

# Enabling Cool Rubin Science with Robust Cross-Matches in the Faint, Crowded LSST Sky

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2024 RUBIN SOLAR NEIGHBORHOOD ULTRACOOOL DWARFS MEETING - 26/JAN/24

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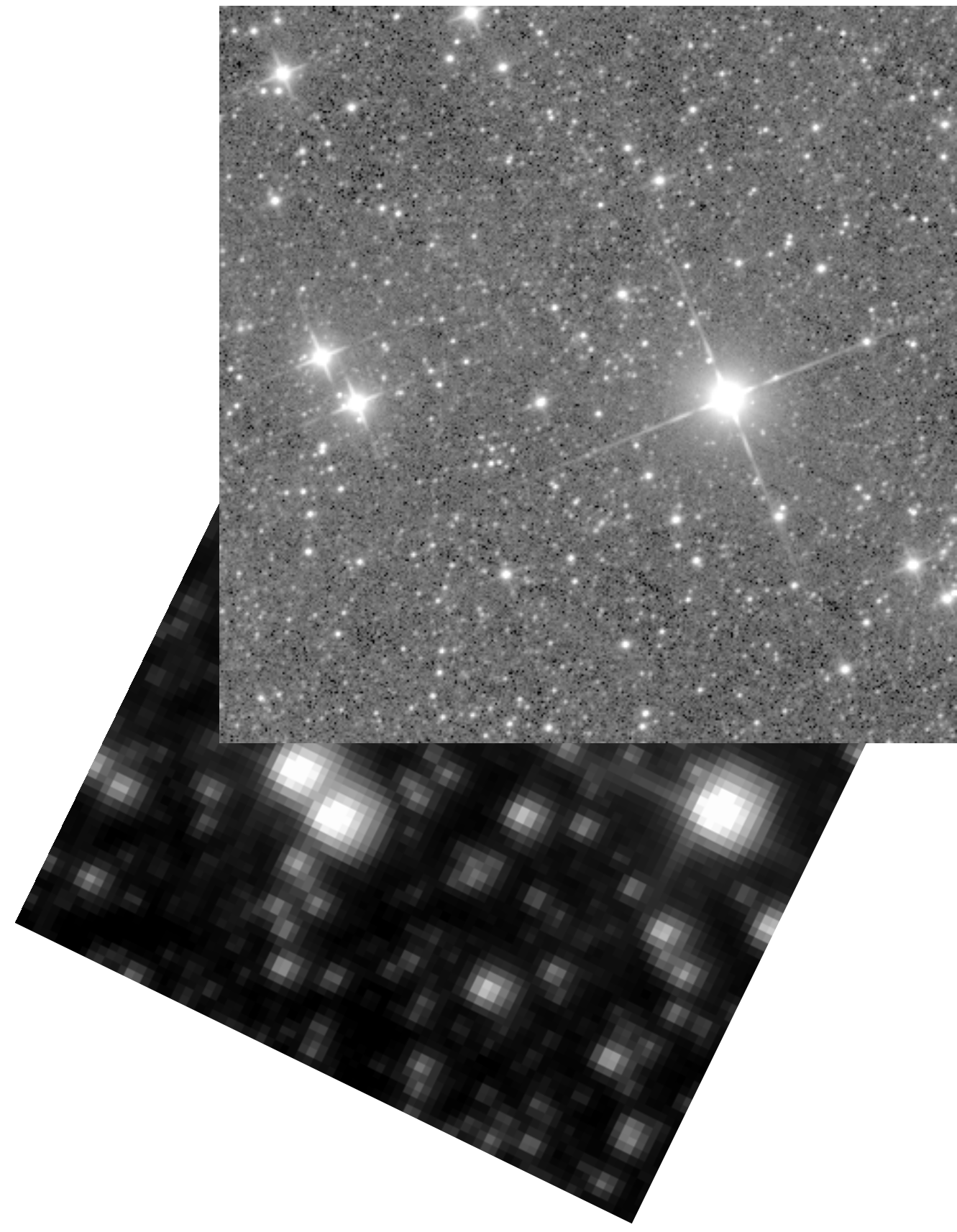
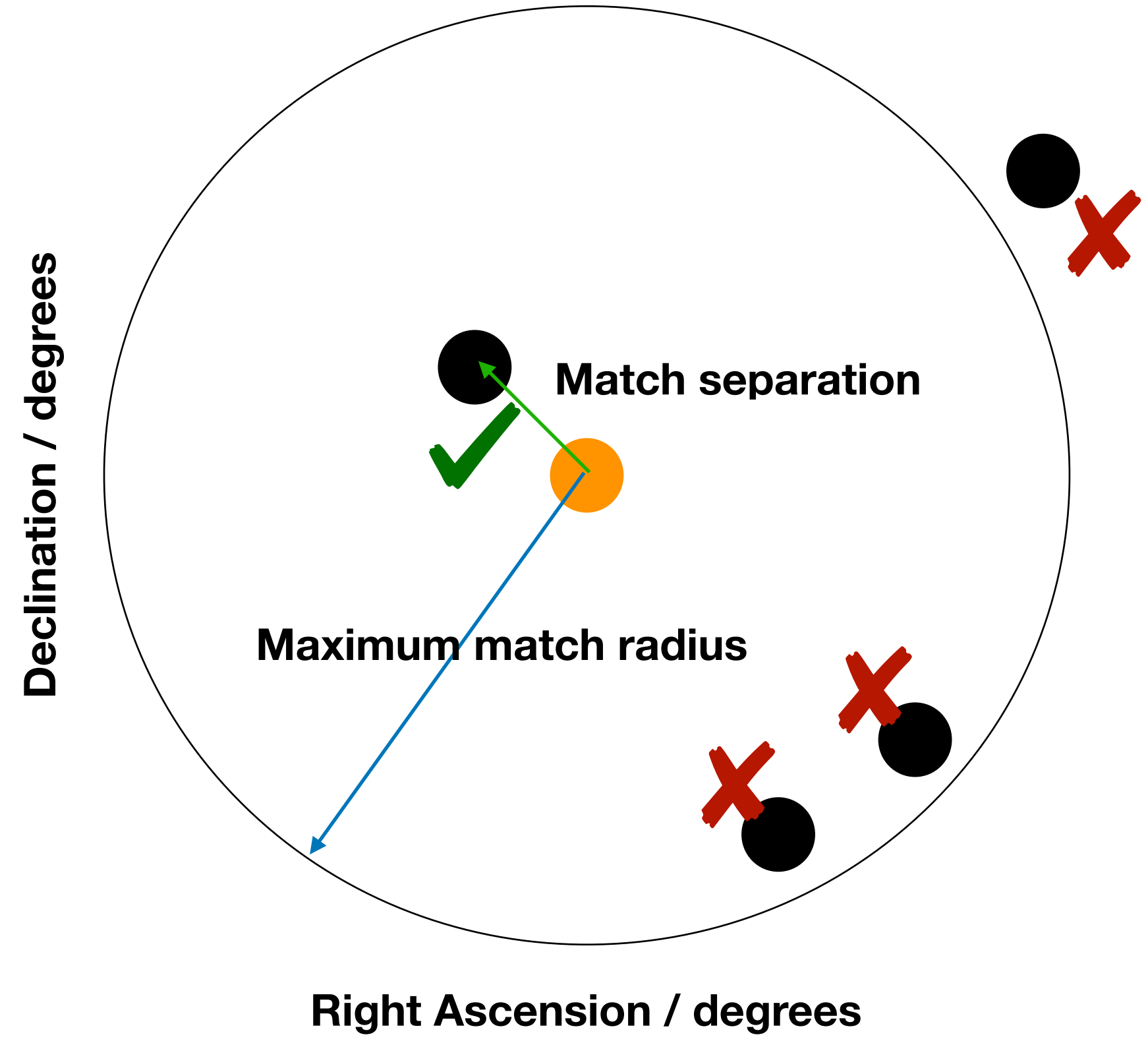
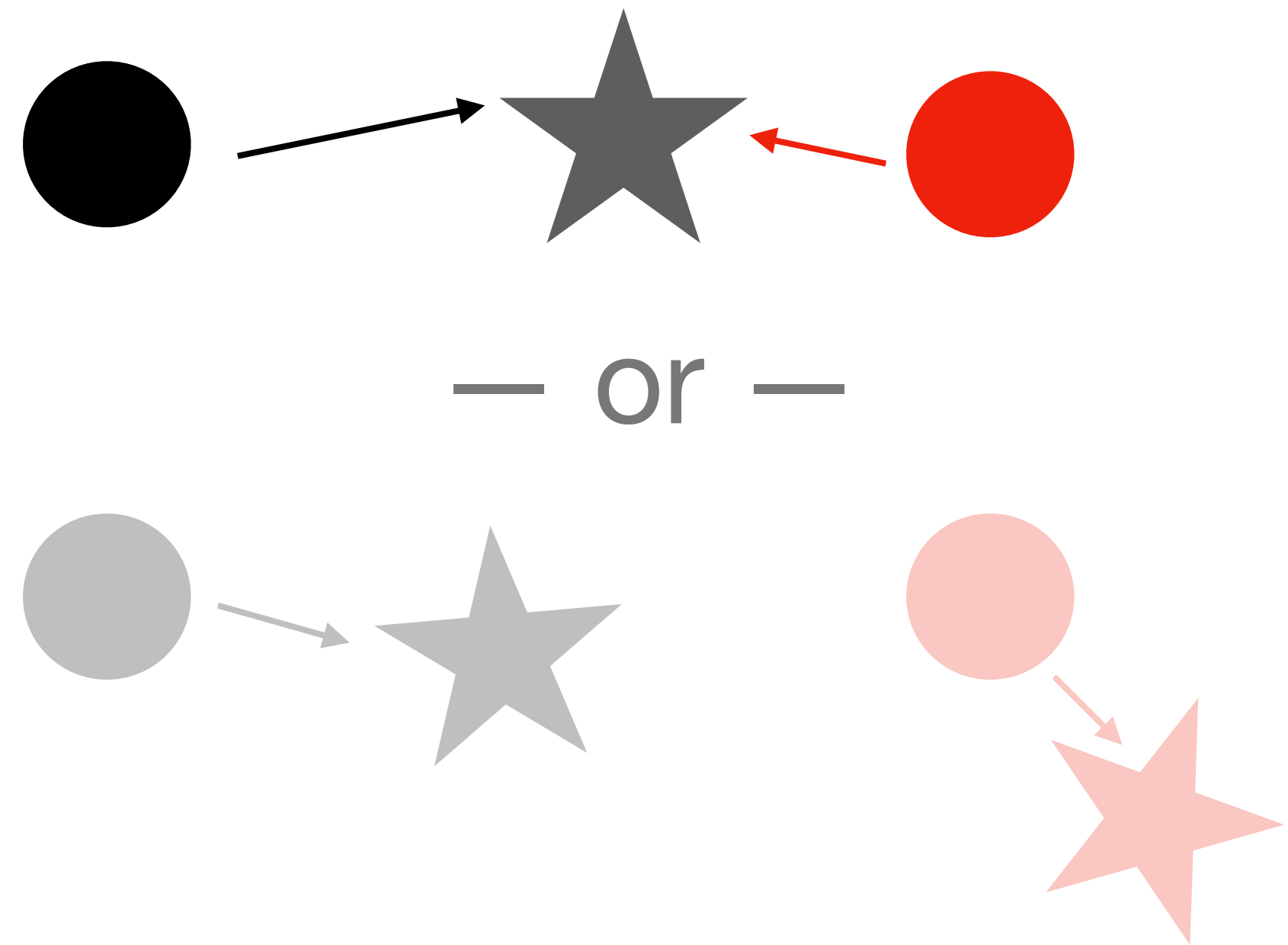
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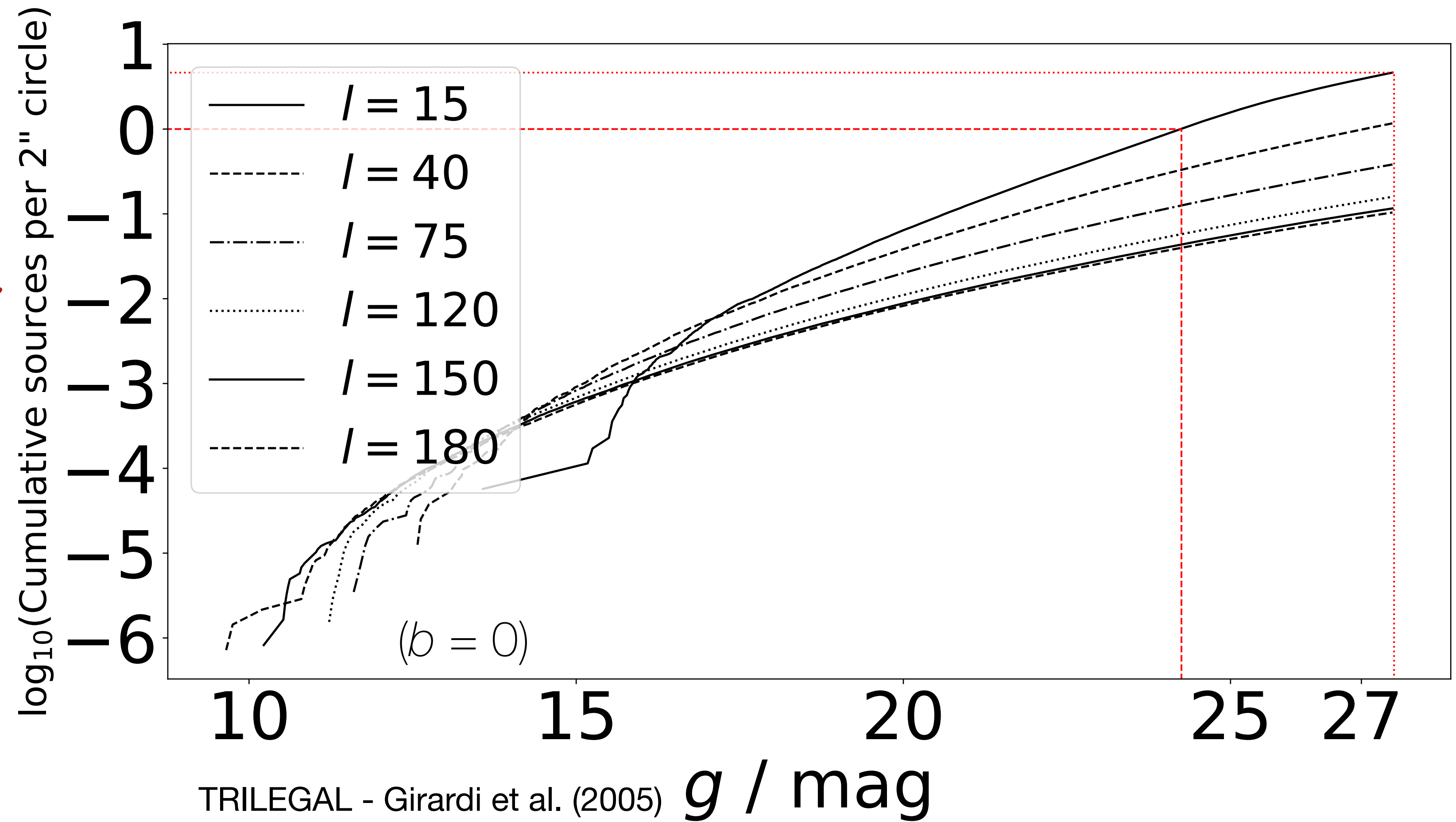
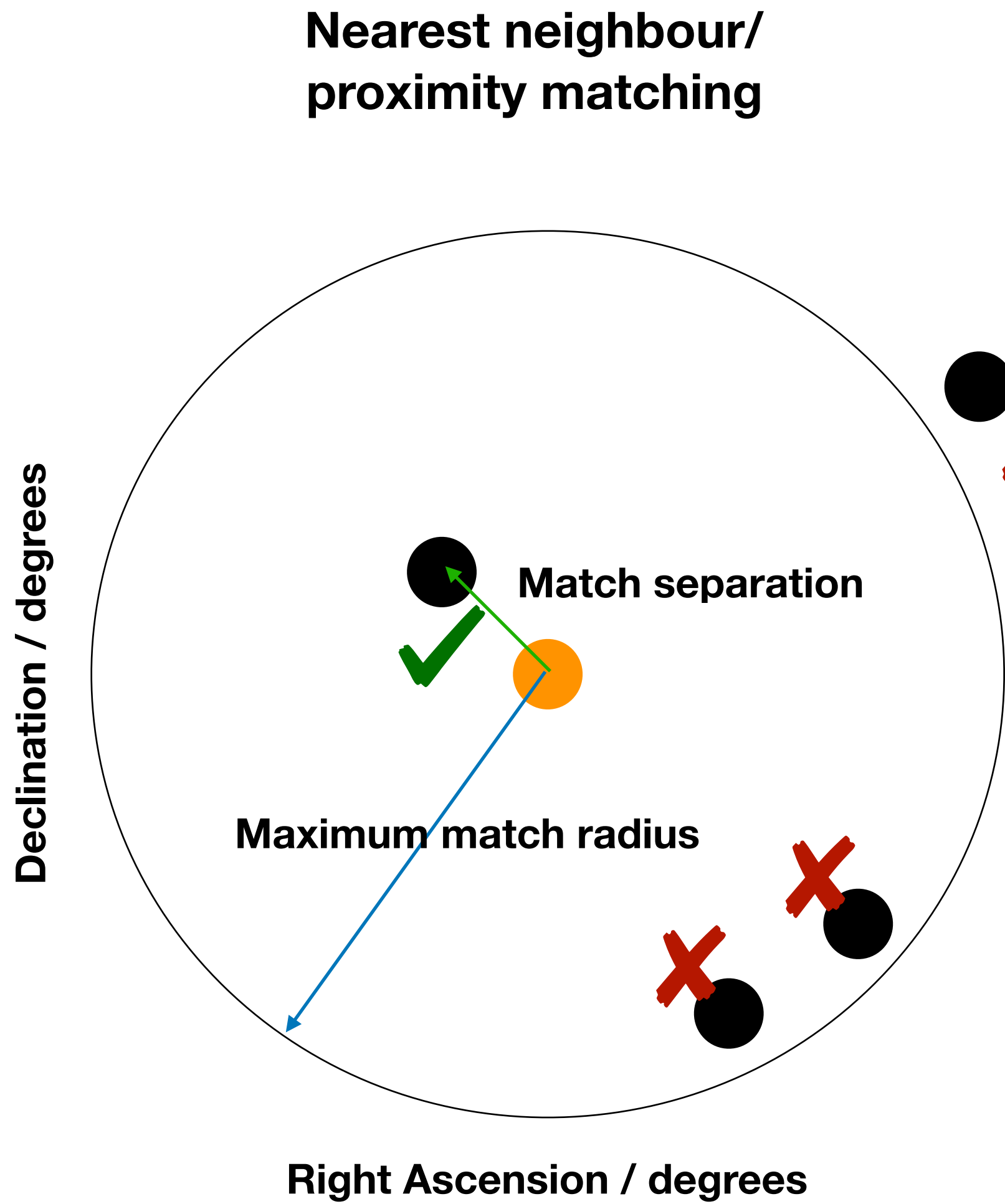
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# “Simple” Cross-Matching

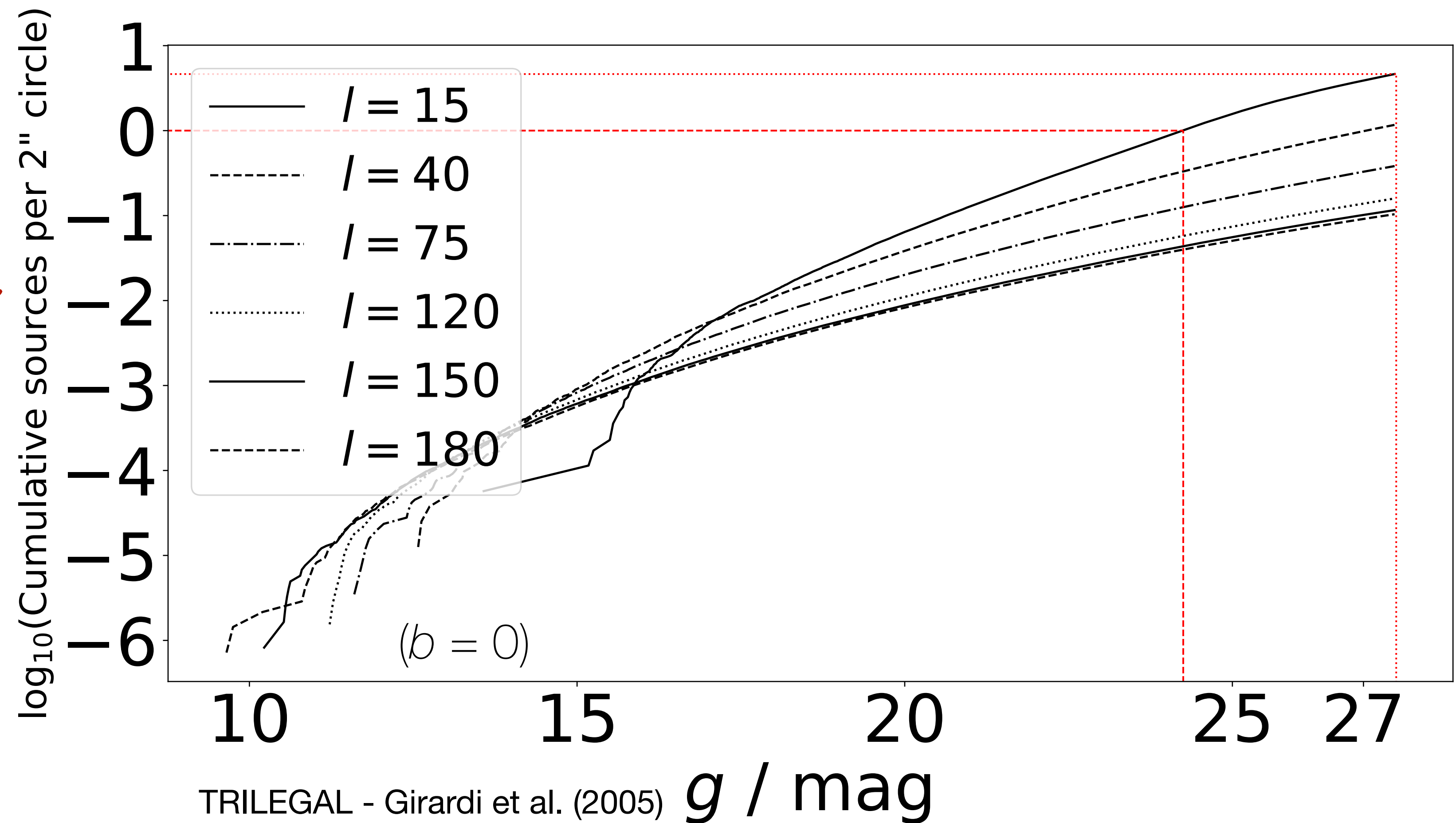
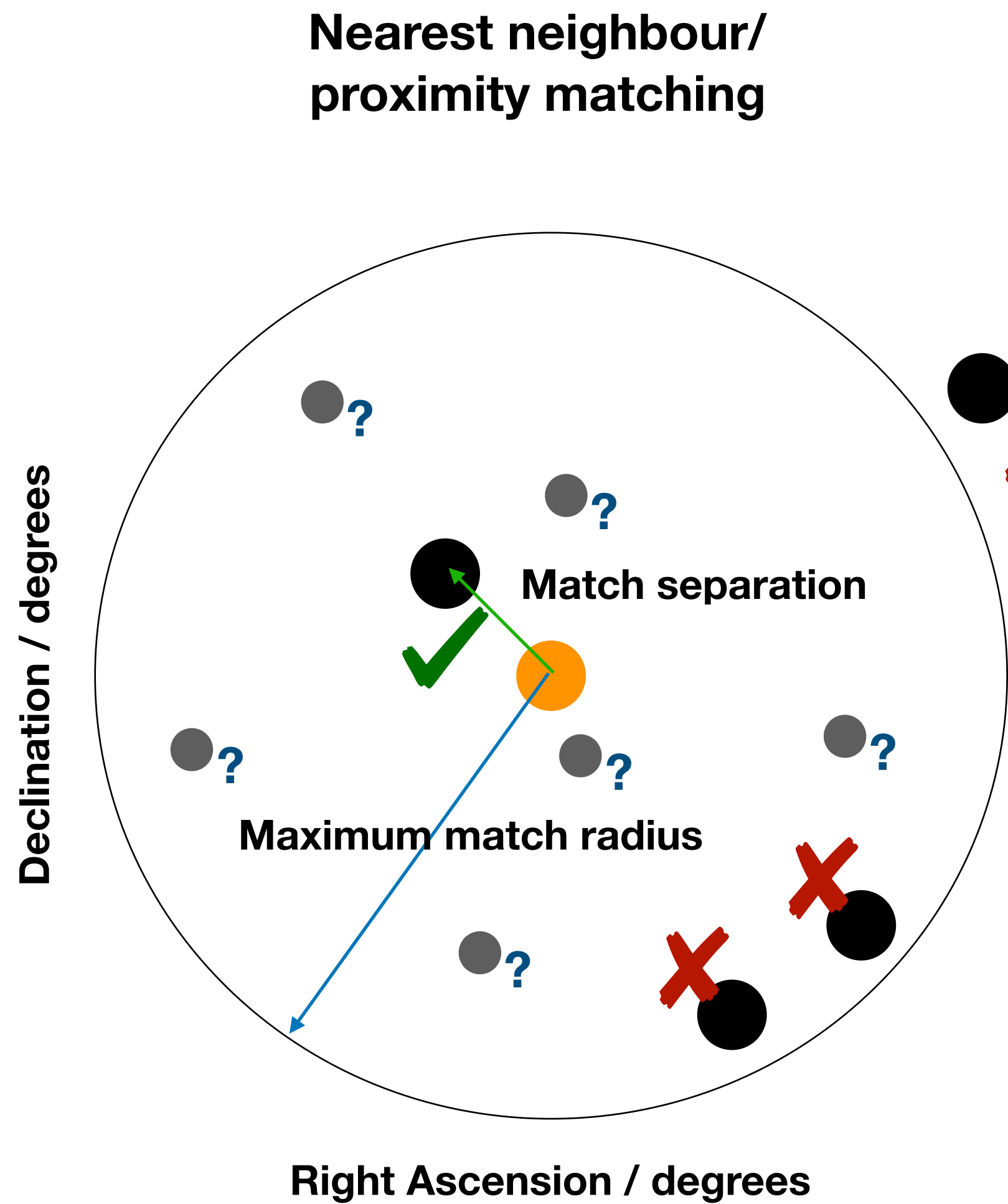


# The Problem With LSST



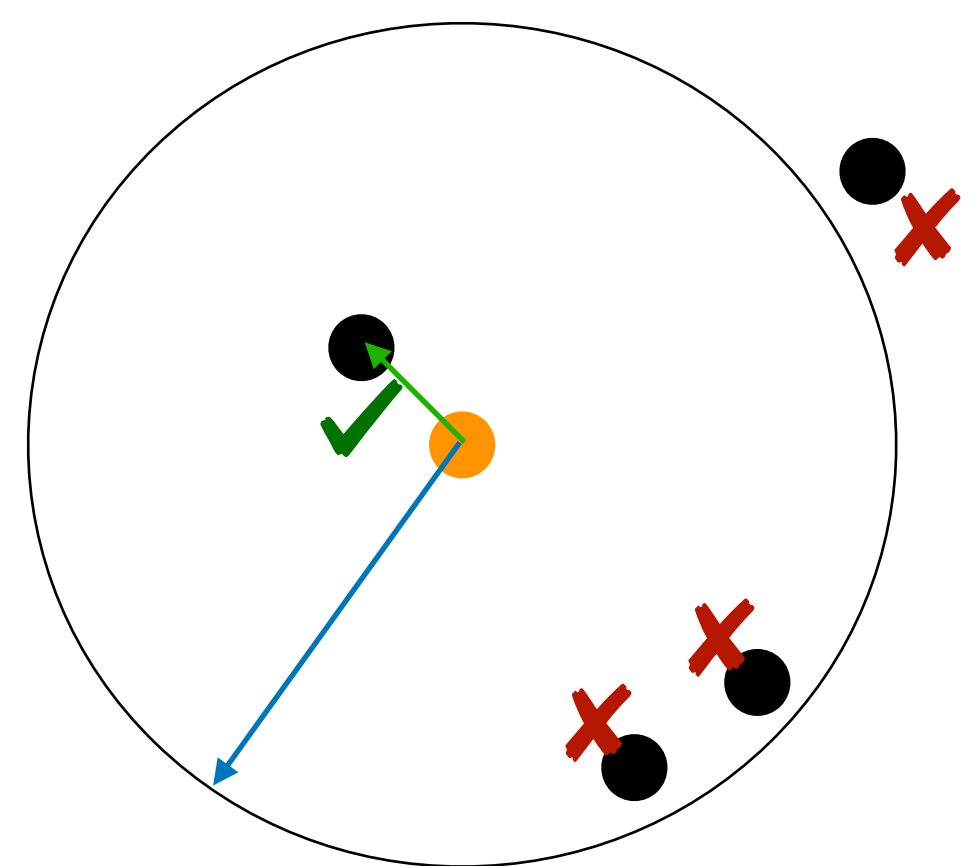
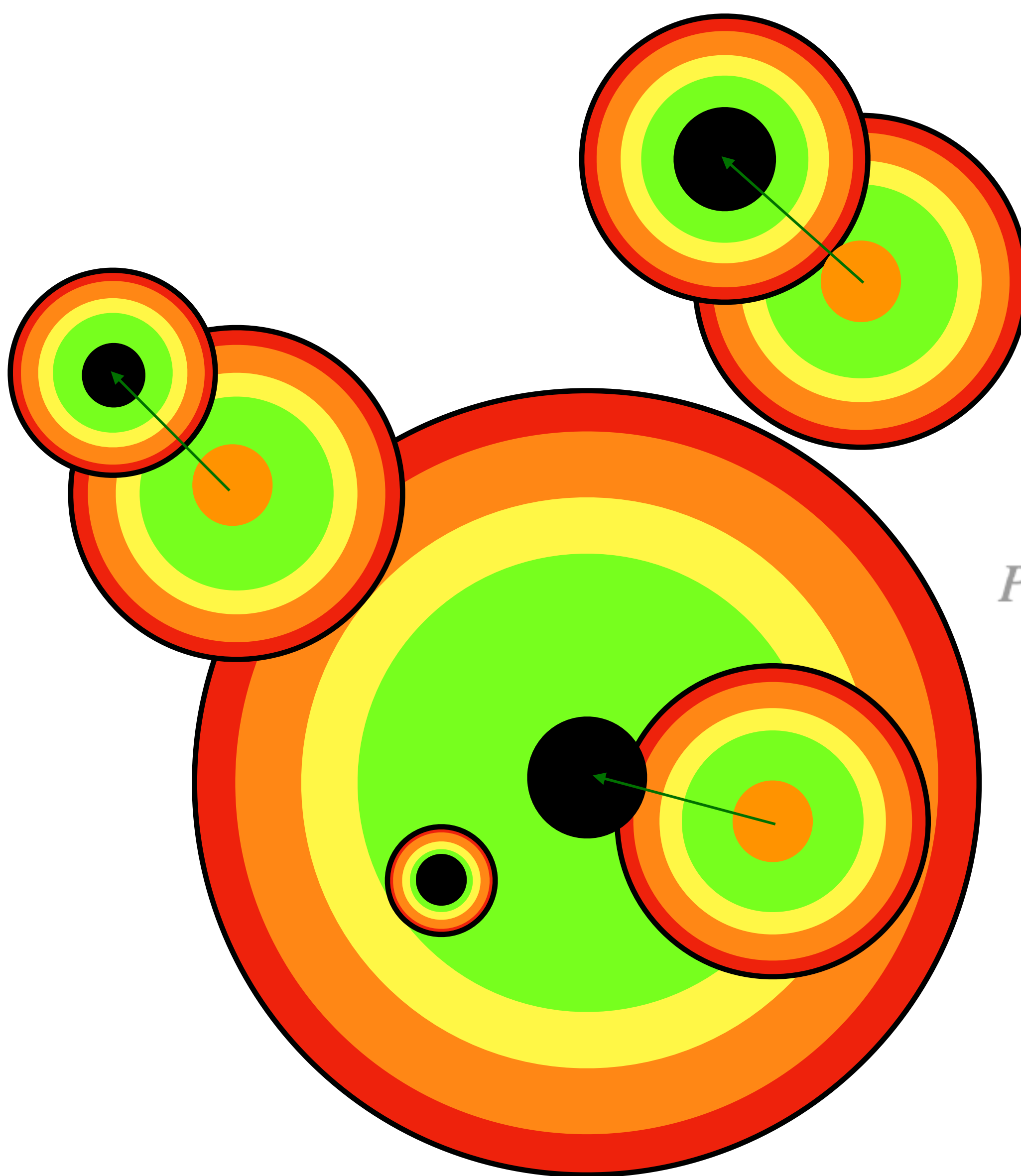
# The Problem With LSST

(It's still a few randomly placed objects in every match radius at high Galactic latitudes)



**Nearest-neighbour matching *will not* work in the era of Rubin!**

# Probabilistic Cross-Matching



Probability of two sources having their on-sky separation given the hypothesis they are counterparts

$$P(\zeta, \lambda, k | \gamma, \phi) = \frac{1}{K} \times \prod_{\delta \notin \zeta \cap \delta \in \gamma} N_\gamma f_\gamma^\delta \prod_{\omega \notin \lambda \cap \omega \in \phi} N_\phi f_\phi^\omega \prod_{i=1}^k N_c G_{\gamma\phi}^{\zeta_i \lambda_i} c_{\gamma\phi}^{\zeta_i \lambda_i}$$

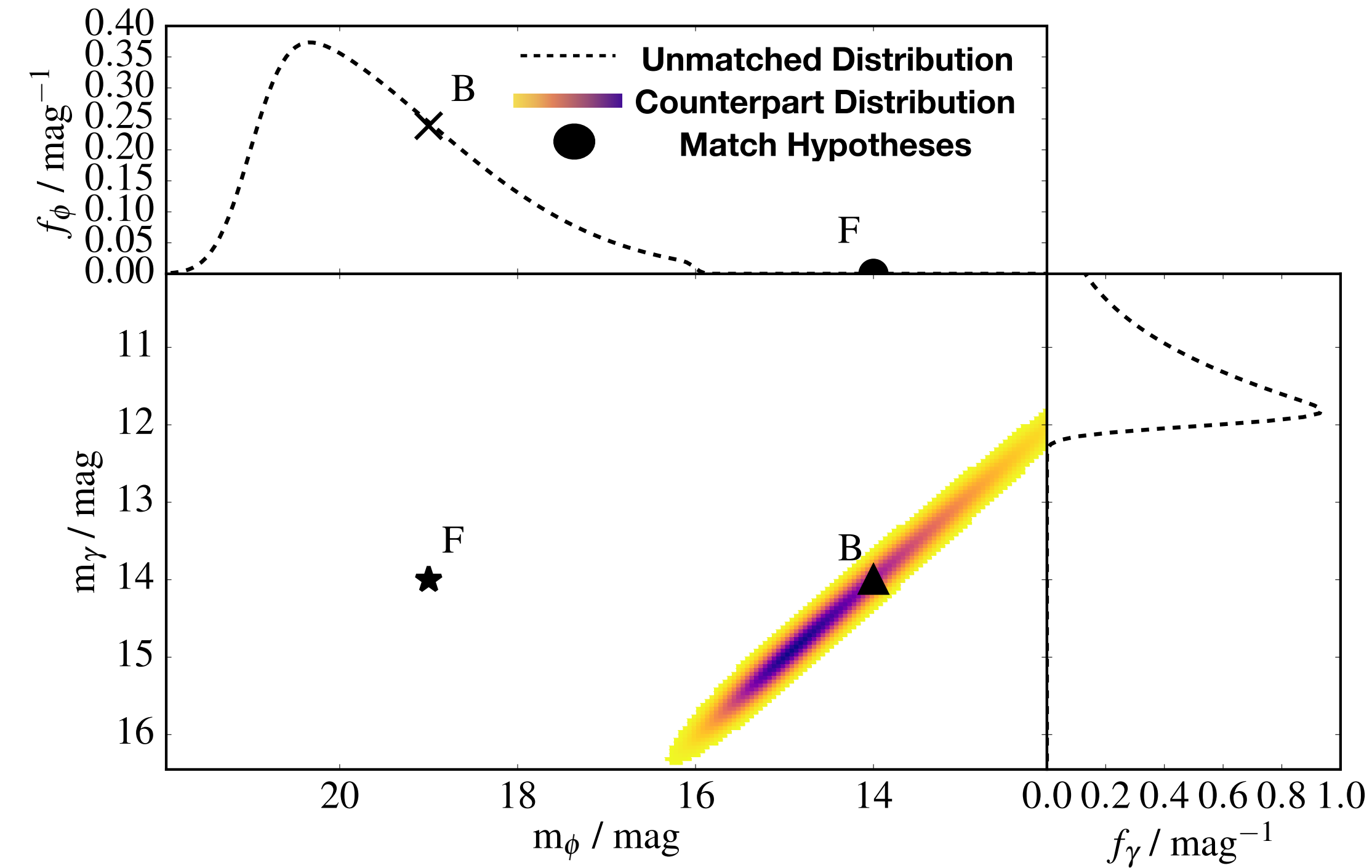
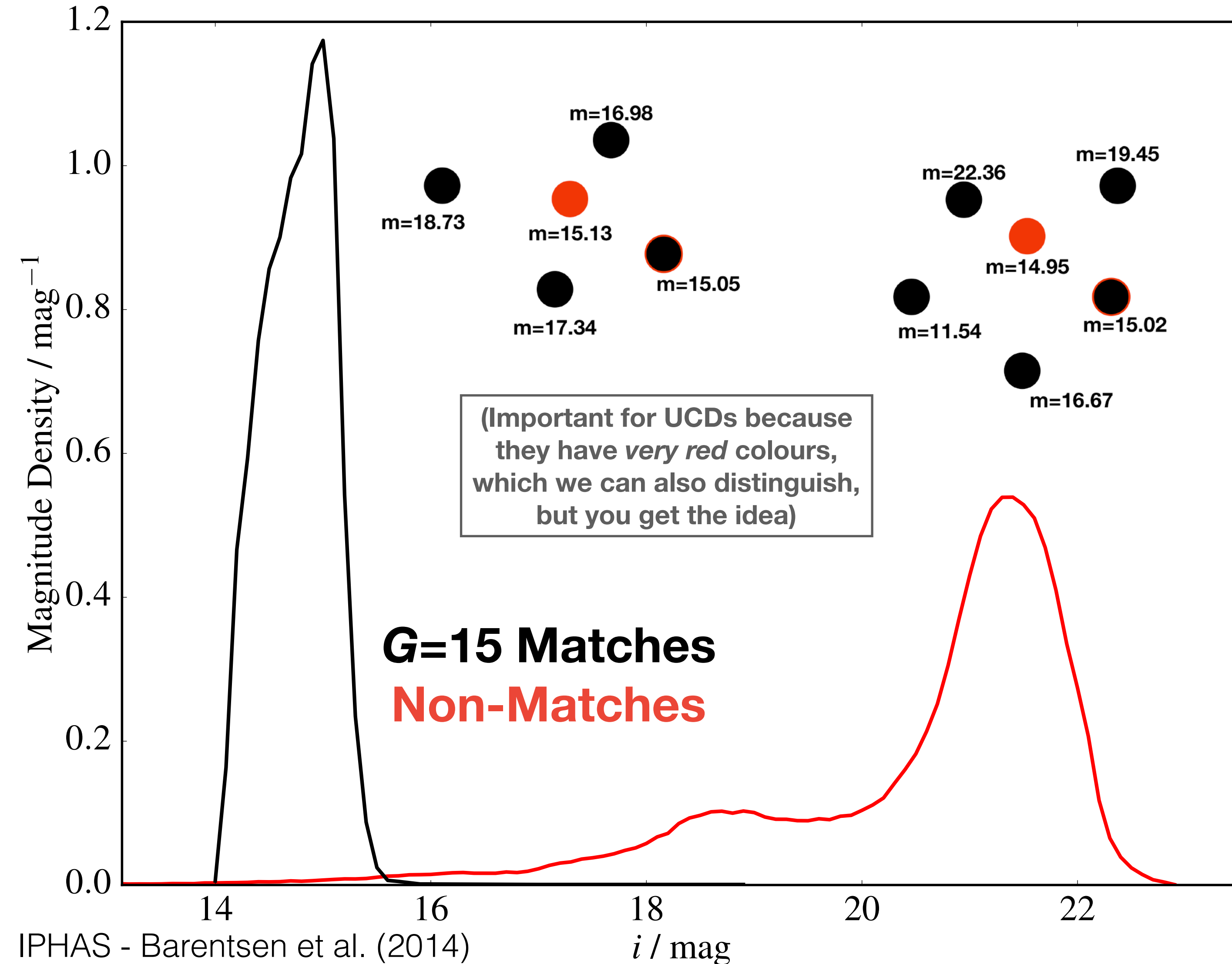
Wilson & Naylor (2018a)

Probability of sources having their brightnesses given they are unrelated to one another (“field stars”)

Probability of sources having their brightnesses given they are counterparts

# Including Magnitude Information: Rejecting False Positives

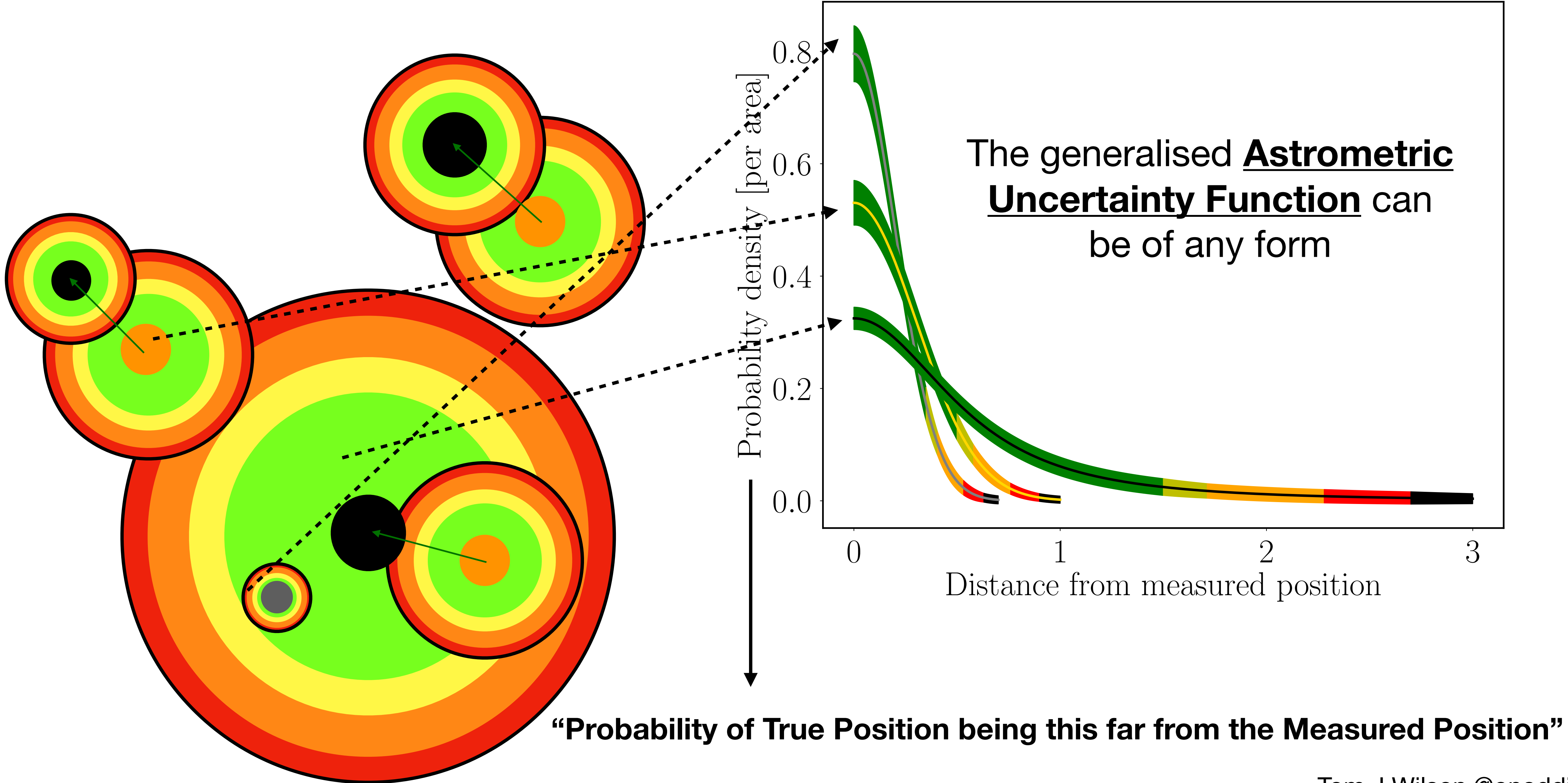
$$P(\zeta, \lambda, k | \gamma, \phi) = \frac{1}{K} \times \prod_{\delta \neq \zeta} N_{\gamma} f_{\gamma}^{\delta} \prod_{\omega \neq \lambda} N_{\phi} f_{\phi}^{\omega} \prod_{i=1}^k N_c G_{\gamma\phi}^{\zeta_i \lambda_i} c_{\gamma\phi}^{\zeta_i \lambda_i}$$



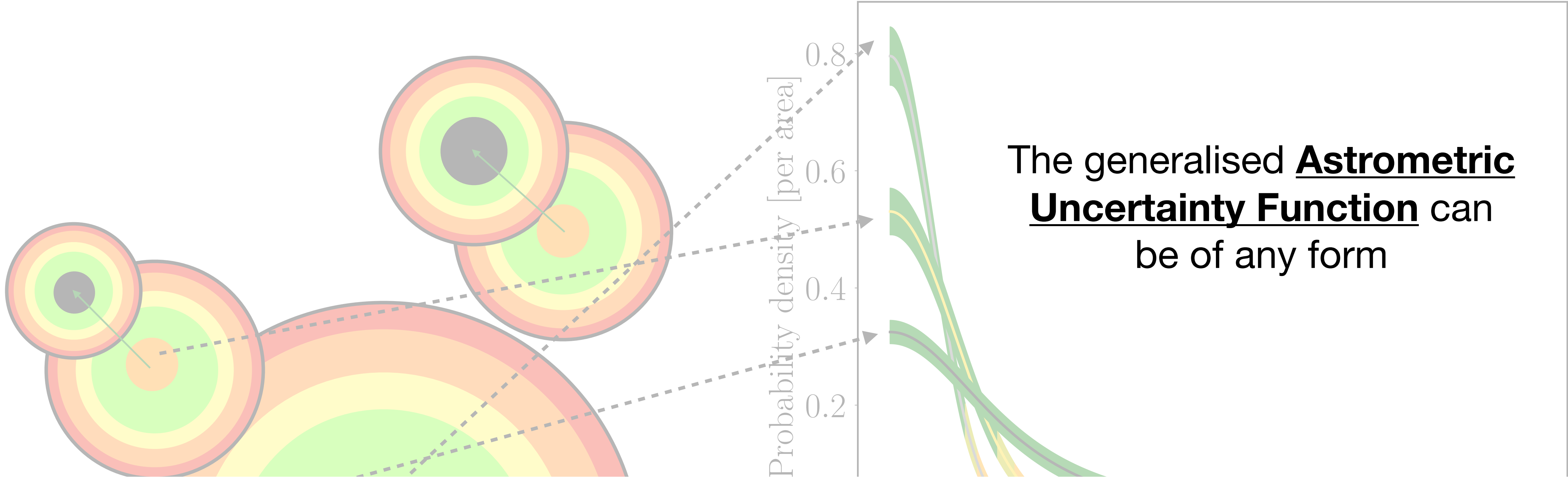
Wilson & Naylor (2018a)

**The photometry-based likelihoods ( $c$  and  $f$ ) allow us to mitigate high false positive rate in crowded fields, but now we need the position-based likelihood  $G$**

# Probabilistic Cross-Matching: the AUF



# Probabilistic Cross-Matching: the AUF



One assumption made in basically all literature: positional errors of sources are Gaussian!

$$dp(r|id) = r \times e^{-r^2/2} dr.$$

de Ruiter, Willis, & Arp (1977)

$$P(i) = \frac{\frac{Xc(m_i) g(\Delta x_i, \Delta y_i)}{Nf(m_i)}}{1 - X + \sum_j \frac{Xc(m_j) g(\Delta x_j, \Delta y_j)}{Nf(m_j)}}$$

Naylor, Broos, & Feigelson (2013)

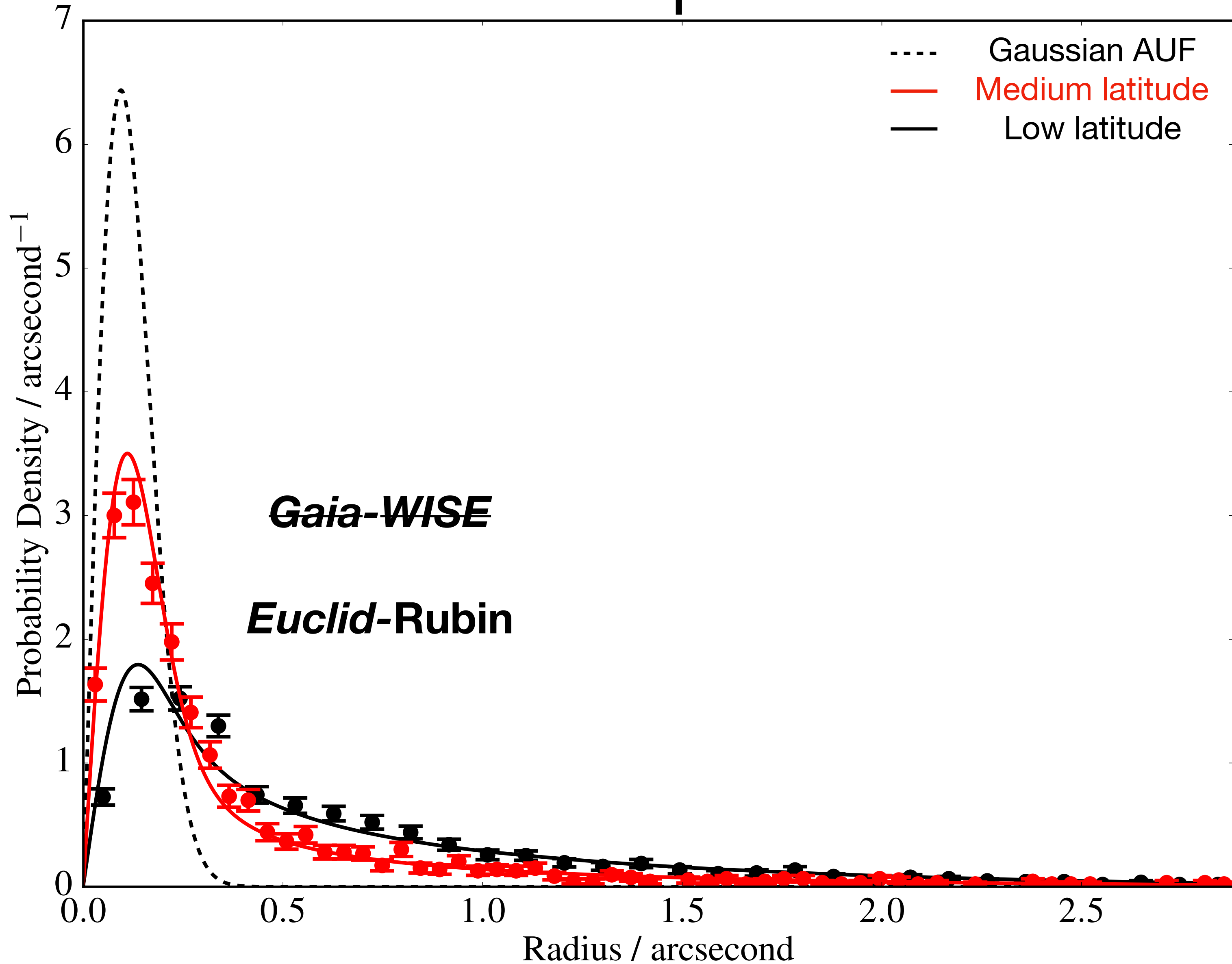
$$p(D|H) = \int p(m|H) \prod_{i=1}^n p_i(x_i|m, H) d^3m$$

Budavári & Szalay (2008)

“Probability of True Position being this far from the Measured Position”



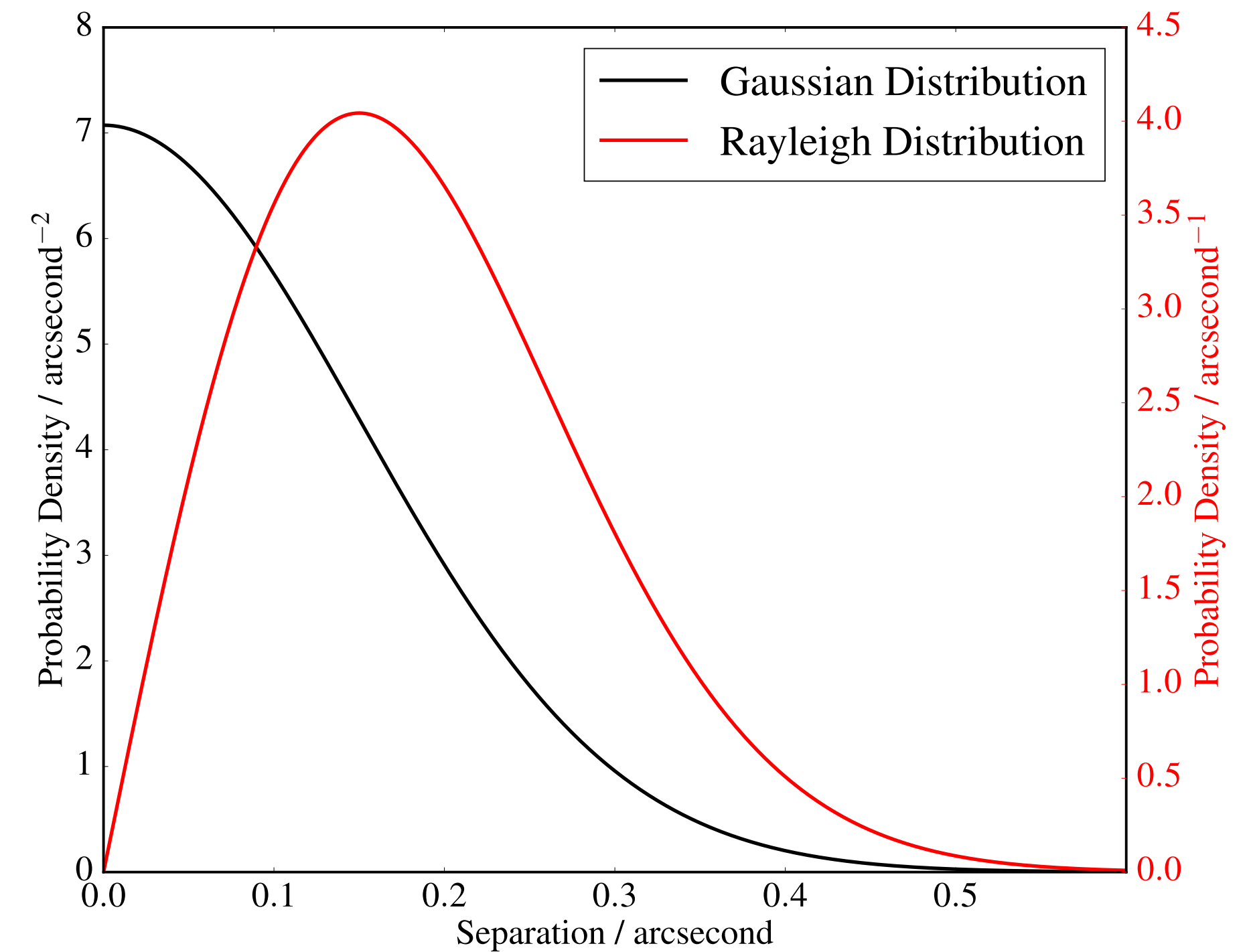
# Additional Components of the AUF



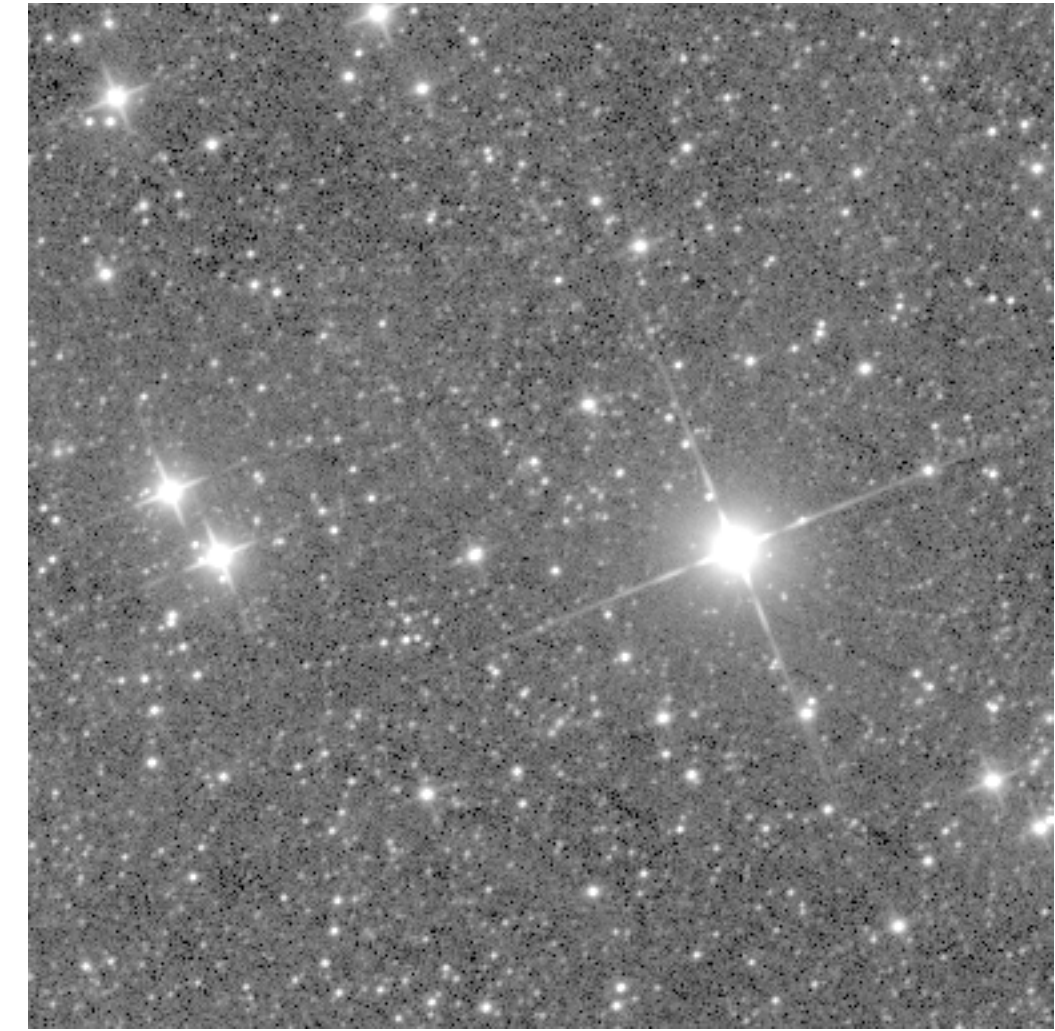
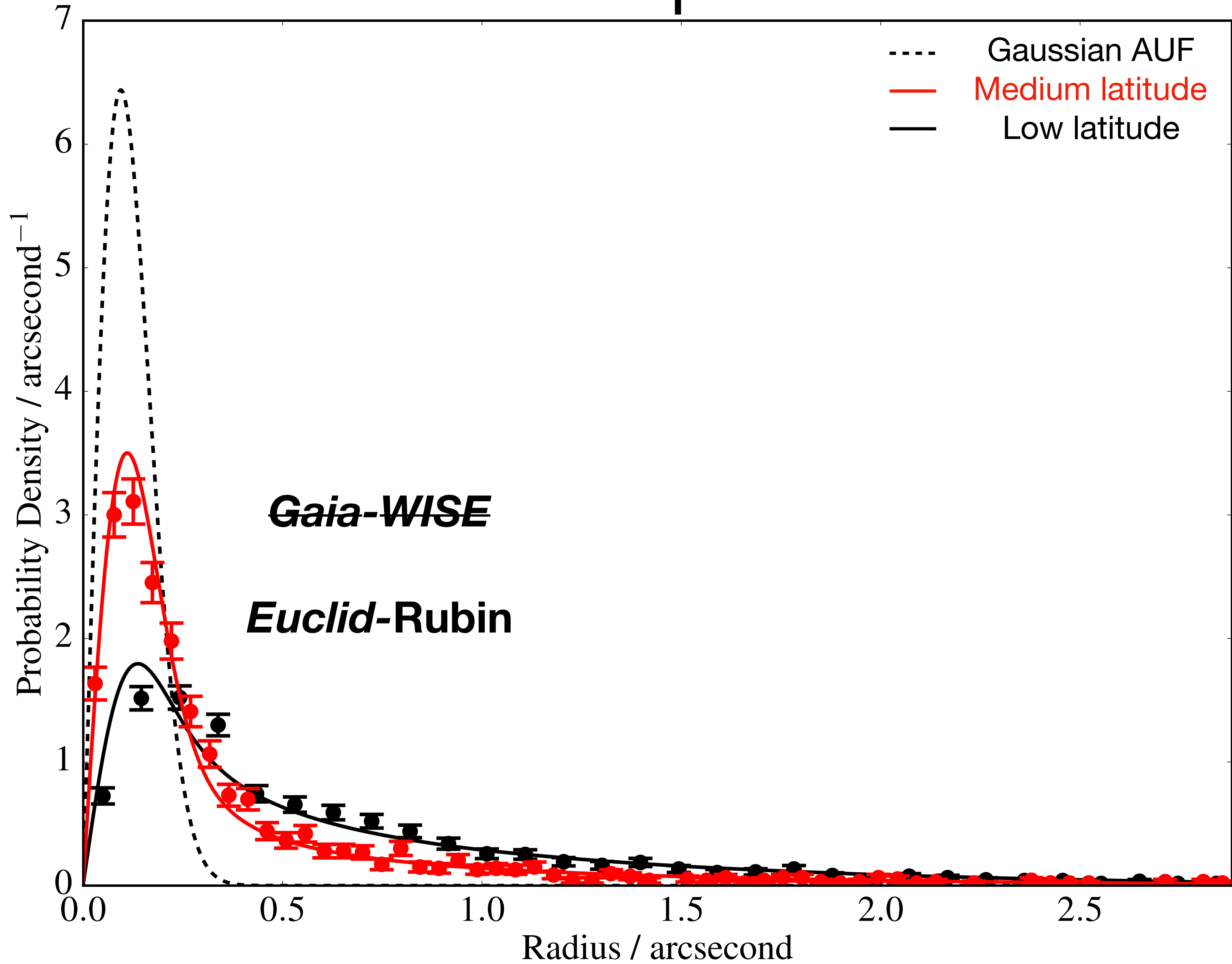
$$g(x, y, \sigma) = (2\pi\sigma^2)^{-1} \exp\left(-\frac{1}{2} \frac{x^2 + y^2}{\sigma^2}\right)$$

↓

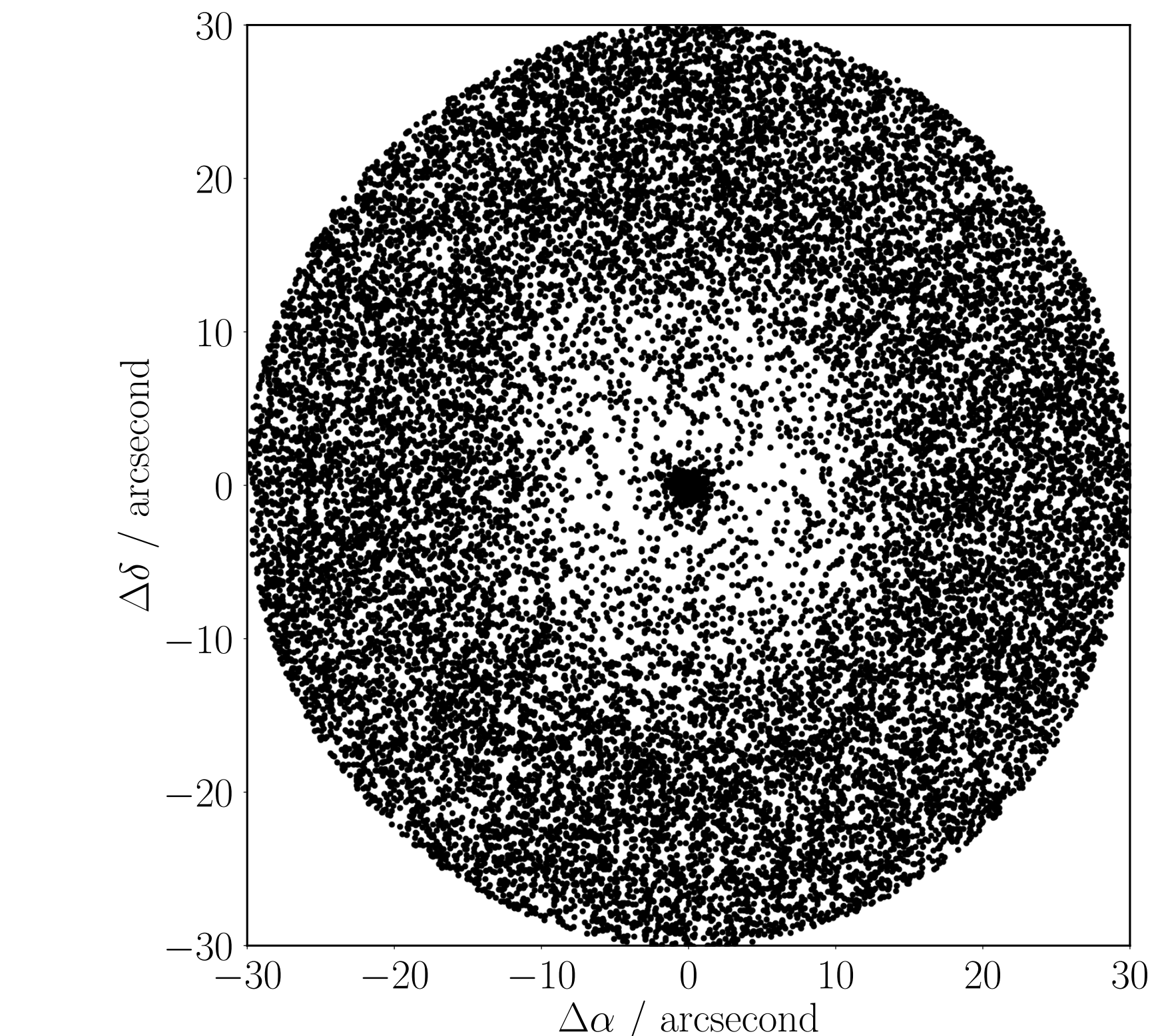
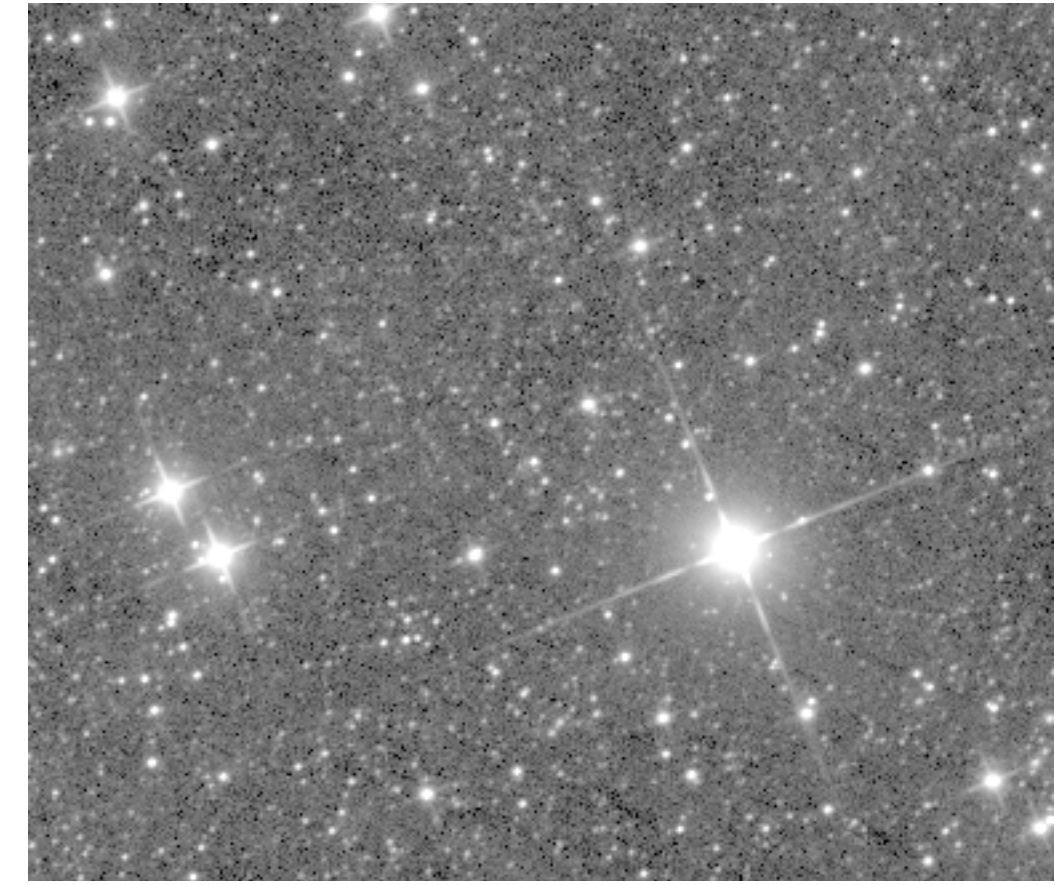
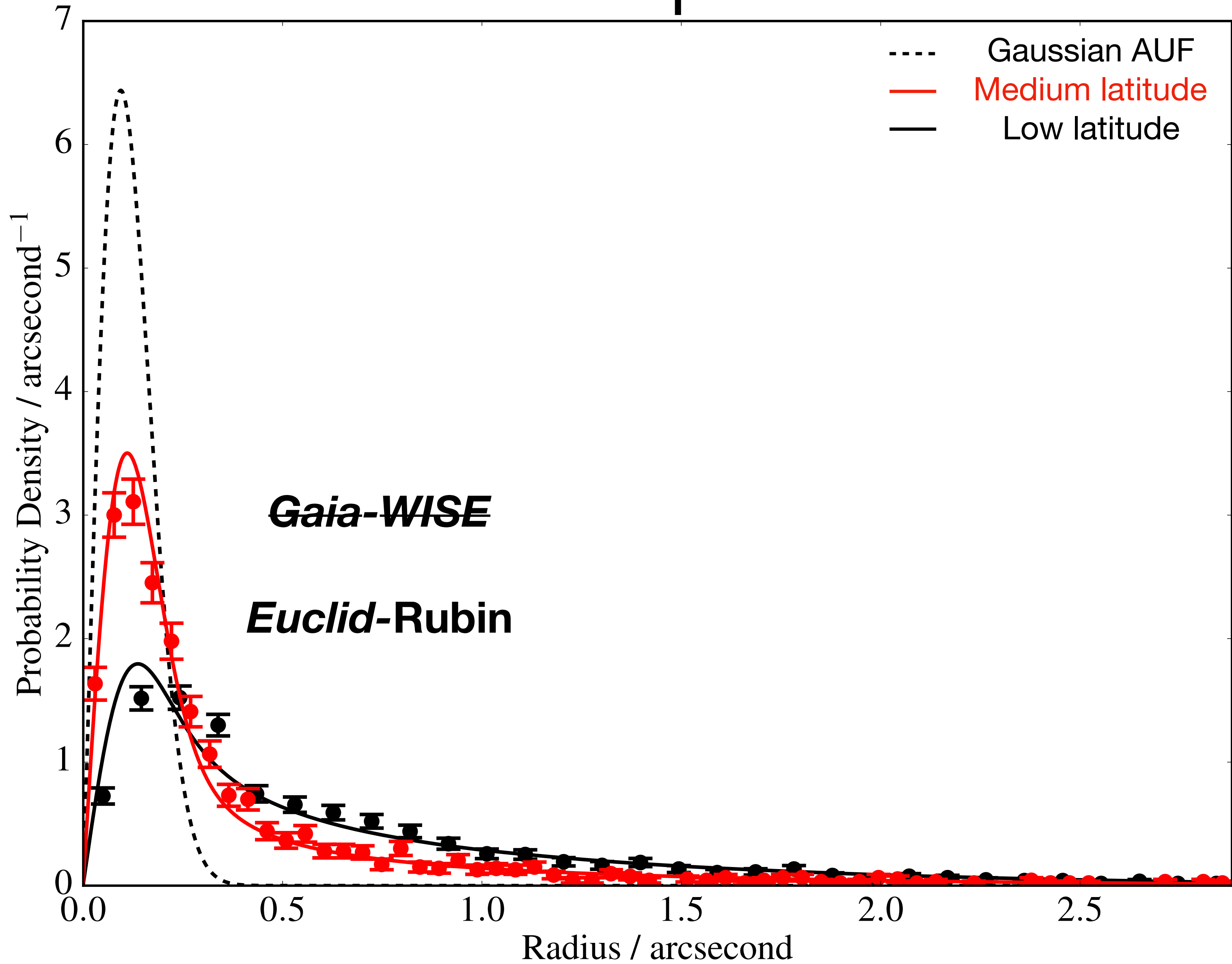
$$g(r, \sigma) = \frac{r}{\sigma^2} \exp\left(-\frac{1}{2} \frac{r^2}{\sigma^2}\right)$$



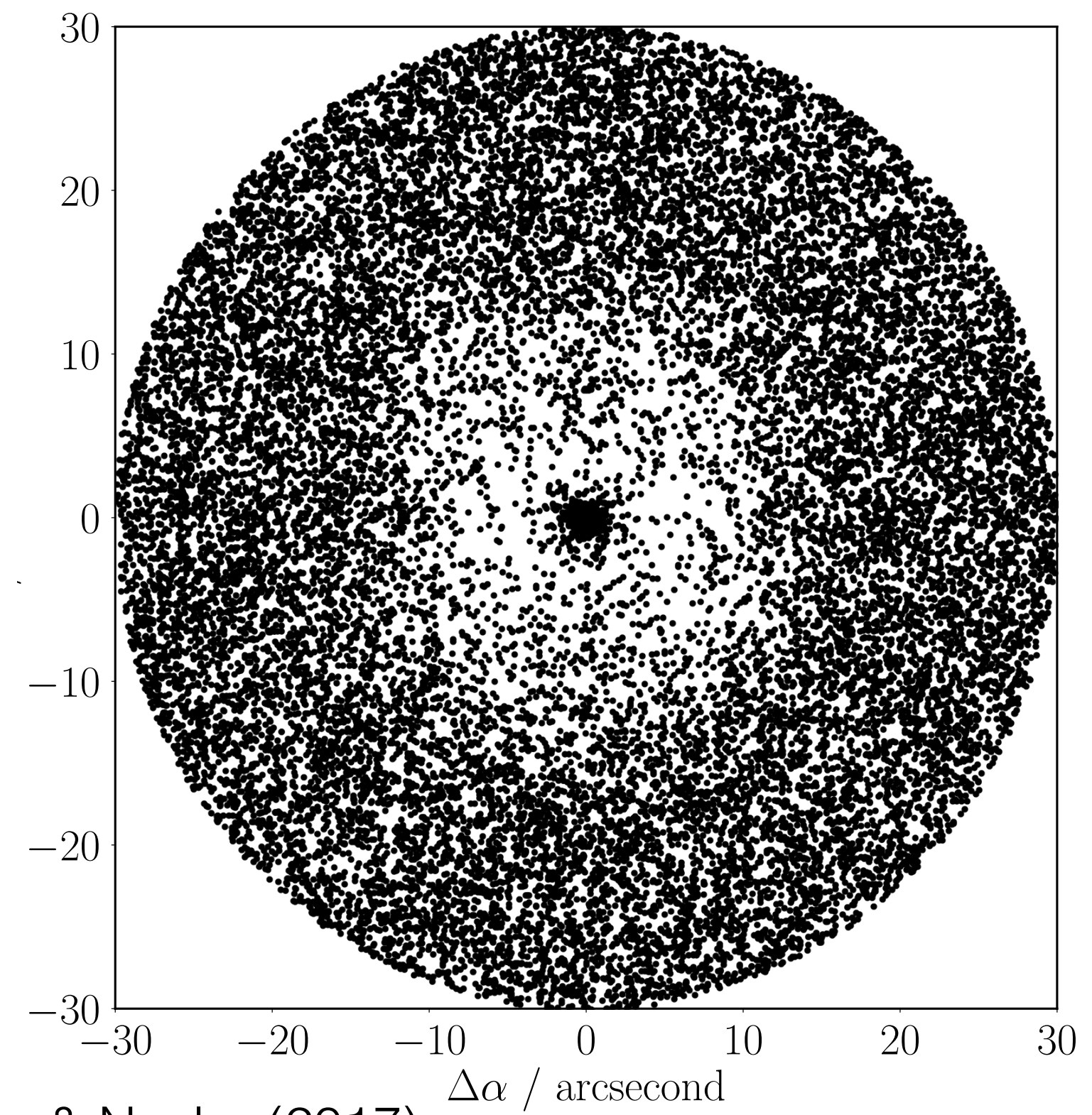
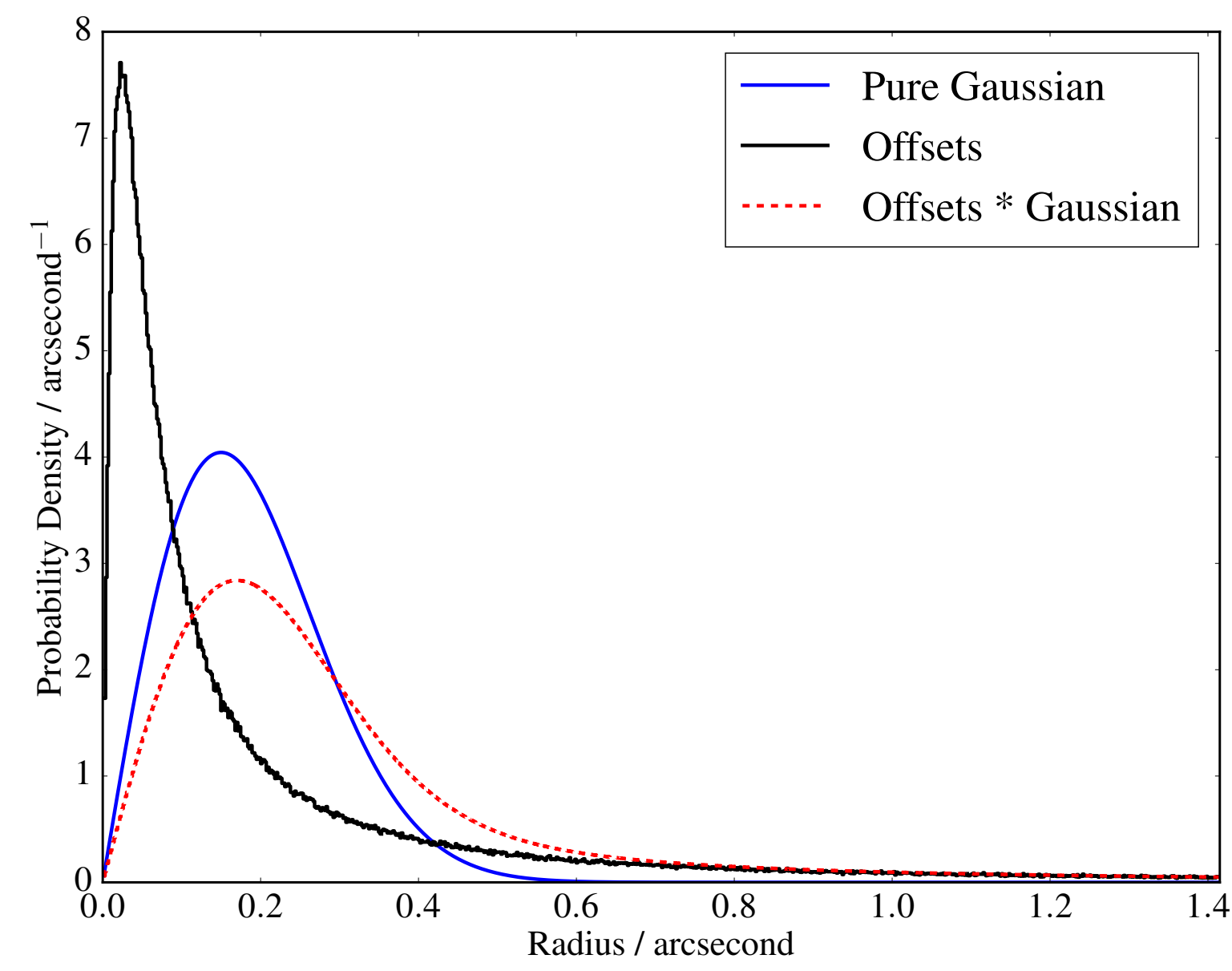
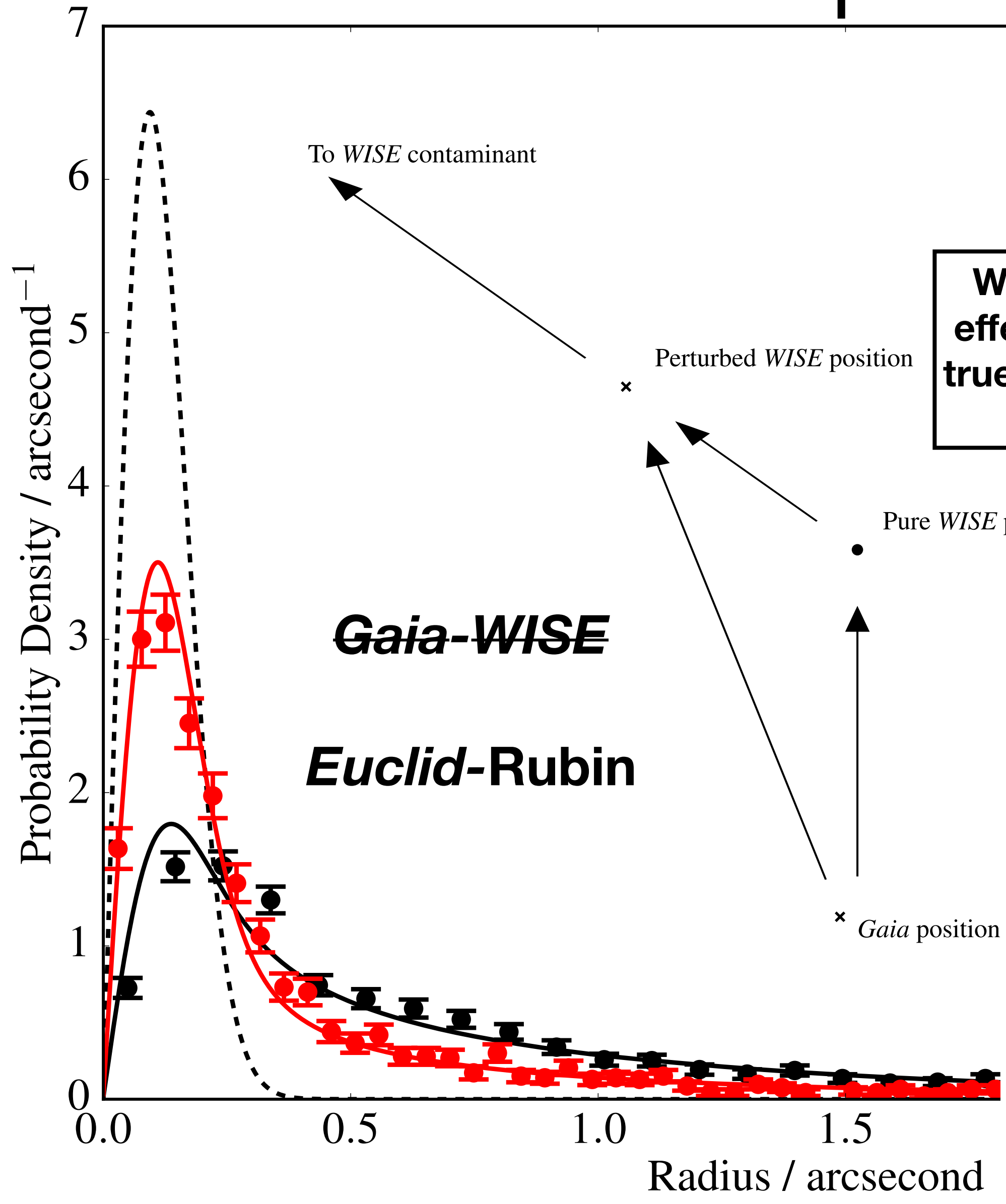
# Additional Components of the AUF



# Additional Components of the AUF (and any other systematic — e.g. proper motions, cf. Wilson 2023, RASTI)



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*WISE* - Wright et al. (2010)

*Gaia* DR2 - Gaia Collaboration, Brown A. G. A., et al. (2018)

Wilson & Naylor (2018b)

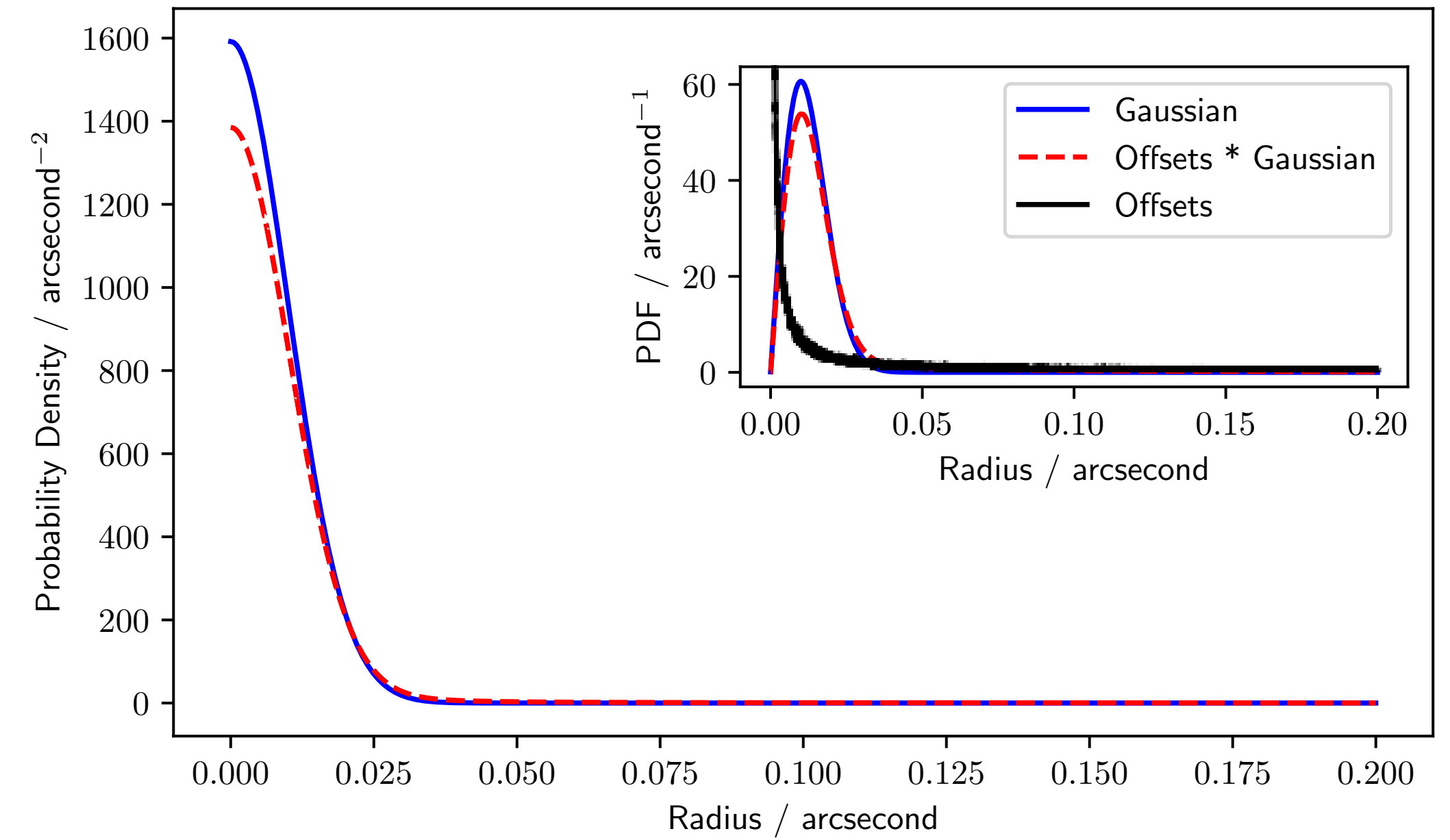
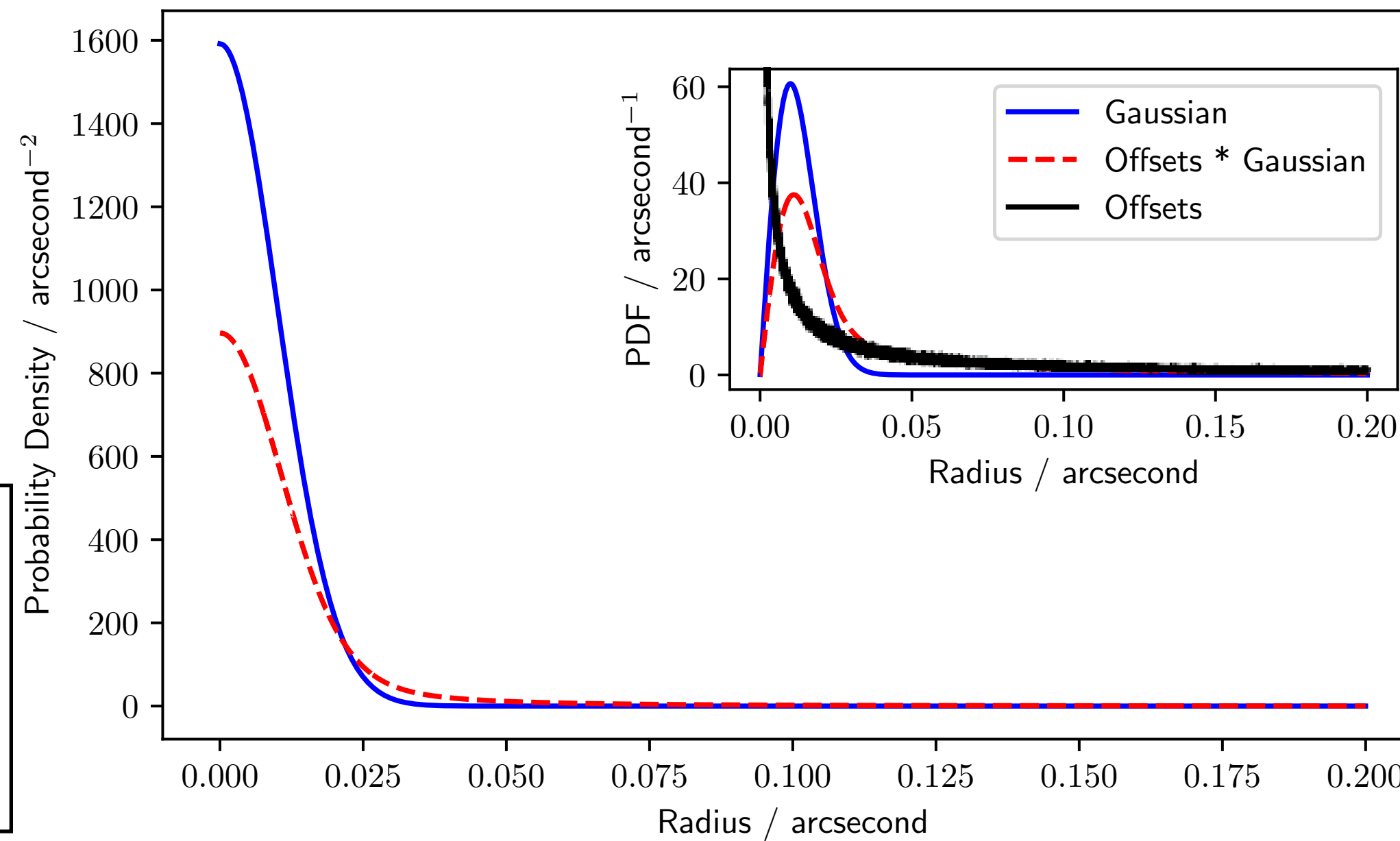
Wilson & Naylor (2017)

# The Rubin AUF: Galactic Plane

## Galactic Centre

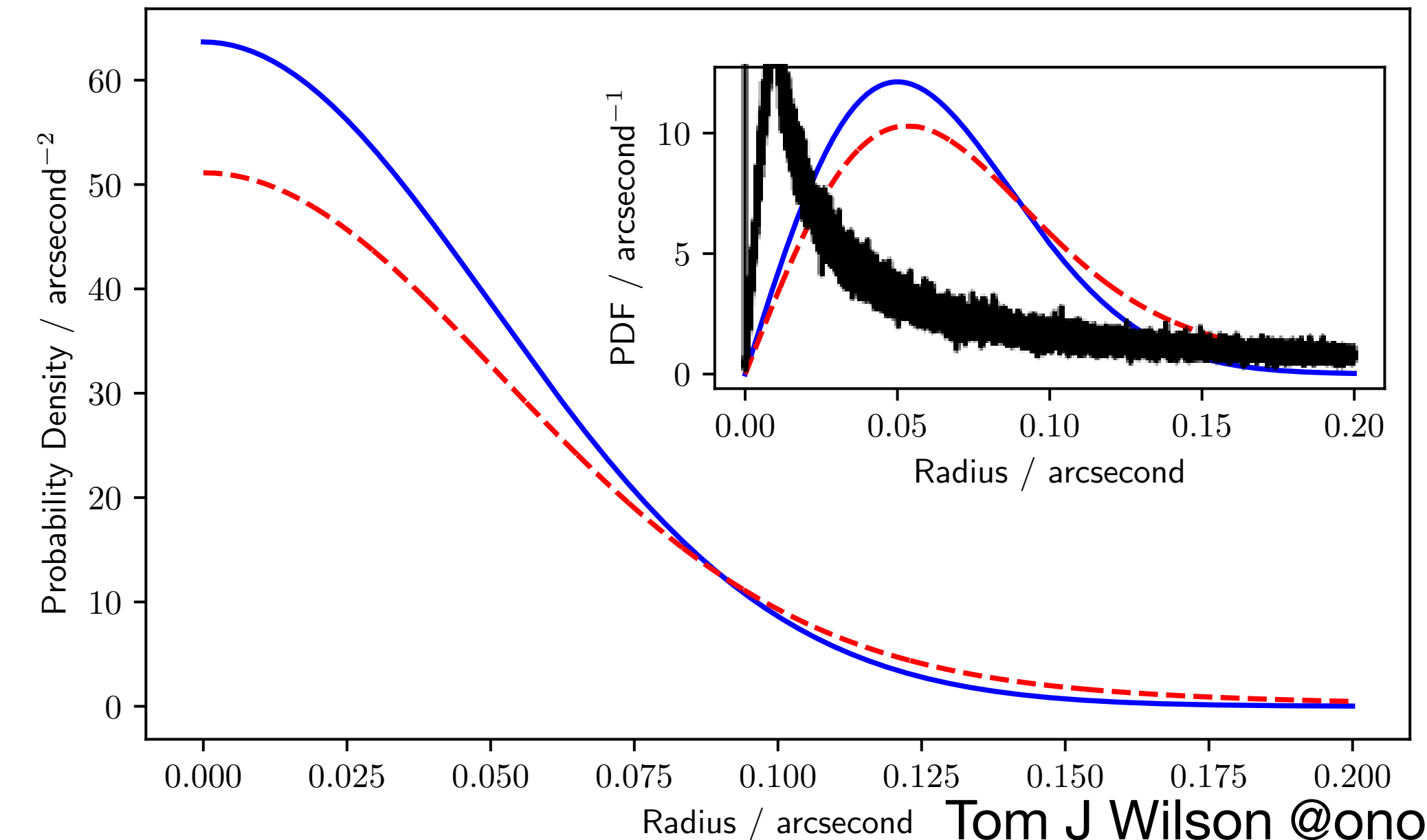
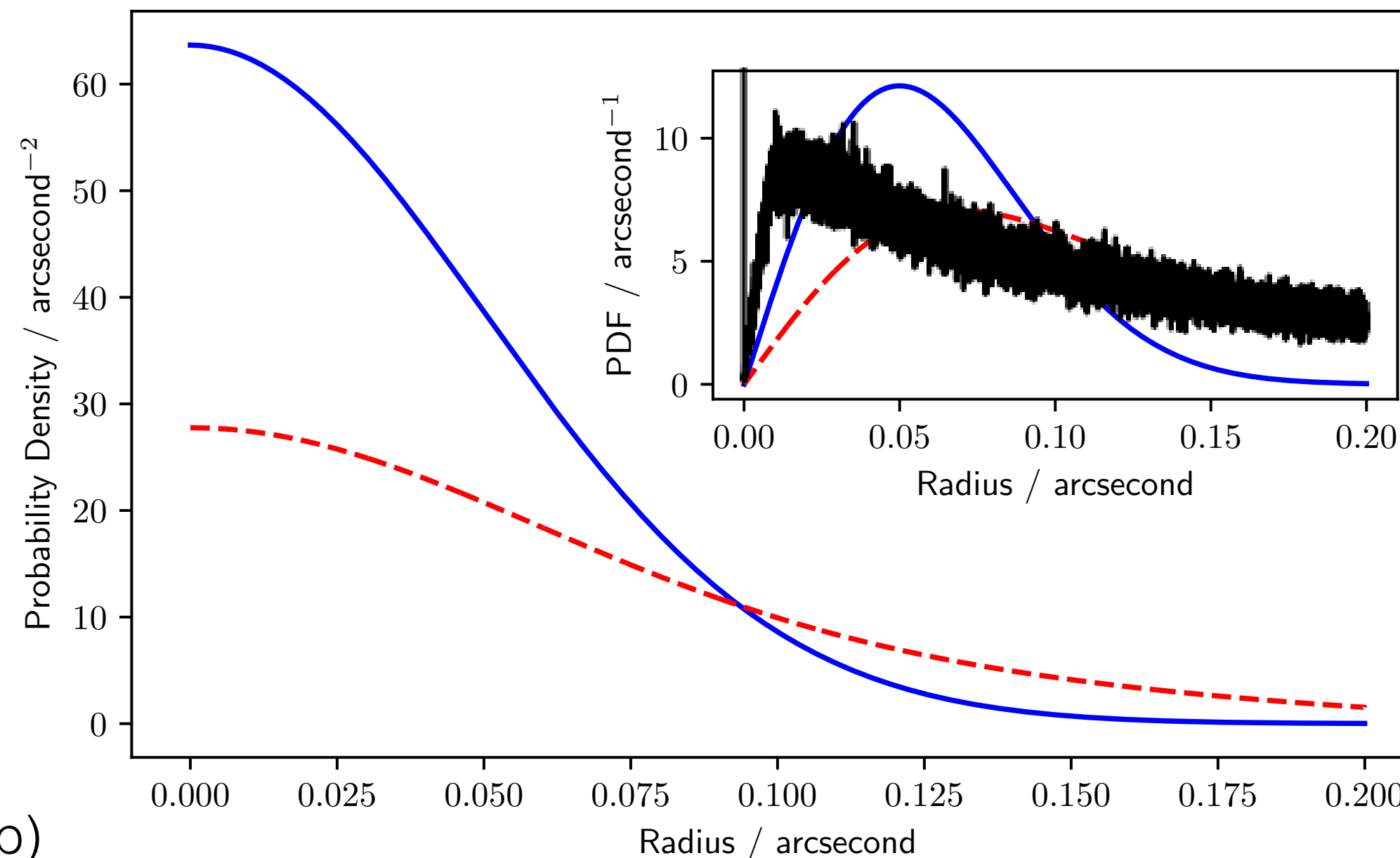
## Not the Galactic Centre

**Single-visit**

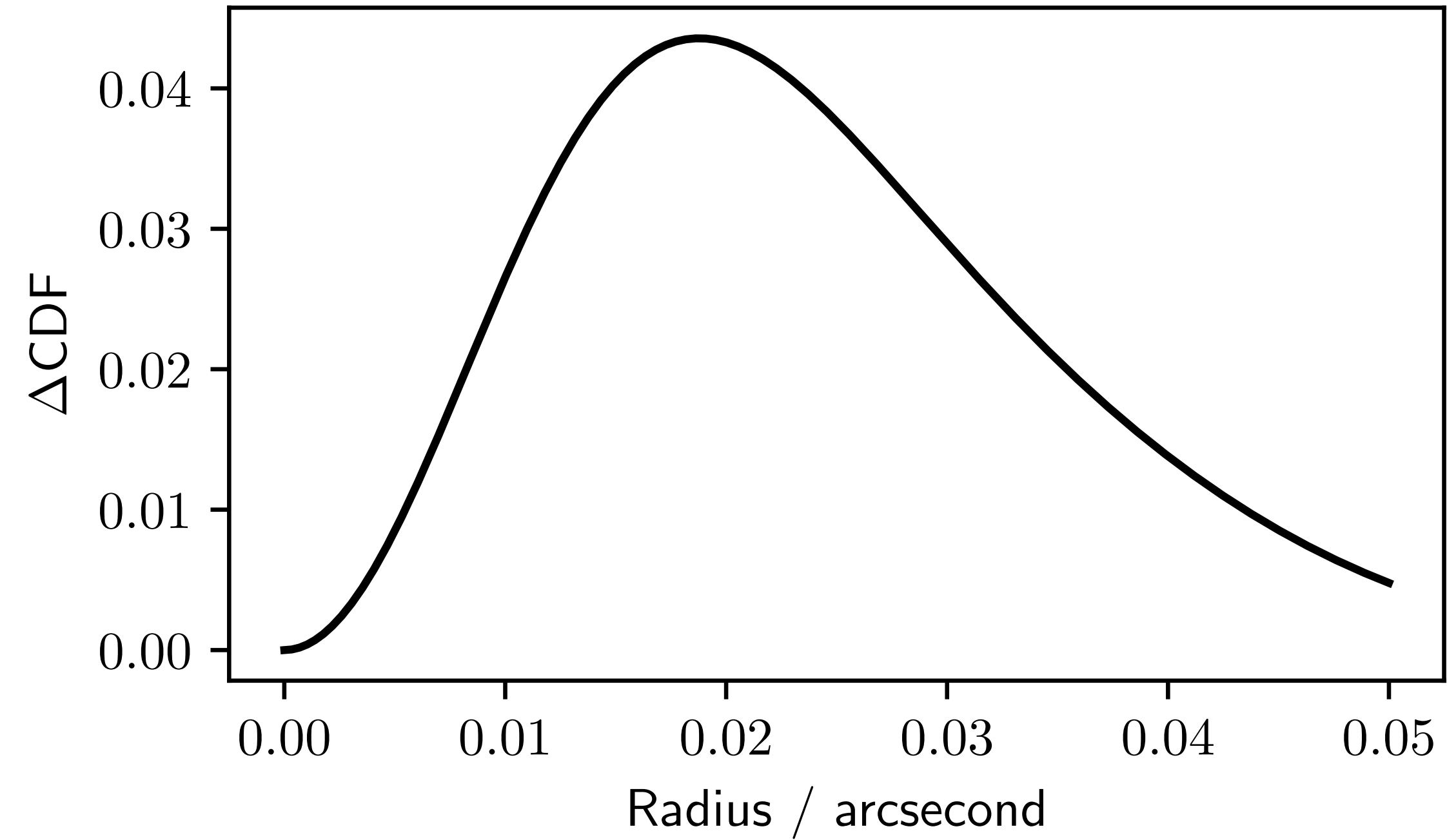
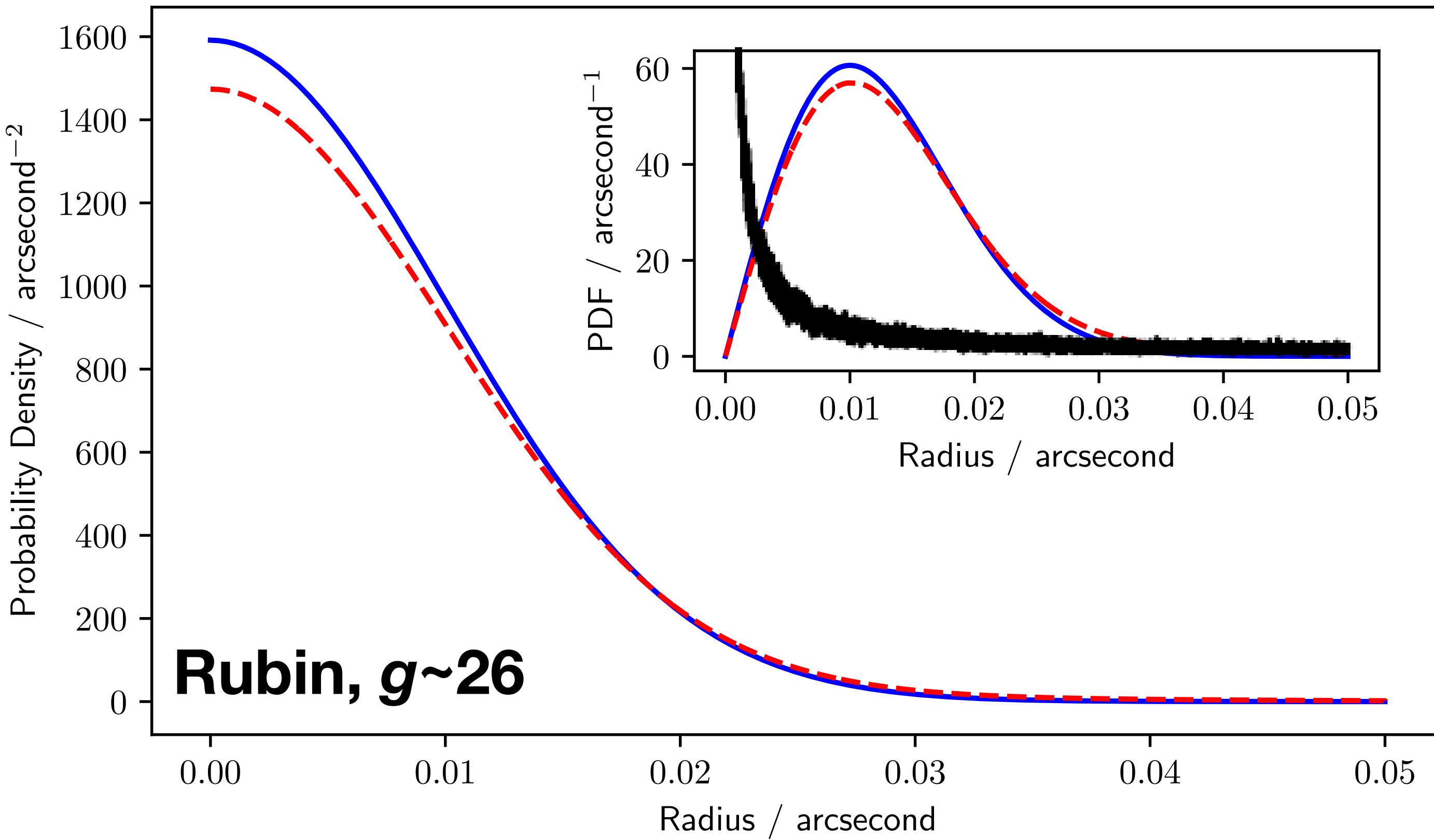


**Without modelling this extra effect, we fail to recover many true pairings, with an artificially high false negative rate!**

**Co-add**

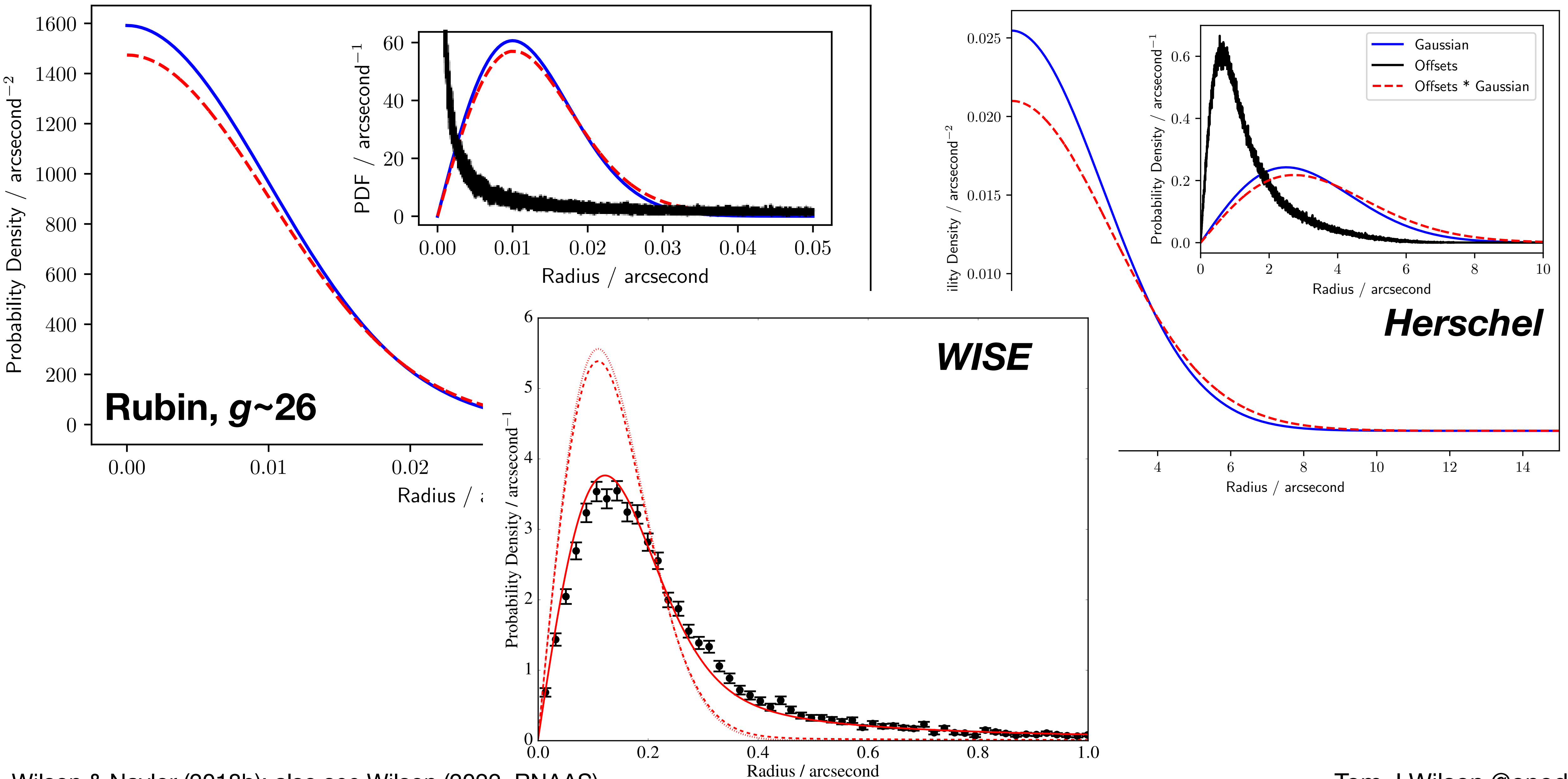


# The Rubin AUF: Extra-Galactic

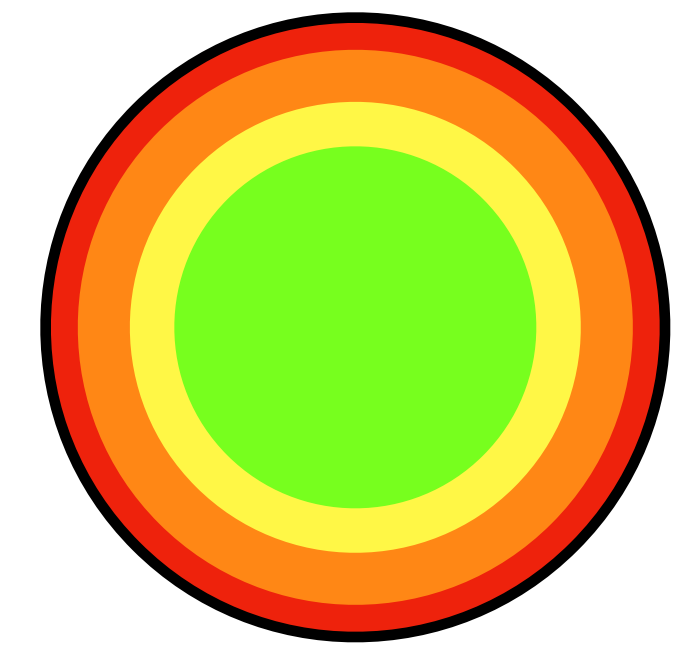
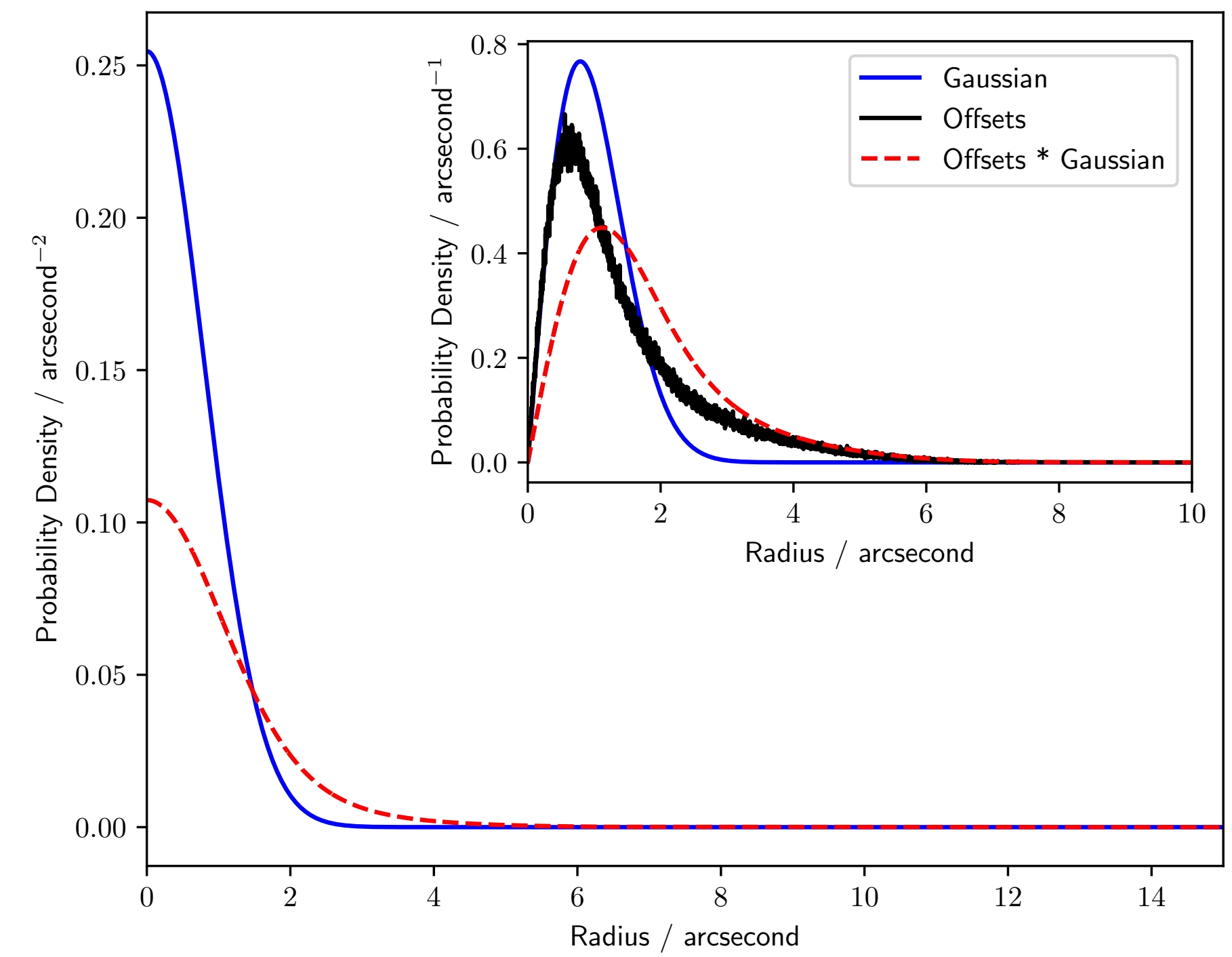
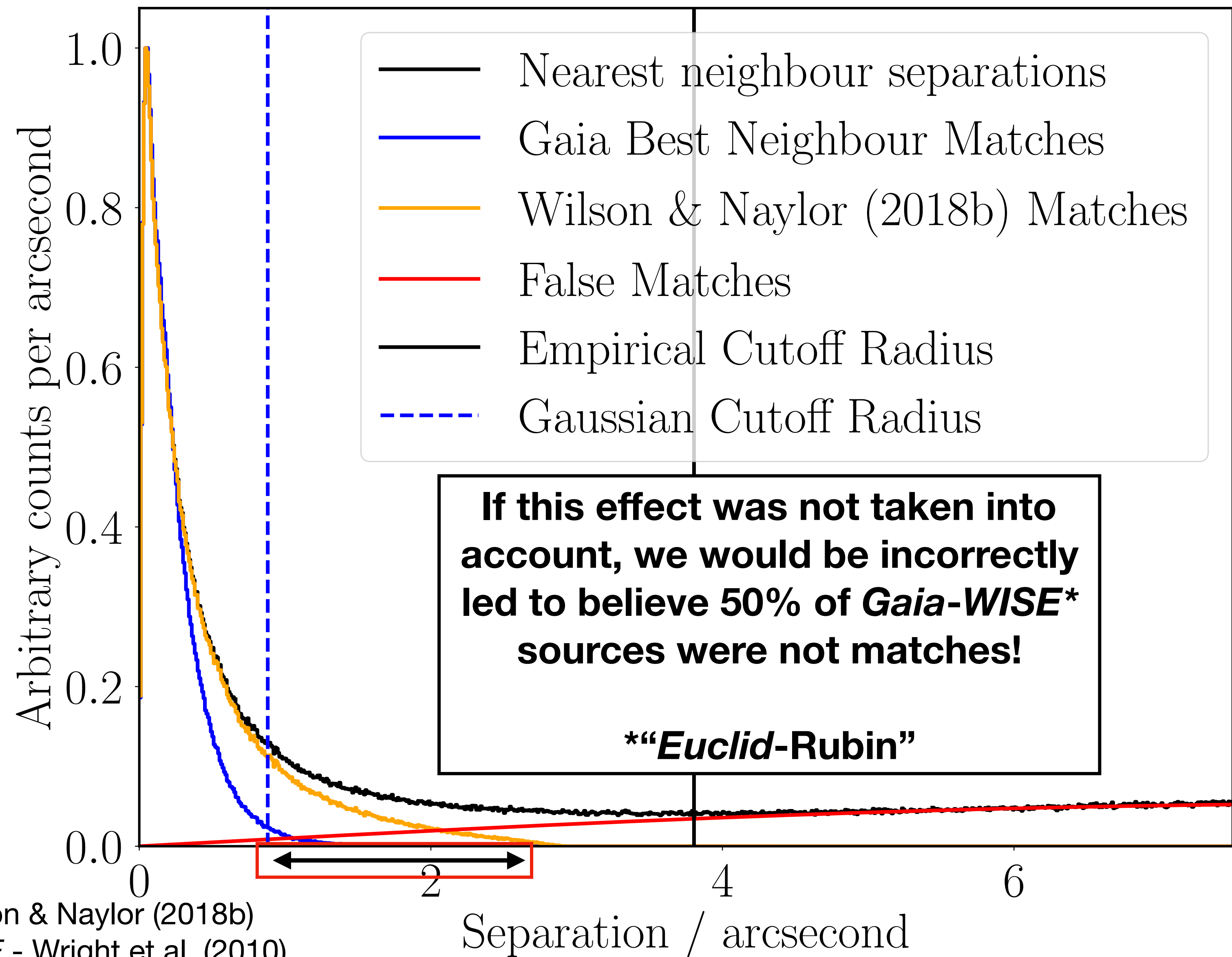


**Without modelling  
this extra effect, we  
fail to recover many  
true pairings, with an  
artificially high false  
negative rate!**

# The Rubin AUF: Extra-Galactic



# Match Separations



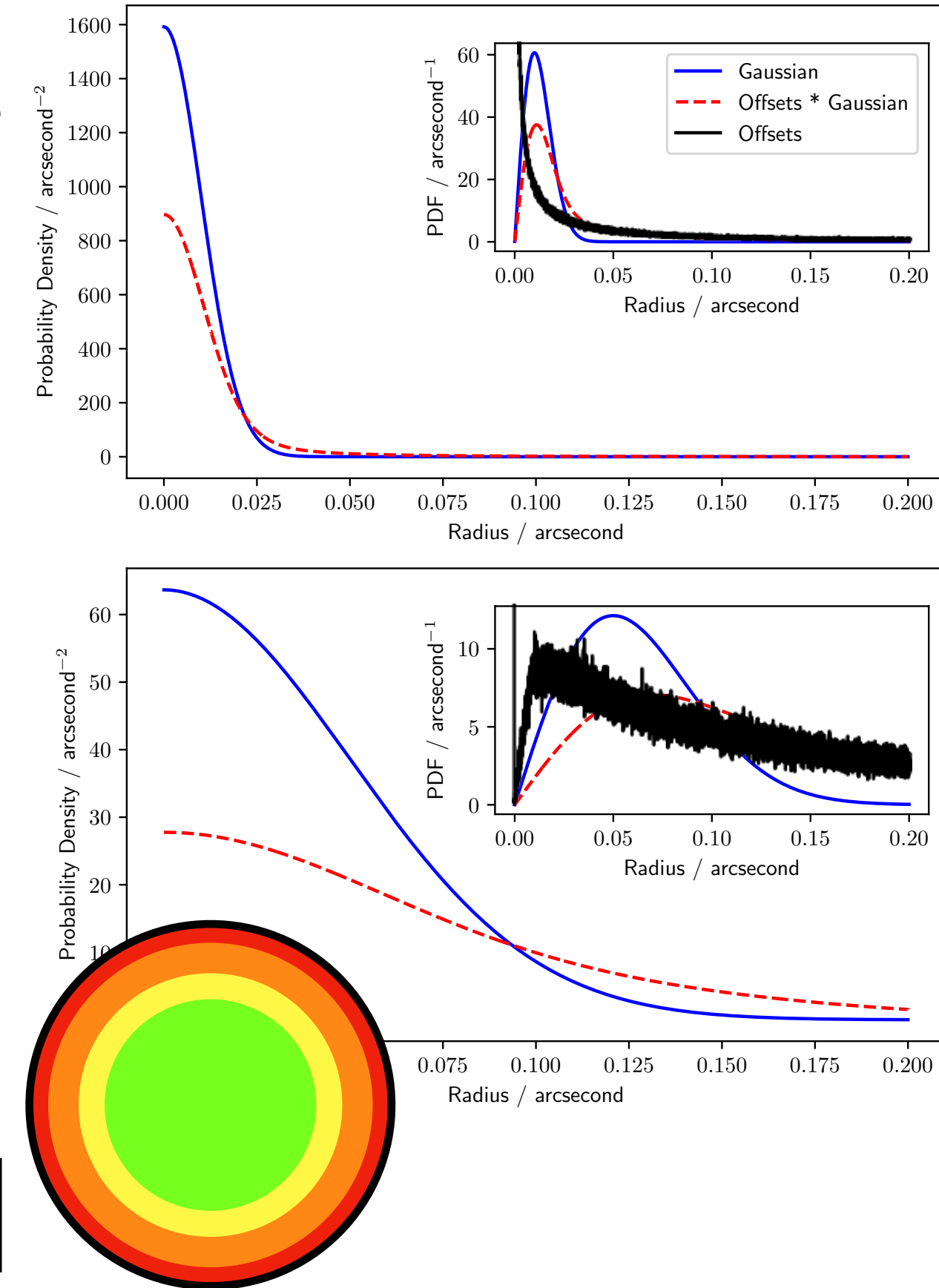
**The AUF does not need to, and in fact quite often should *not*, be Gaussian!**

Wilson & Naylor (2018b)  
*WISE* - Wright et al. (2010)  
*Gaia* matches - Marrese et al. (2019)  
*Gaia* DR2 - Gaia Collaboration, Brown A. G. A., et al. (2018)



# Conclusions

- Our cross-match algorithms include two key elements to avoid issues with crowded & confused data
  - A generalised approach to the Astrometric Uncertainty Function allows for the full inclusion of the effects of perturbation due to blended sources — reduce false -ves!
  - Use of (two-sided) photometry to sort out multiple competing matches— reduce false +ves!
- Software package macauff developed to cross-match catalogues, including the effect of unresolved contaminant sources (and rejection of interloper objects using photometry in the static sky)
  - Developed through an IKC to Rubin/LSST:UK, matches planned to *Gaia*, *WISE*, *VISTA*, *SDSS*, ...
  - We have compute time to cross-match datasets — let me know your favourite combo, and what you need matched (to LSST or otherwise)!
- Incorporating this extension of position uncertainty into real-time matches allows for more robust counterpart identification in the alert stream and a more accurate and precise transient SED
- Furthermore, we can provide *statistical* information on the level of photometric contamination unresolved contaminant sources cause, which can be subtracted in a probabilistic framework!



Nearest-neighbour matching *will not* work in the era of Rubin!

The AUF does not need to, and in fact quite often *should not*, be Gaussian!



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.github.io

Wilson & Naylor, 2017, MNRAS, 468, 2517  
Wilson & Naylor, 2018a, MNRAS, 473, 5570  
Wilson & Naylor, 2018b, MNRAS, 481, 2148  
Wilson, 2022, RNAAS, 6, 60  
Wilson, 2023, RASTI, 2, 1



<https://github.com/macauff/macauff>

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