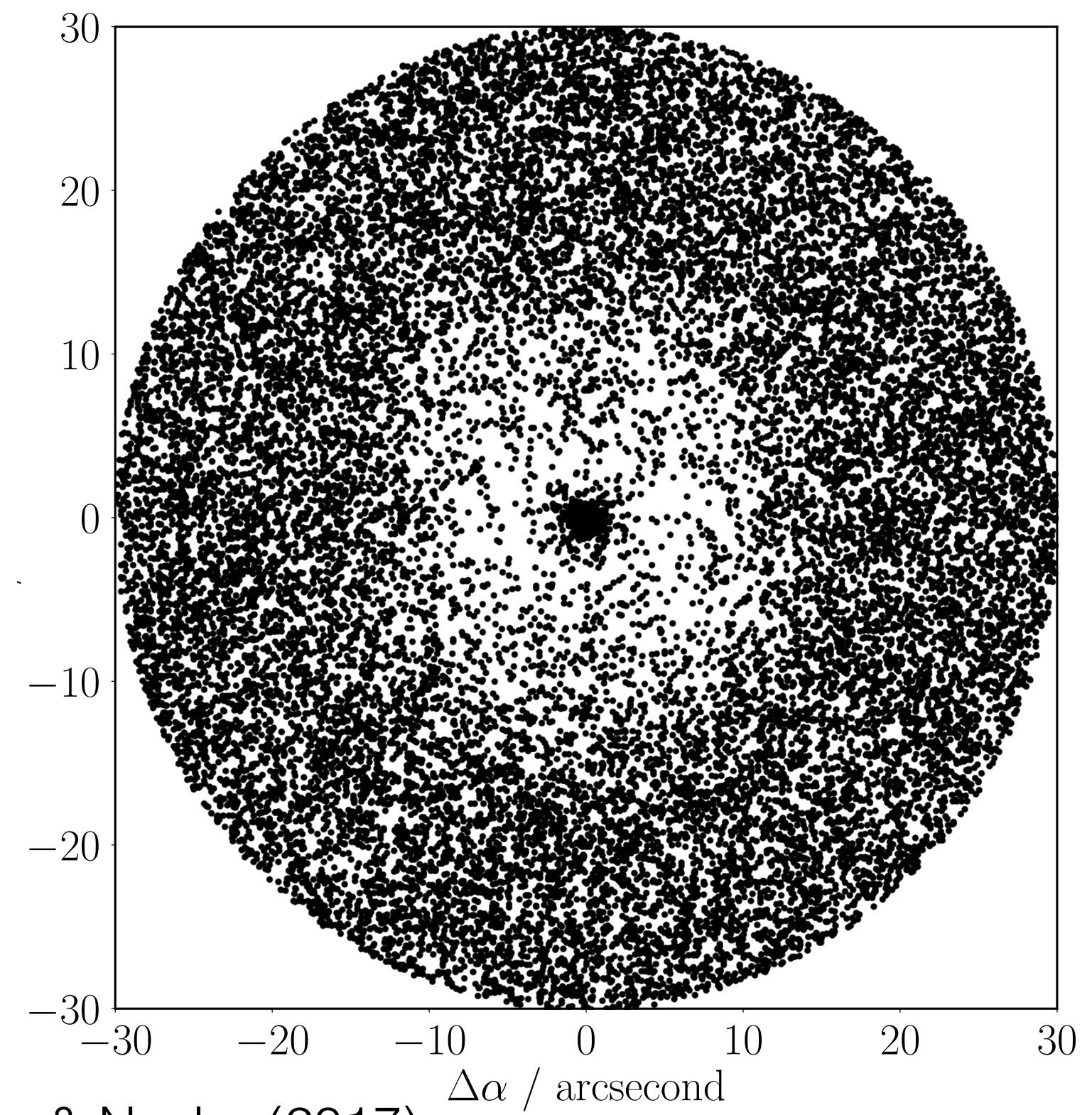
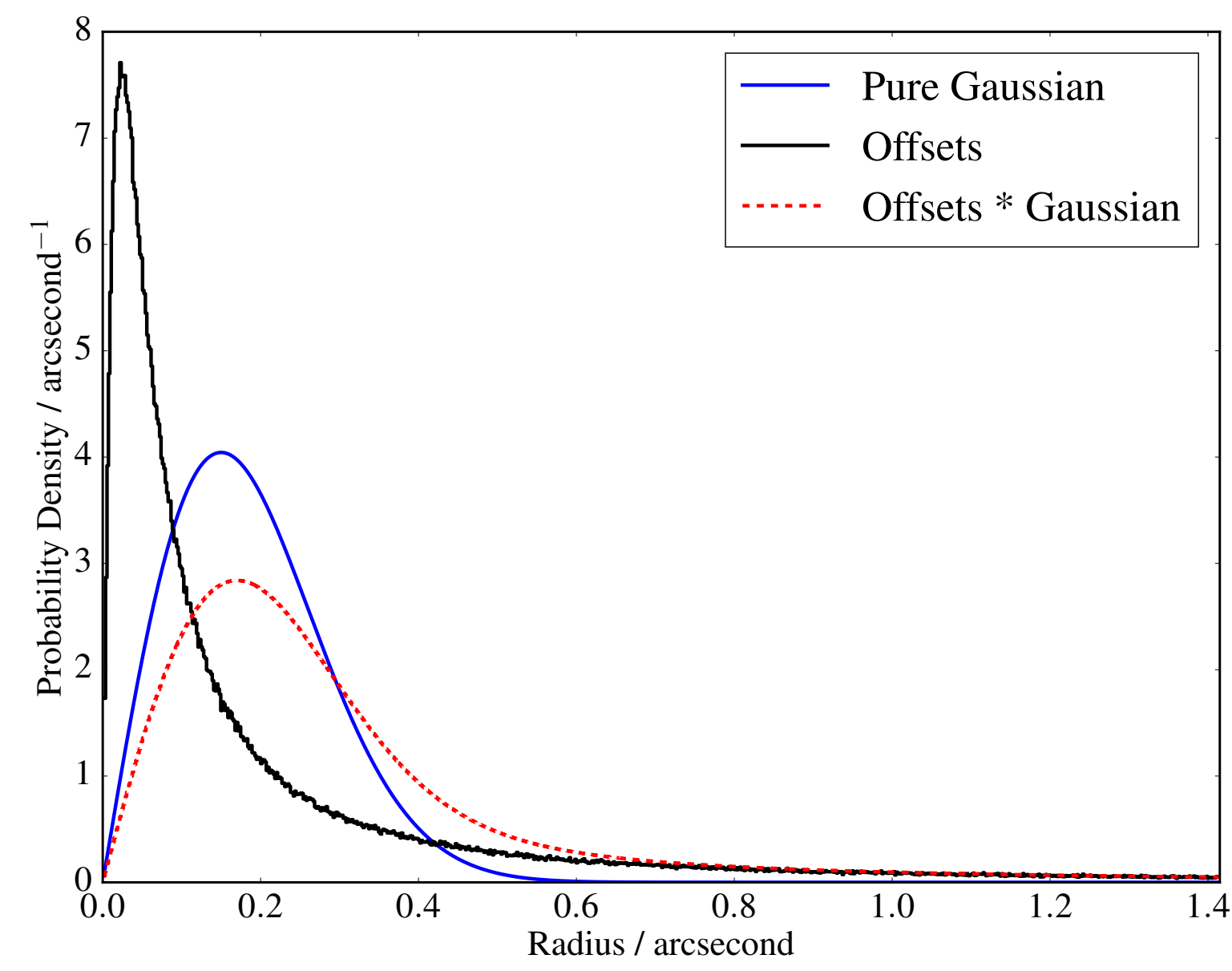
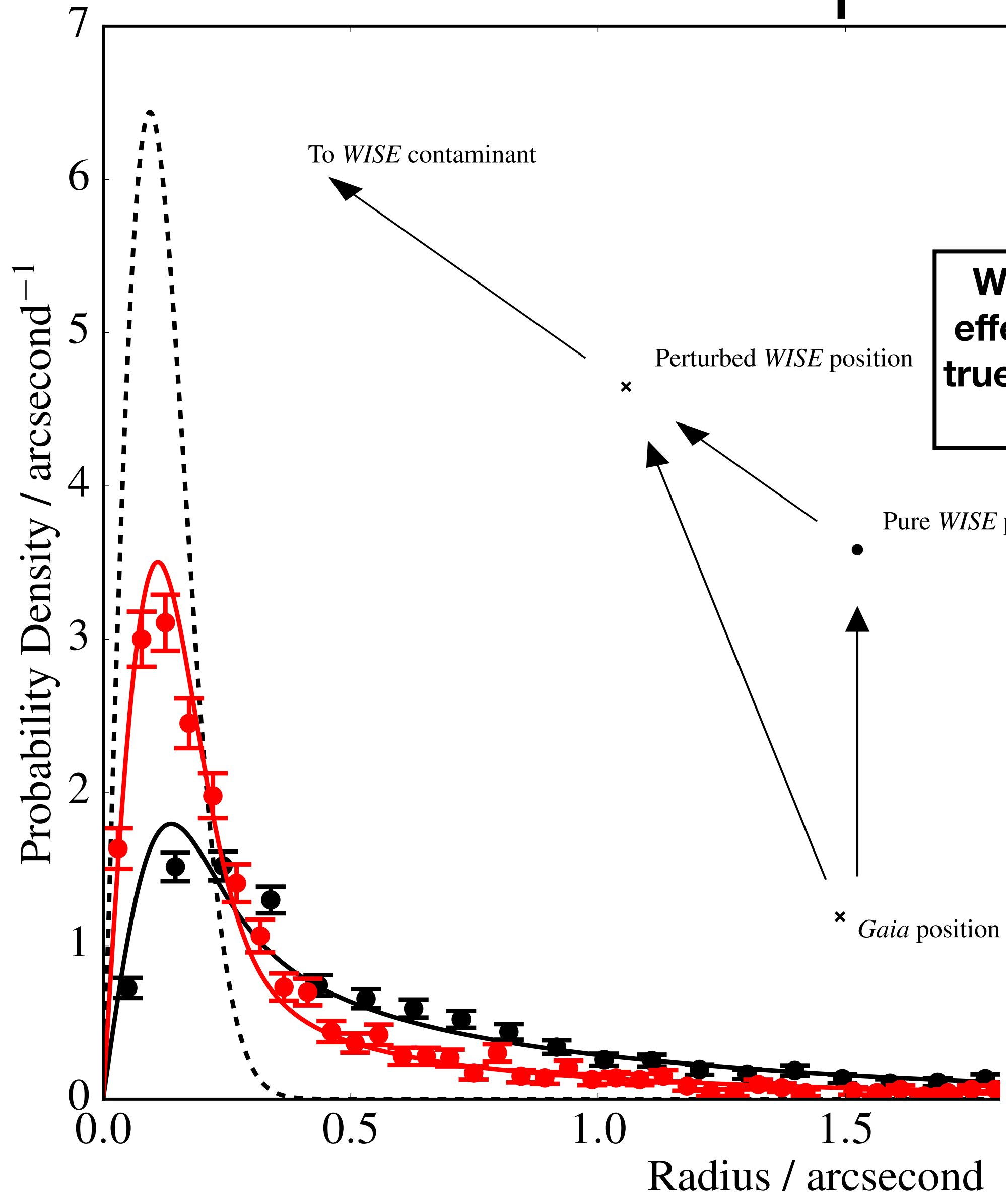
Additional Components of the AUF



Additional Components of the AUF (and any other systematic — e.g. proper motions, cf. Wilson 2023, RASTI)



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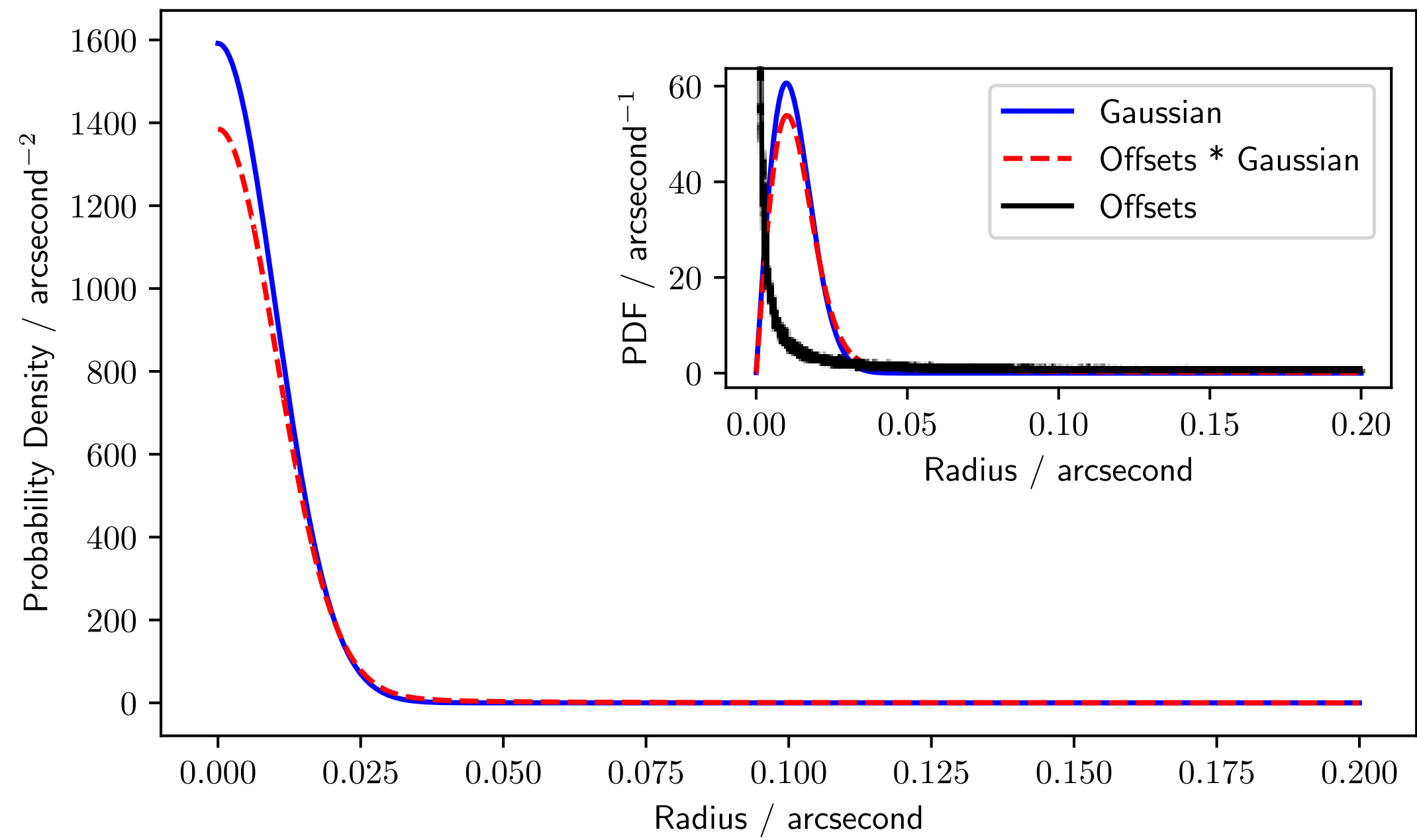
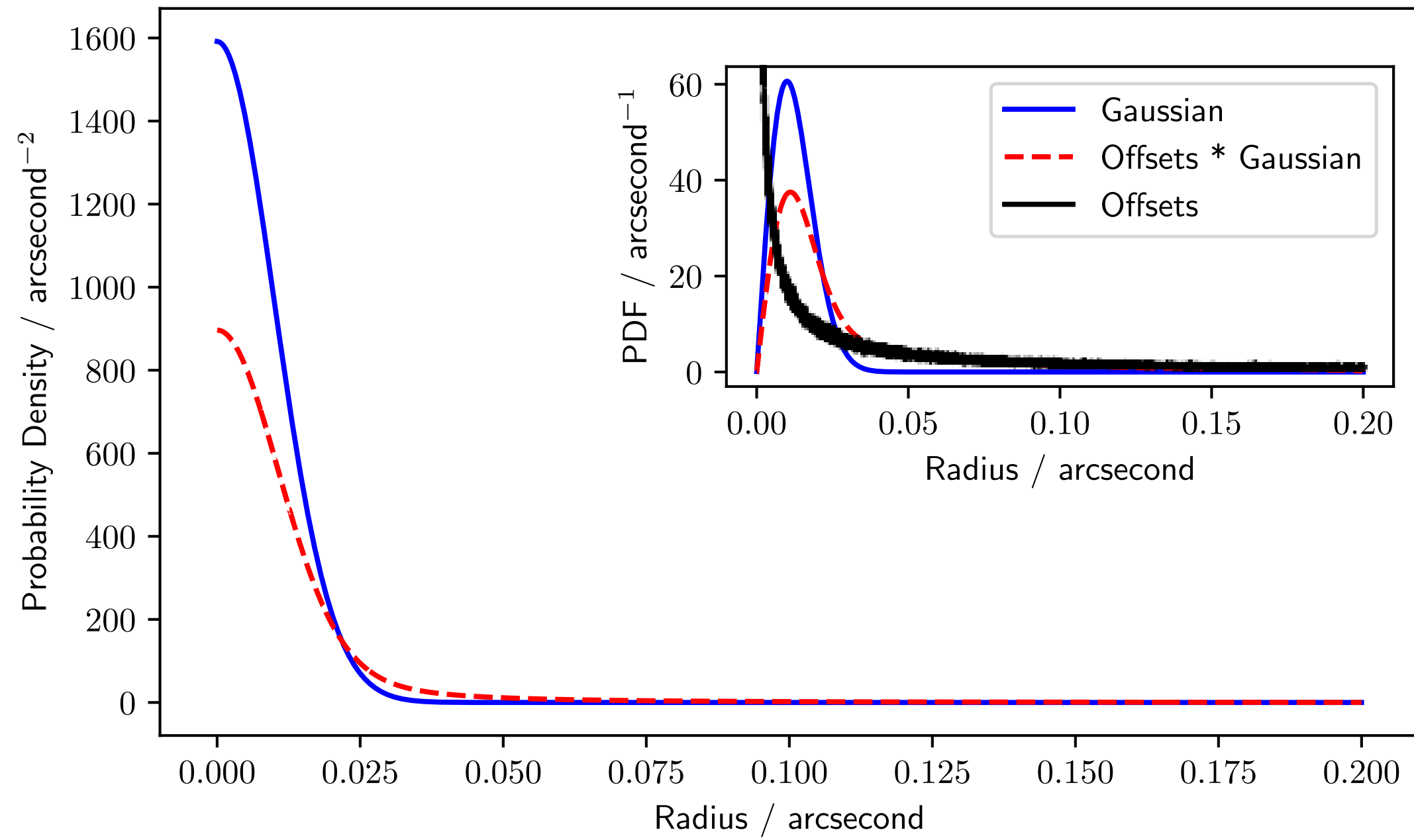
WISE - Wright et al. (2010)

Gaia DR2 - Gaia Collaboration, Brown A. G. A., et al. (2018)

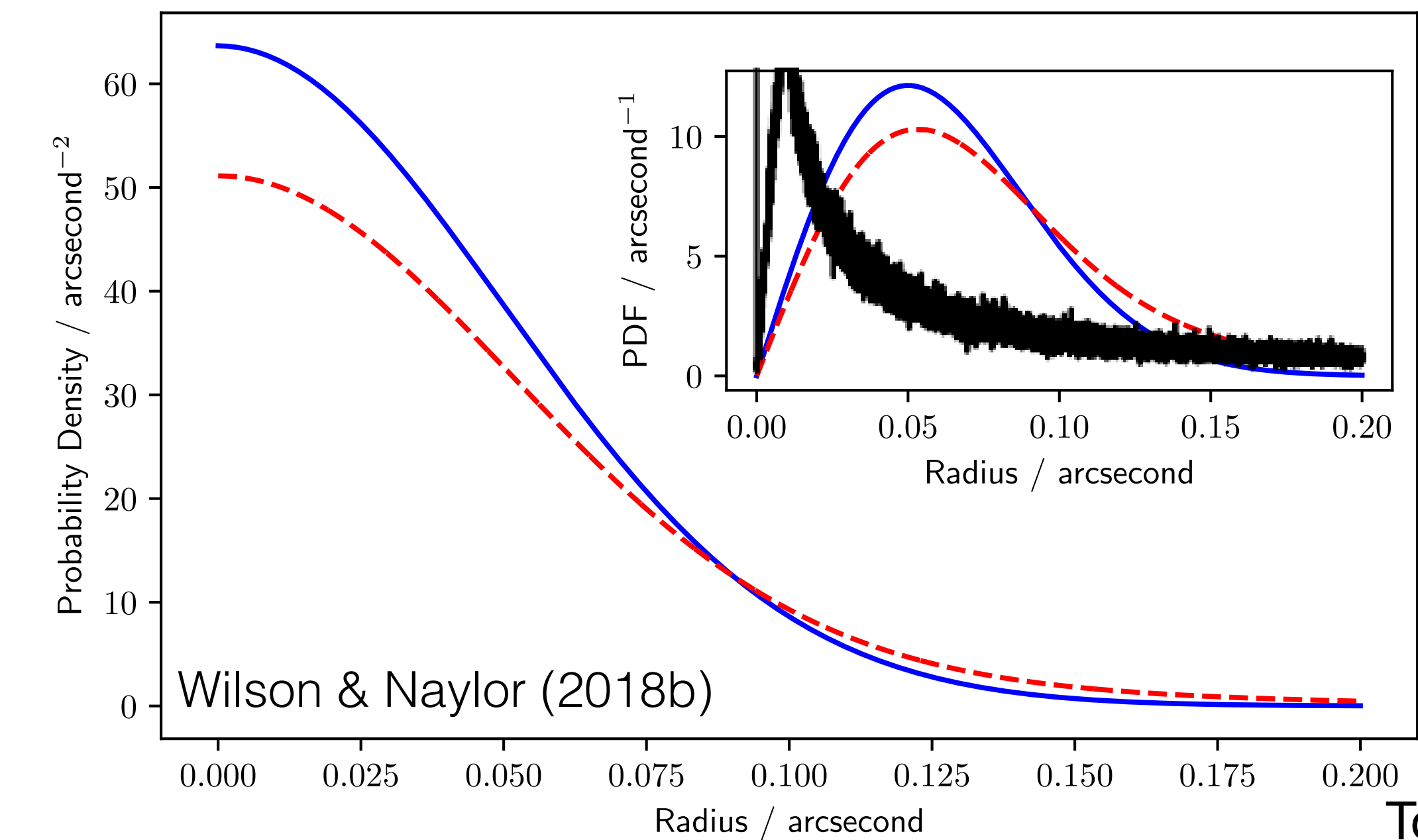
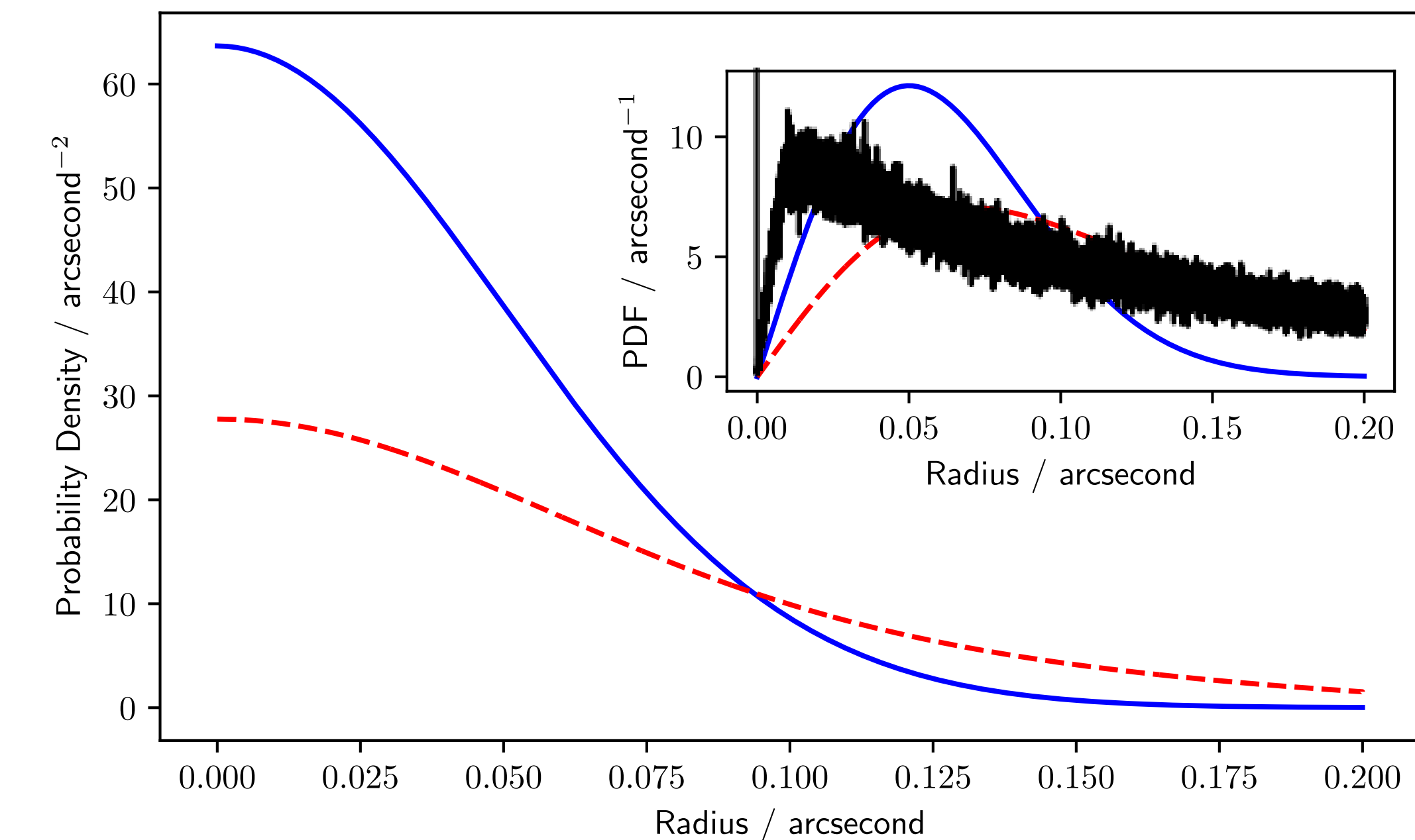
Wilson & Naylor (2018b)

Wilson & Naylor (2017)

The Rubin AUF: Galactic Plane

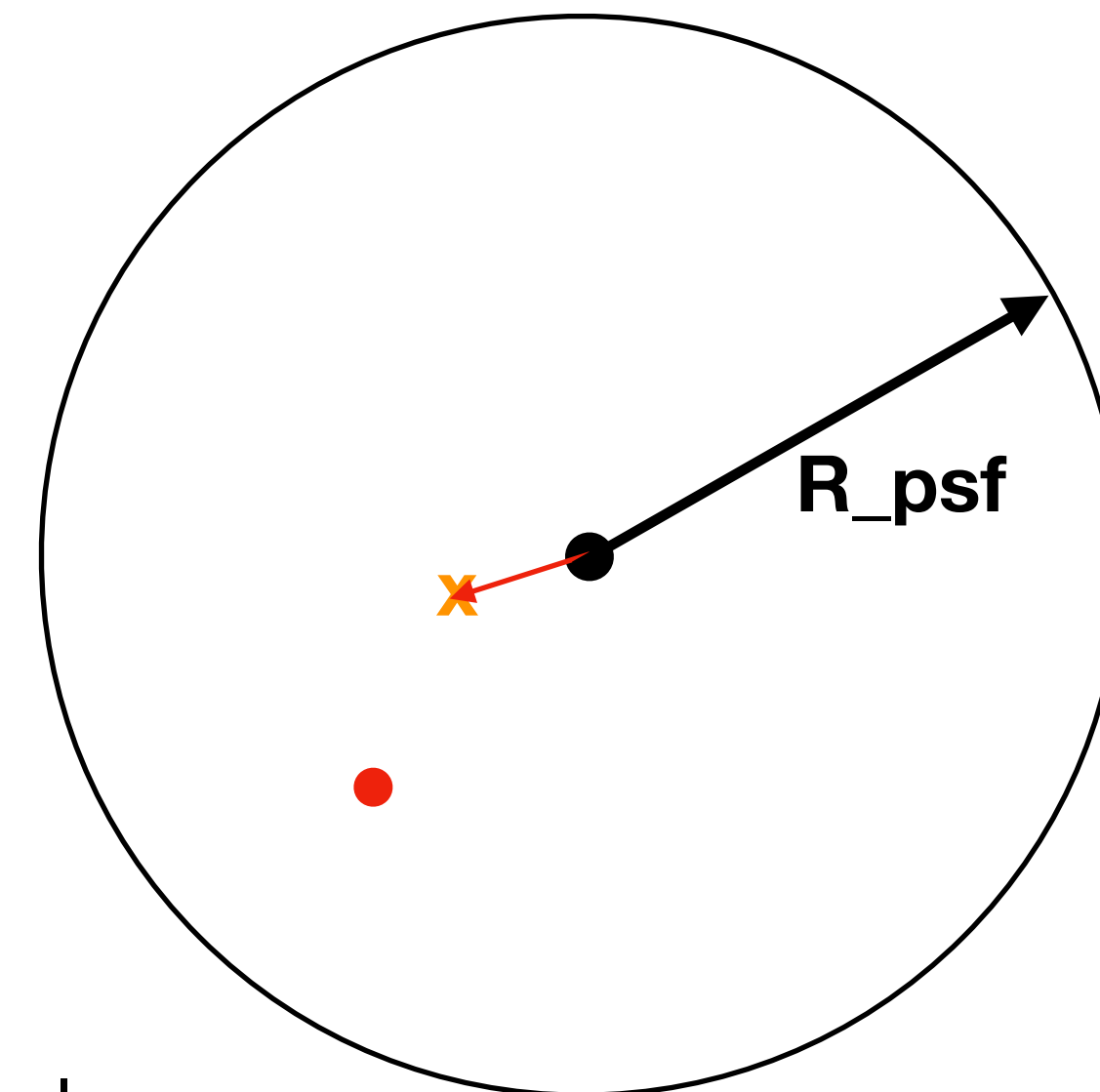
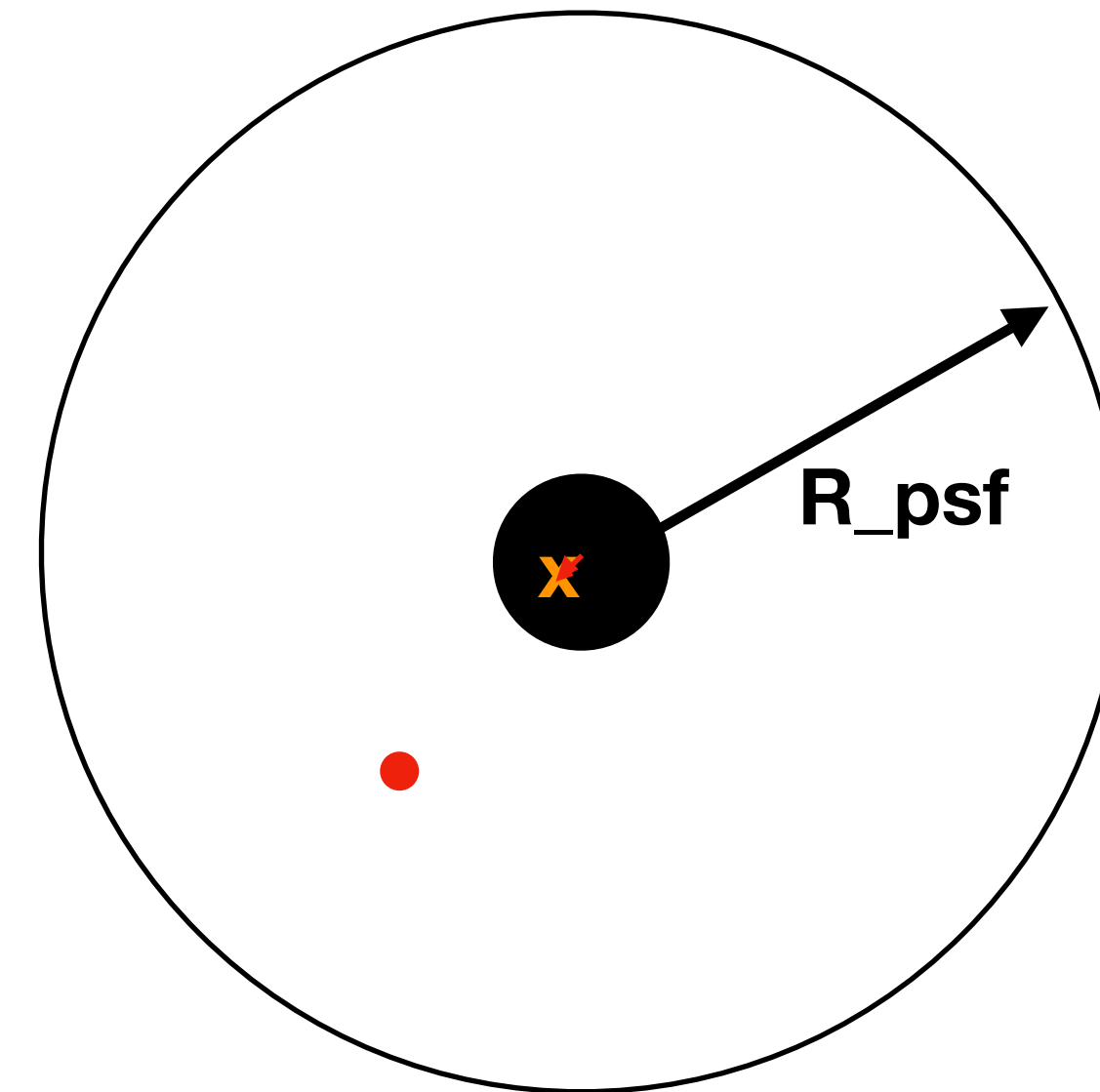
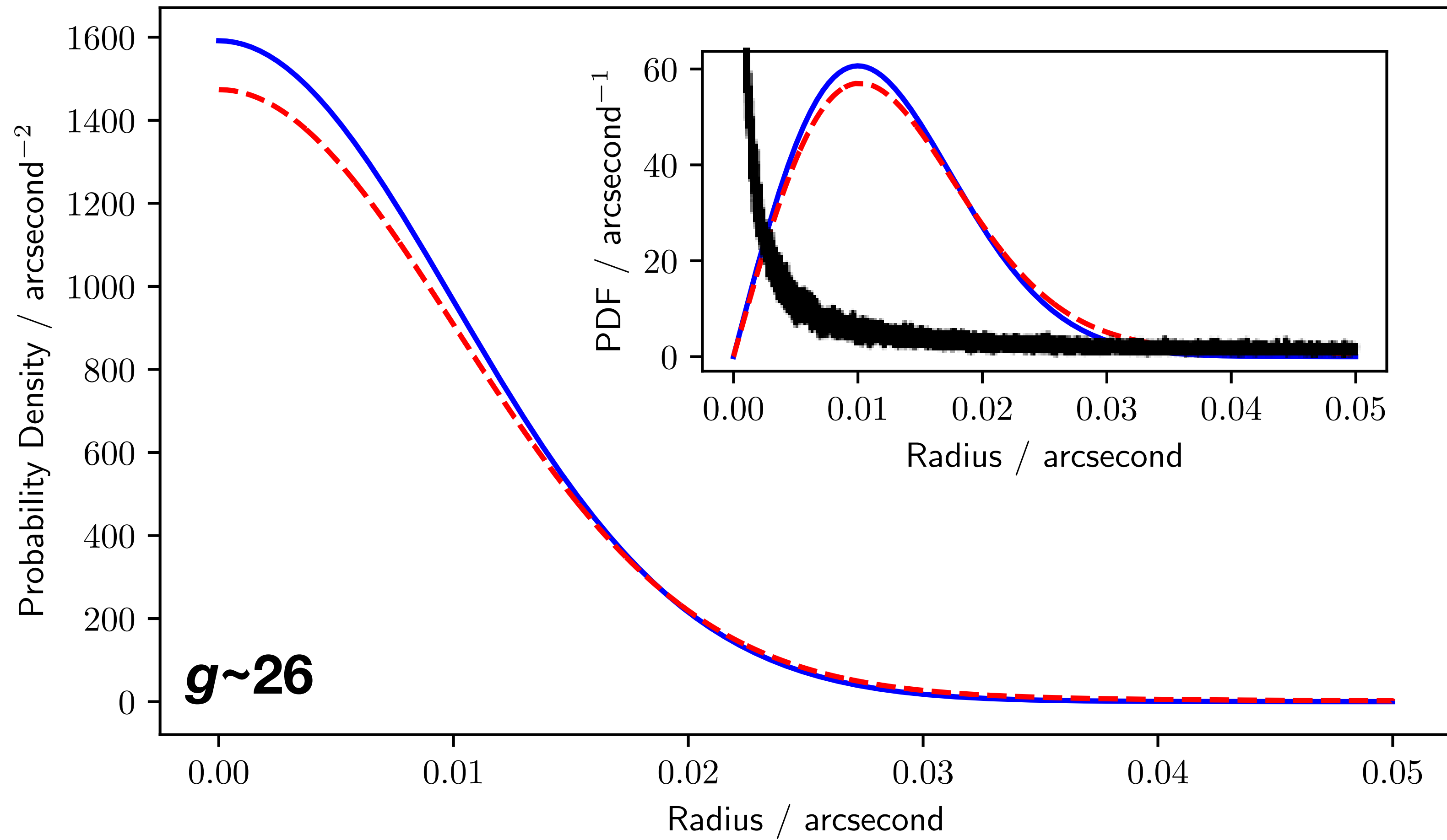


Without modelling this extra effect, we fail to recover many true pairings, with an artificially high false negative rate!



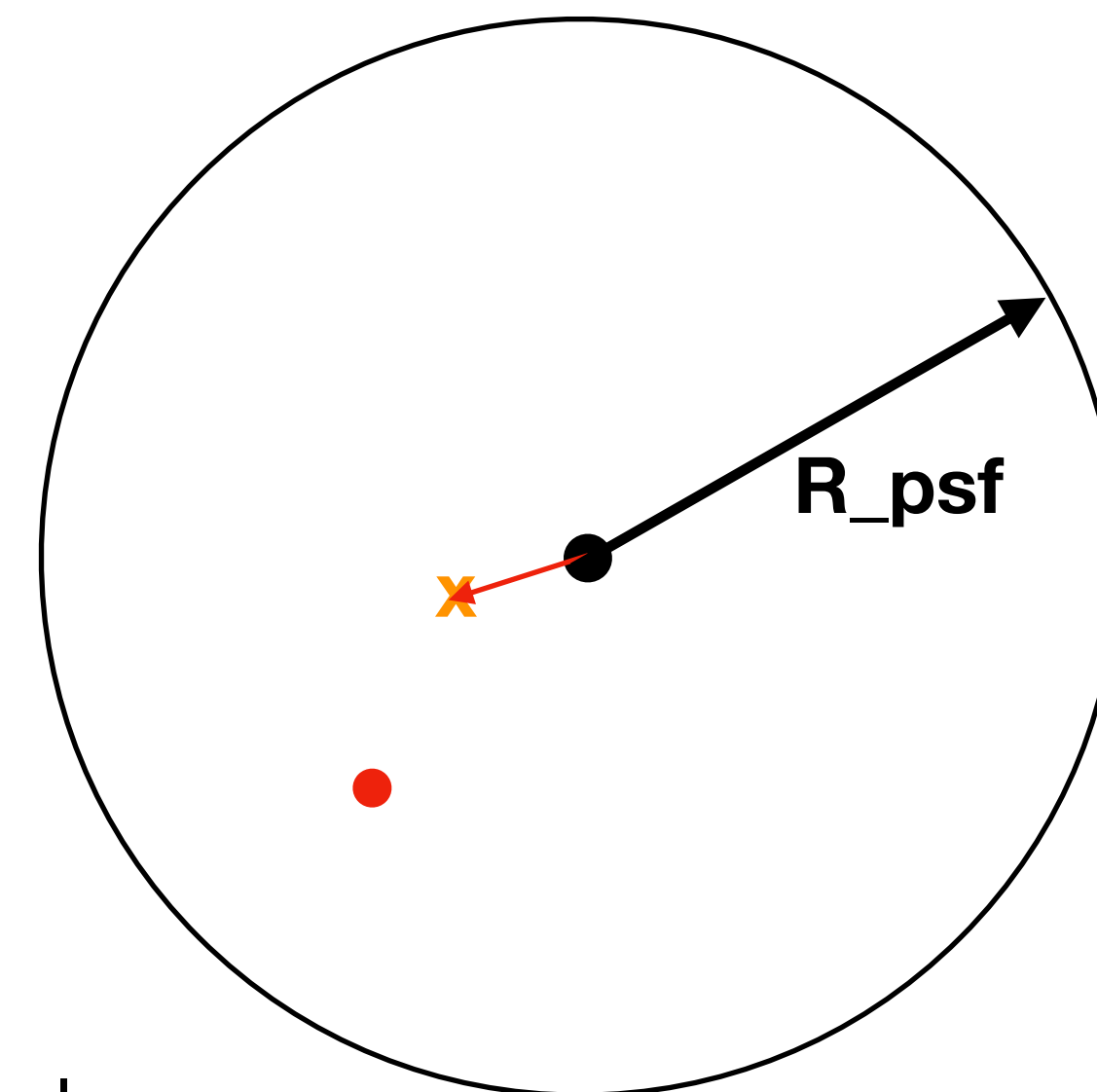
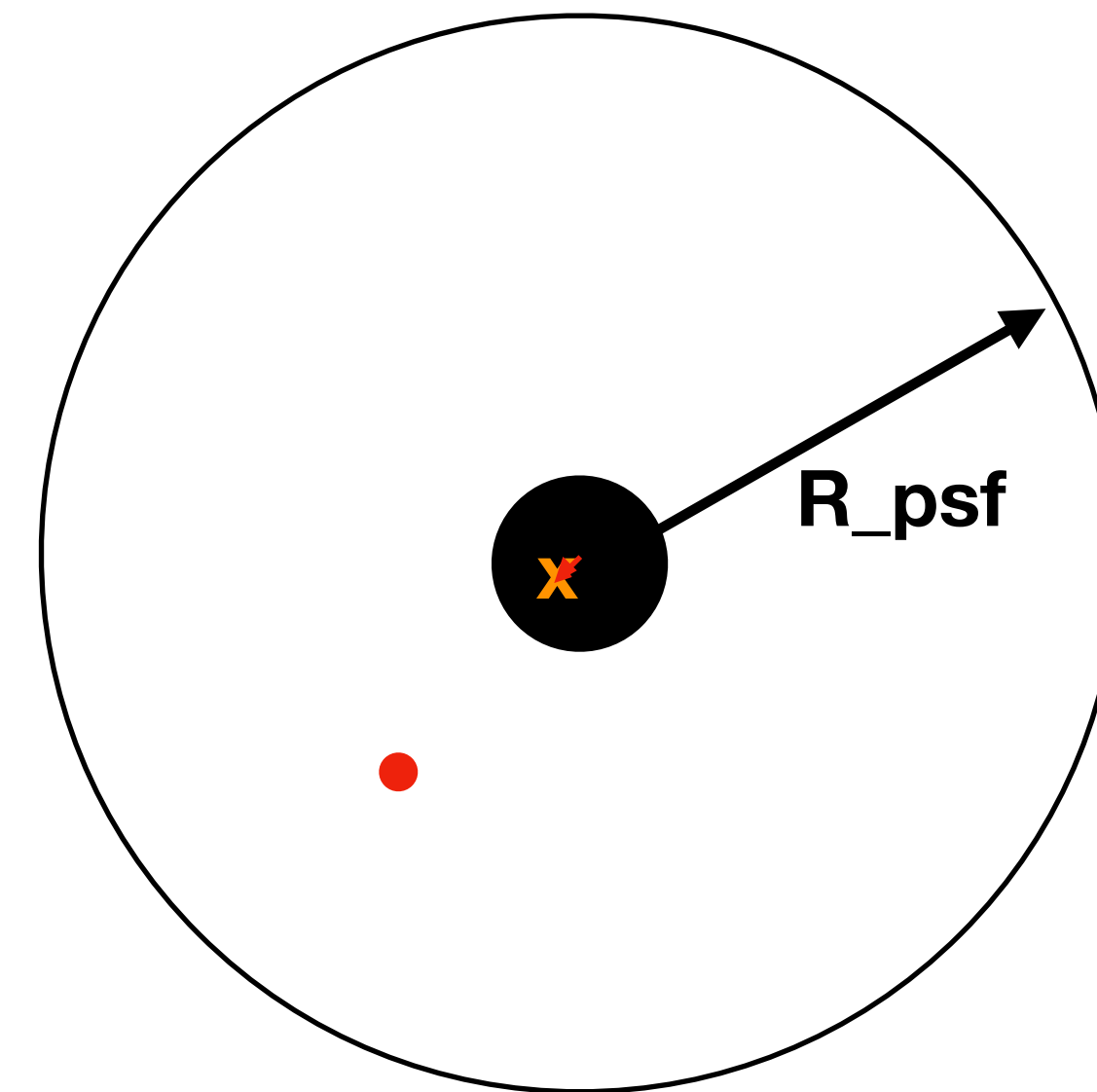
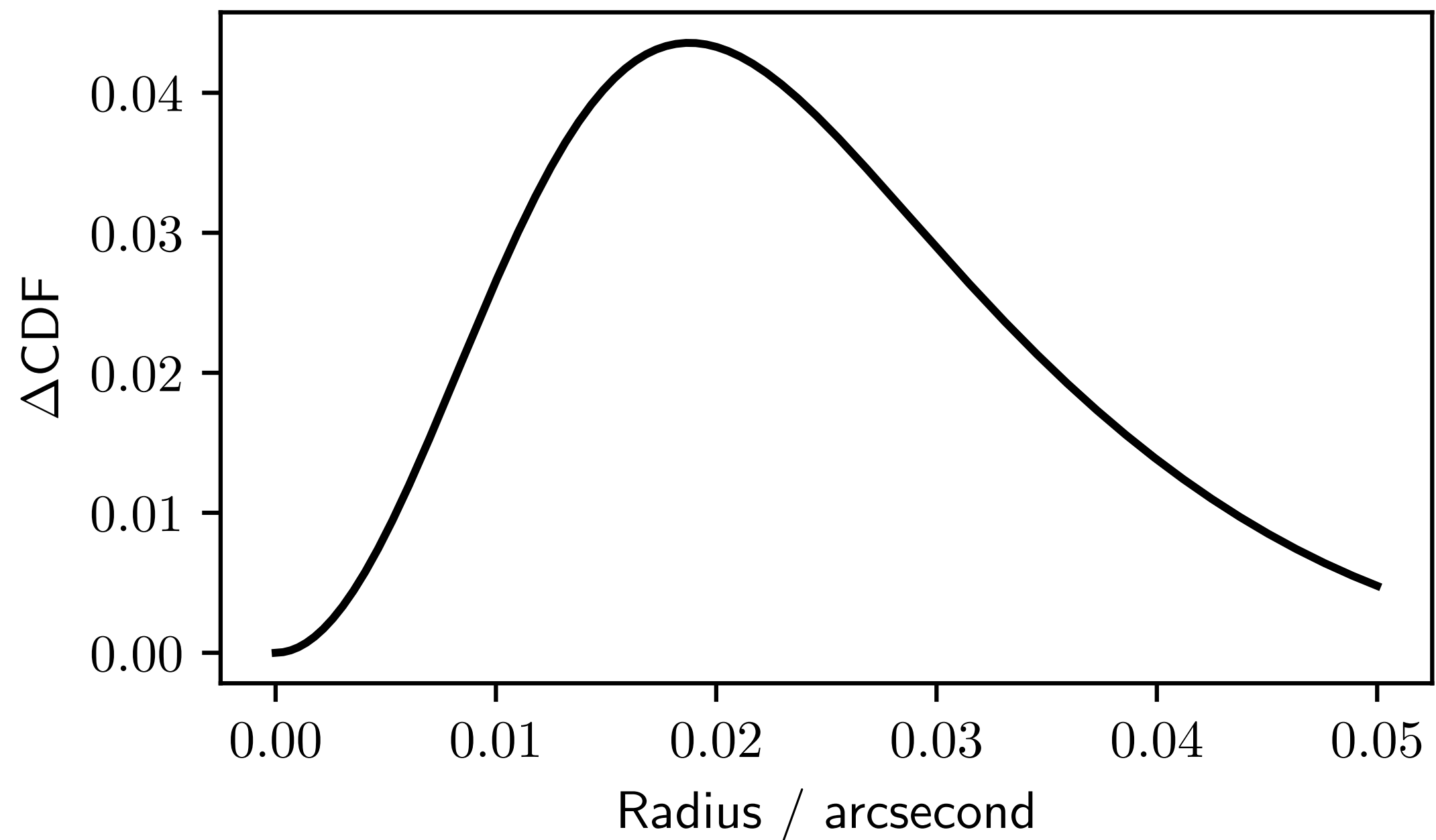
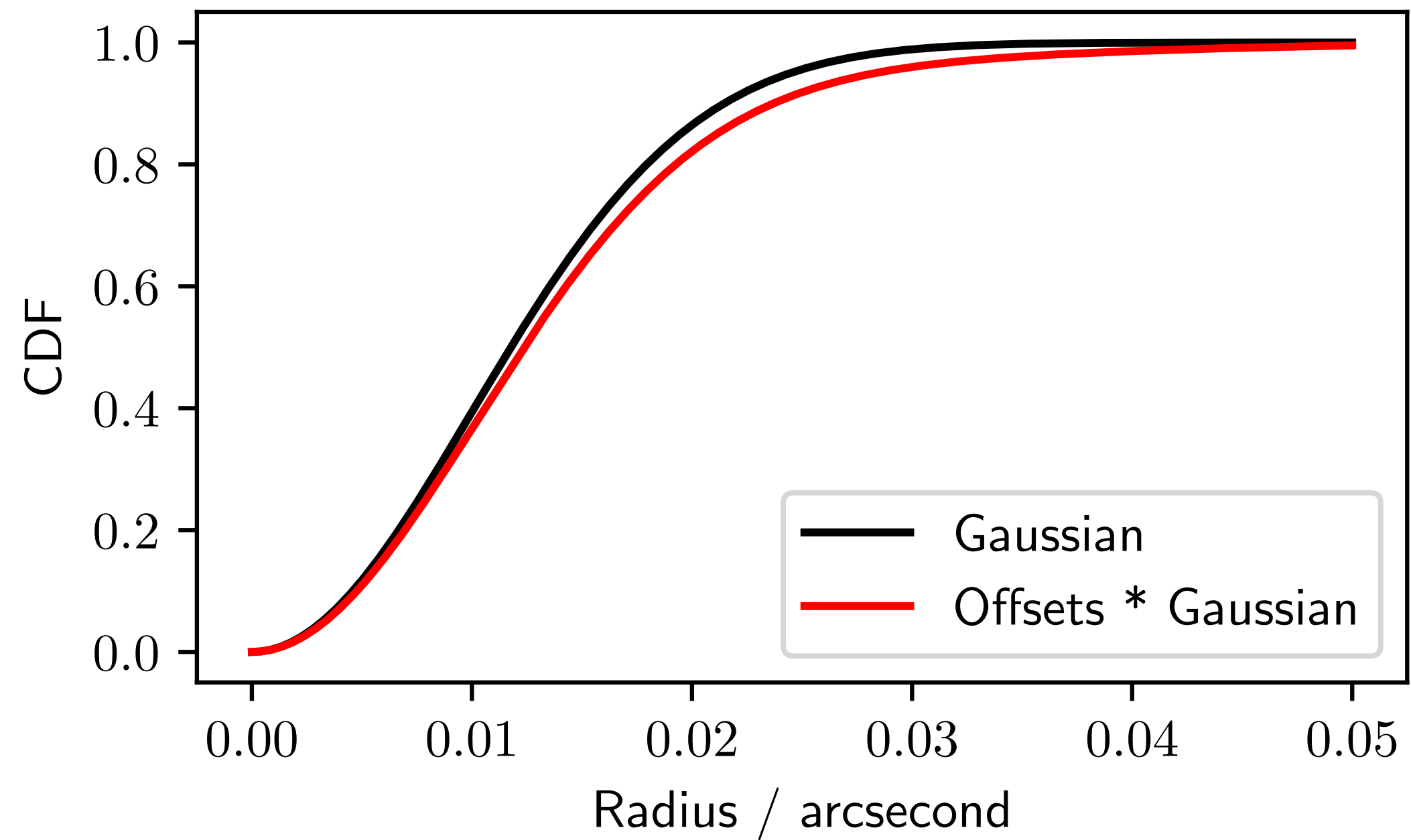
The Rubin AUF: \checkmark Extra-Galactic Transients

(very well-behaved!)



Wilson & Naylor (2018b); also
see Wilson (2022, RNAAS)

The Rubin AUF: Extra-Galactic Transients



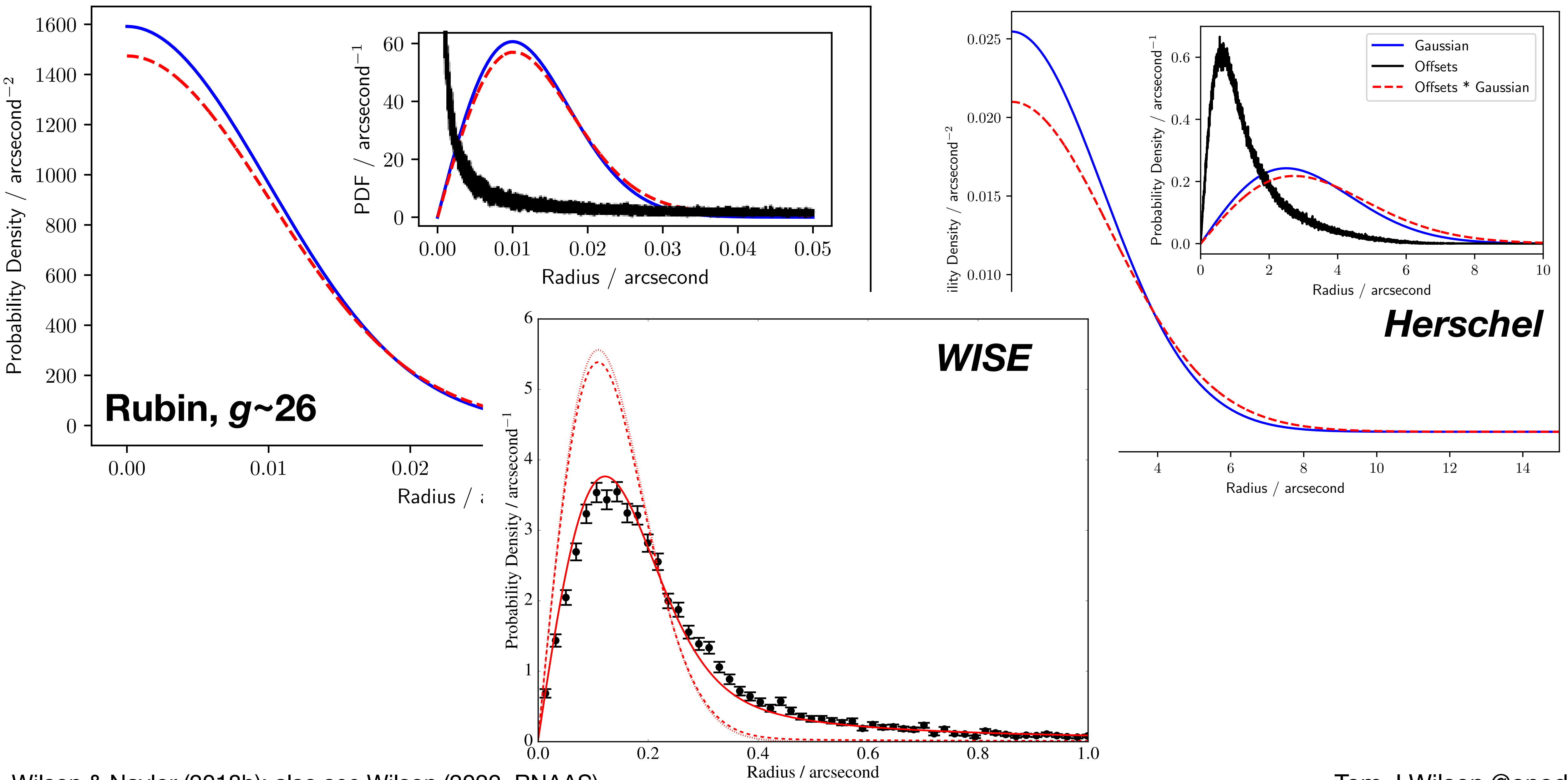
Explosion

Progenitor

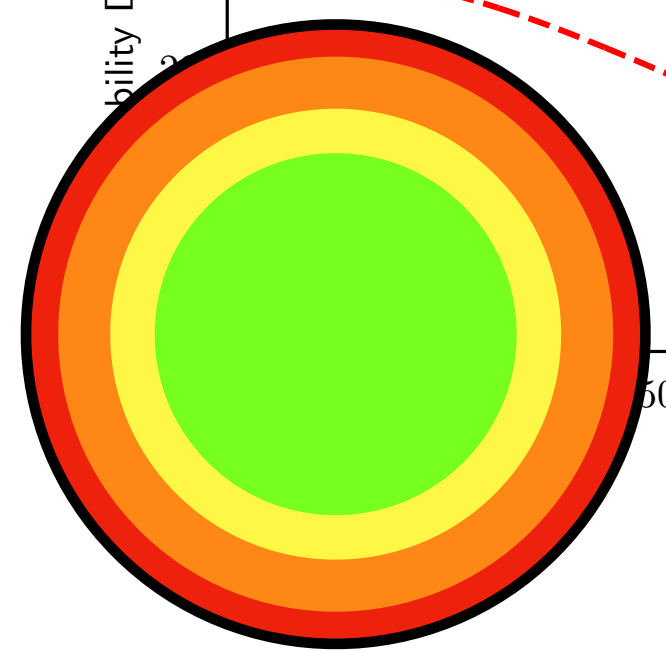
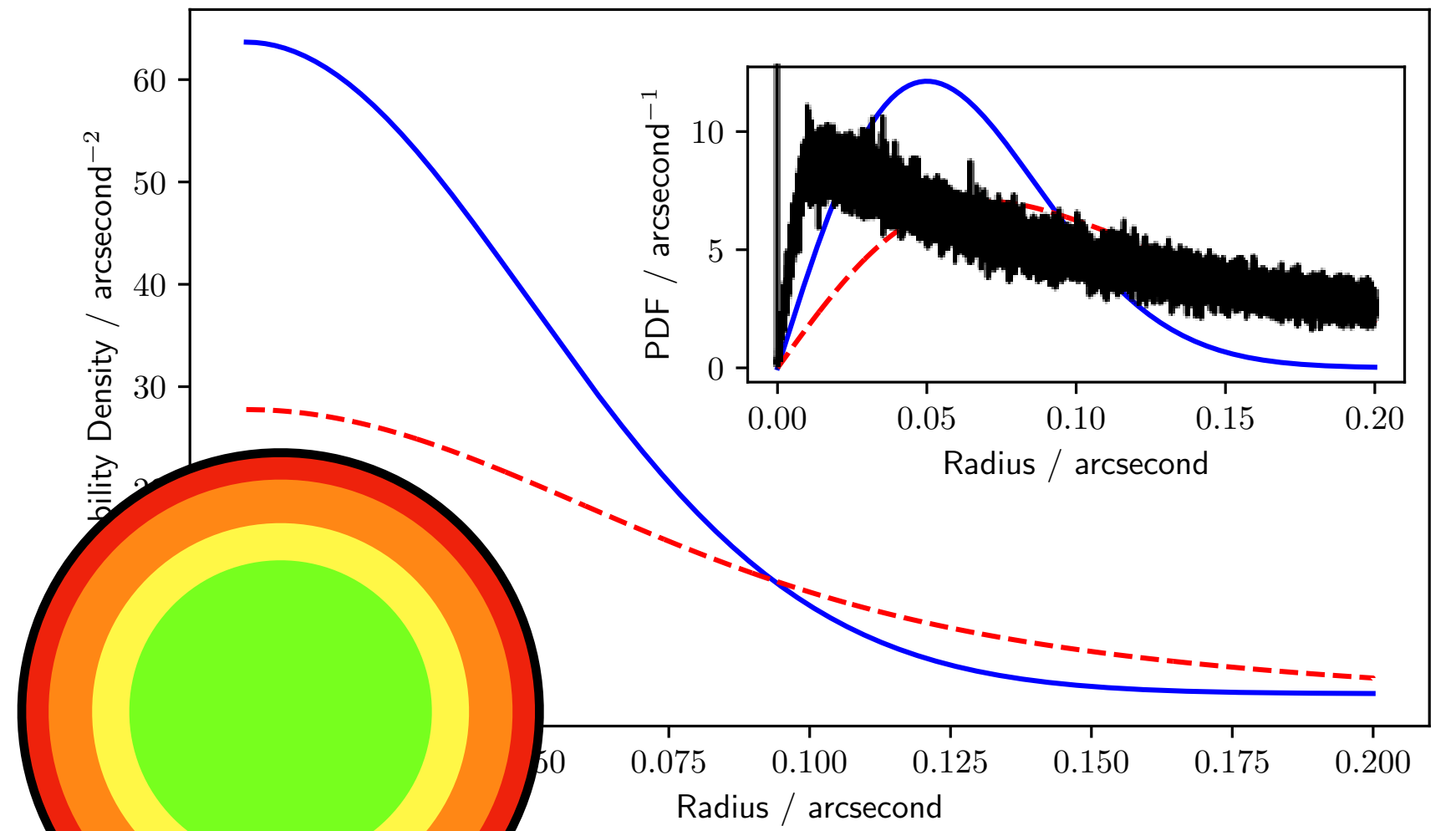
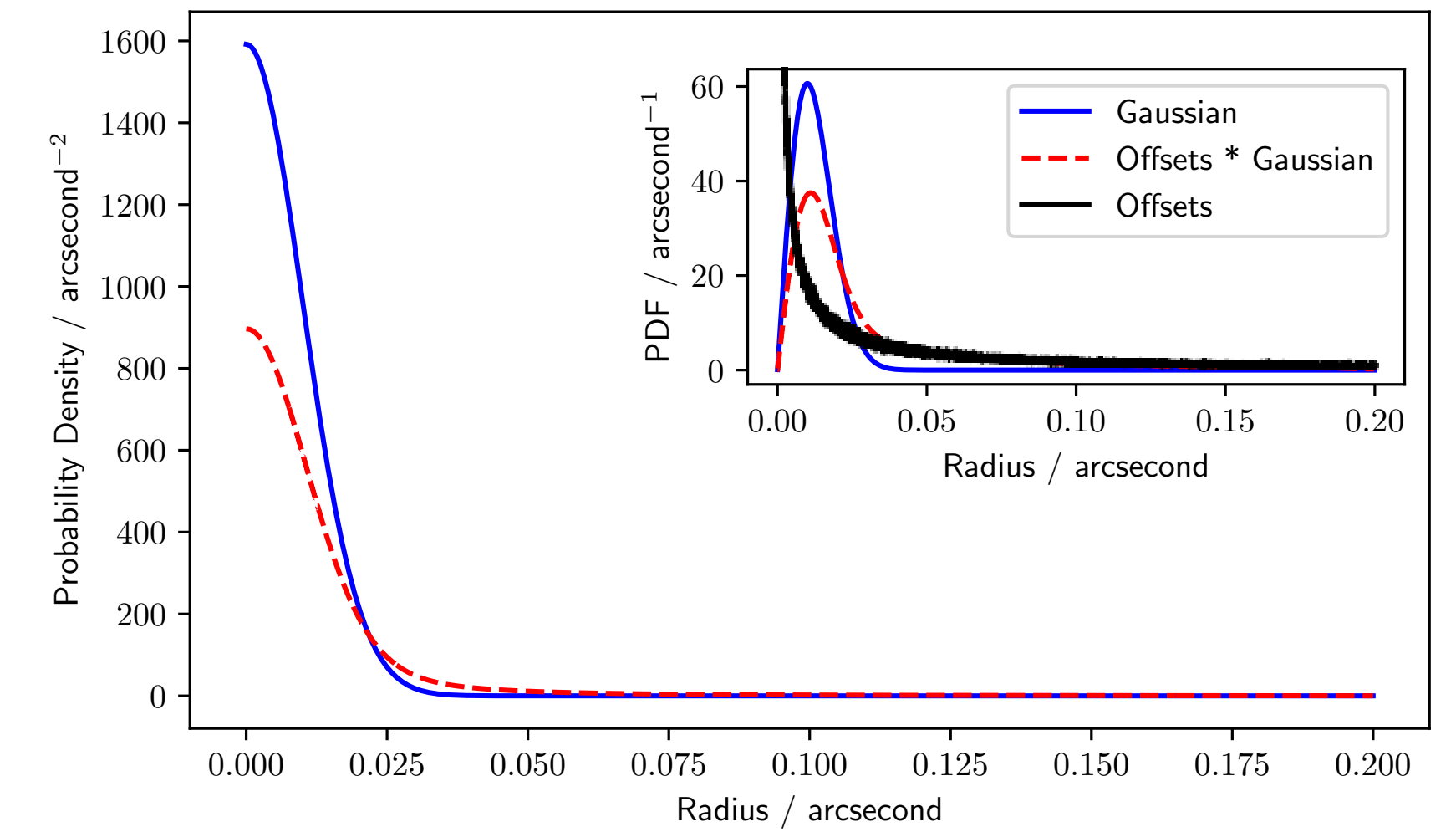
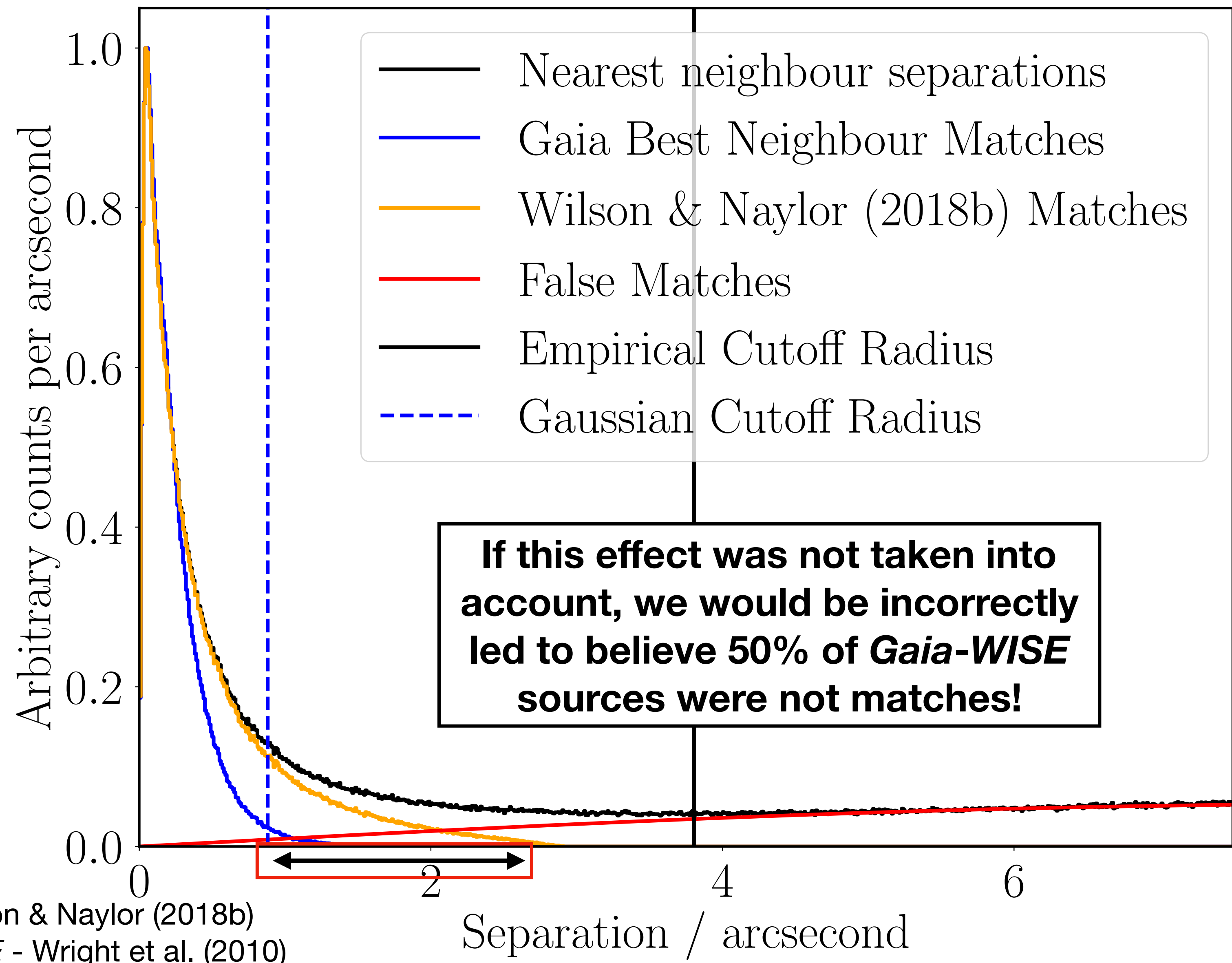
Wilson & Naylor (2018b); also
see Wilson (2022, RNAAS)

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The Rubin AUF: Extra-Galactic Transients



Match Separations



The AUF does not need to, and in fact quite often should *not*, be Gaussian!

Wilson & Naylor (2018b)
WISE - Wright et al. (2010)
Gaia matches - Marrese et al. (2019)
Gaia DR2 - Gaia Collaboration, Brown A. G. A., et al. (2018)

Conclusions

- Our cross-match algorithms include two key elements to avoid issues with crowded & confused data
 - A generalised approach to the Astrometric Uncertainty Function allows for the full inclusion of the effects of perturbation due to blended sources – reduce false -ves!
 - Where it can be applied (i.e., the static sky) use of (two-sided) photometry to sort out multiplicity of higher resolution data – reduce false +ves!
- Software package macauff developed to cross-match catalogues, including the effect of unresolved contaminant sources (and rejection of interloper objects using photometry in the static sky)
 - Developed through Rubin/LSST:UK, with plans to match LSST to *Gaia*, *WISE*, *VISTA*, *SDSS*, ...
 - We have compute time to cross-match datasets – let me know your favourite combo, and what you need matched (to LSST or otherwise)!
- Incorporating this extension of position uncertainty into real-time matches allows for more robust counterpart identification in the alert stream and a more accurate and precise transient SED
 - Furthermore, we can provide *statistical* information on the level of photometric contamination unresolved contaminant sources cause, which can be subtracted in a probabilistic framework!



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Wilson & Naylor, 2017, MNRAS, 468, 2517
Wilson & Naylor, 2018a, MNRAS, 473, 5570
Wilson & Naylor, 2018b, MNRAS, 481, 2148
Wilson, 2022, RNAAS, 6, 60
Wilson, 2023, RASTI, 2, 1

<https://github.com/Onoddil/macauff>



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